

## OSFP MSA

Specification for

### OSFP OCTAL SMALL FORM FACTOR PLUGGABLE MODULE

Rev 3.0

March 14th, 2020

#### Abstract:

This specification defines the electrical connectors, electrical signals and power supplies, mechanical and thermal requirements of the OSFP Module, connector and cage systems. The OSFP Management interface is described in a separate document, Common Management Interface Specification for 8/16X Pluggable Transceivers.

This document provides a common specification for systems manufacturers, system integrators, and suppliers of modules.

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**Revision History:**

Rev 3.0	3/14/2020	Specifications for the stacked SMT connector and its cage are added to section 5. Reference design of cage vent holes are added to SMT single row cage. Universal MIS is added to the reference section.
Rev 2.0	1/14/2019	Major updates including: Touch temperature (section 3.9), stacked cage/connector (section 5), OSFP-RHS (section 8) and informative pull tab length (Appendix B) are added. Impedance requirement for the OSFP is relaxed (section 7.2). Management interface speed is increased (Section 10.5). Power class definition are updated, with increase of max power to 21.1W (section 10.6). GD&T of the drawings are updated. MPO-12 two row and MPO-16 lane assignments are added (section 9.8).
Rev 1.12	8/1/2017	Editorial updates, as of: Note 1 in the Figure 1 is clarified with "0.00mm max from top". PMD in the section 7 and titles are updated, including Figure 49 and 50 the optical receiver/transmitter lane numbers are revised to avoid any confusion. In section 8, word "must" replaced with "shall". Legal claim at page 1 "fitness or any.." typo fixed as "fitness for any..".
Rev 1.11	6/26/2017	Editorial updates, as of: Typo in the figure number in the figure table of contents fixed; Revision history added.
Rev 1.1	6/7/2017	Minor updates, as of: MPO 24 lane assignment (section 7.7.3) removed, to remove conflict with other industry conventions ; PCB location with respect to the module is specified with MMC modifier, to provide better dimensional control (Figure 8) ; Test ambient condition (20C, sea level) specified for the clarification in the module airflow impedance (Figure 42) ; In section 8.5, "optional" added to the fast and high-speed bus mode to clarify that those modes are optional ; In table 8-6, T_hlp description is updated for better clarification of the feature ; Power filter inductance adjusted to increase the power supply margin (Figure 59)
Rev 1.0	3/17/2017	Initial Release

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## 1 Scope

The OSFP specification defines:

- The OSFP module mechanical form factor, including latching mechanism;
- Host cage together with the mating connector;
- Electrical interface, including pin-out, data, control, power and ground signals;
- Mechanical interface, including package outline, front panel and printed circuit board (PCB) layout requirements;
- Thermal requirements and limitations, including heat sink design and airflow;
- Electrostatic discharge (ESD) requirements, and;
- The module management interface (contained in the OSFP Management Specification).

## 2 References

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- IEEE802.3bs: Media Access Control Parameters, Physical Layers and Management Parameters for 200 Gb/s and 400 Gb/s Operation
- IEEE802.3cd: Media Access Control Parameters for 50 Gb/s and Physical Layers and Management Parameters for 50 Gb/s, 100 Gb/s, and 200 Gb/s Operation
- IEEE802.3bj: Amendment 2: Physical Layer Specifications and Management Parameters for 100 Gb/s Operation Over Backplanes and Copper Cables
- IEEE802.3bm: Amendment 3: Physical Layer Specifications and Management Parameters for 40 Gb/s and 100 Gb/s Operation over Fiber Optic Cables
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- UL 60950-1, Information Technology Equipment – Safety – Part 1: General Requirements, 2007
- QSFP-DD Hardware Specification for QSFP Double Density 8X Pluggable Transceiver, Revision 3.0, September 19, 2017
- 400G BiDi MSA, <https://www.400gbidi-msa.org/>
- Interface Specification for MDC Receptacle, Rev 4, February 6 2020, USC11383001, US Conec
- Specification for SN™ Transceiver Receptacle, SN™ Connector Specification SN60092019 Rev 1.0, Senko
- Common Management Interface Specification for 8/16X Pluggable Transceivers, Rev 4.0, QSFP-DD MSA, <http://www.qsfp-dd.com/>

### 3 OSFP Module Mechanical Specification

#### 3.1 Overview

A typical OSFP module is shown in Figure 3-1. An assortment of connector types are shown. Connector and cable variations not shown here are allowed, including as depicted in Section 10.8.

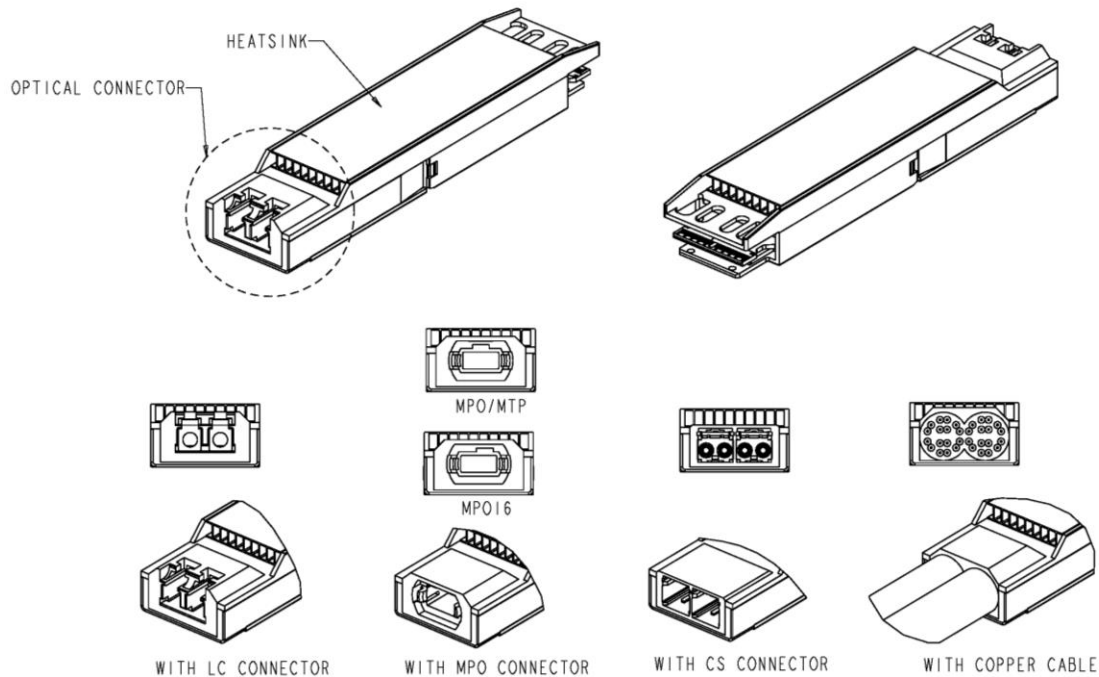


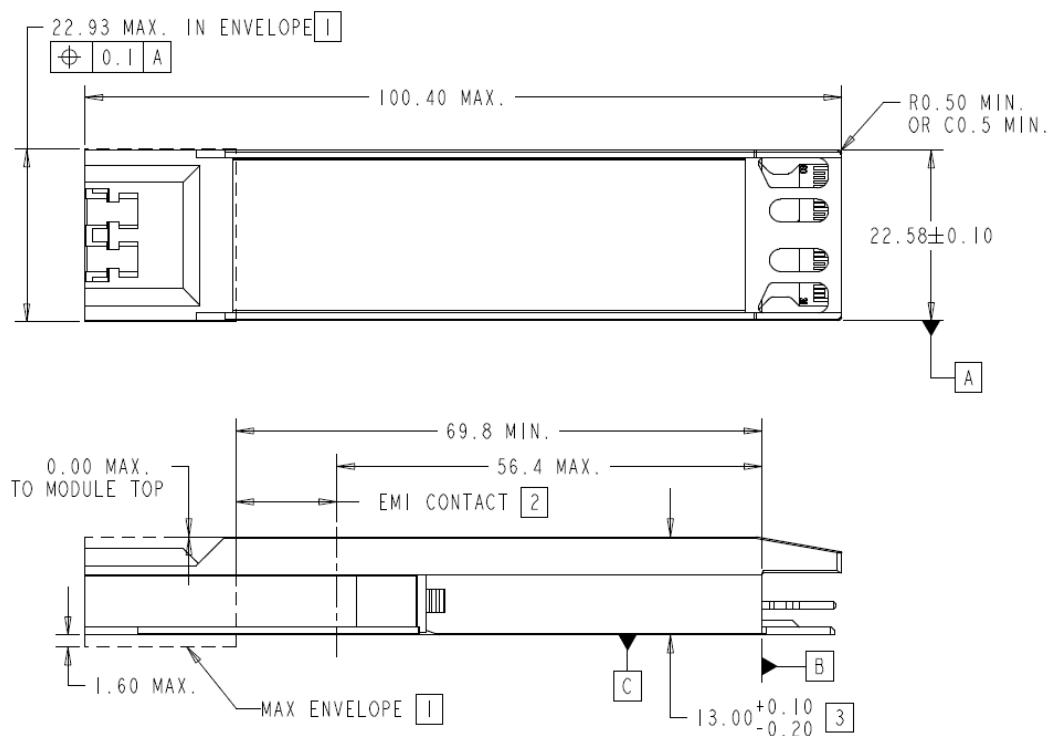
Figure 3-1: OSFP module with different connectors (Duplex LC, MPO, CS, Copper)

In the module mechanical drawings included throughout this specification, the datum as defined in Table 3-1 shall apply.

Table 3-1: Descriptions of the module mechanical datum

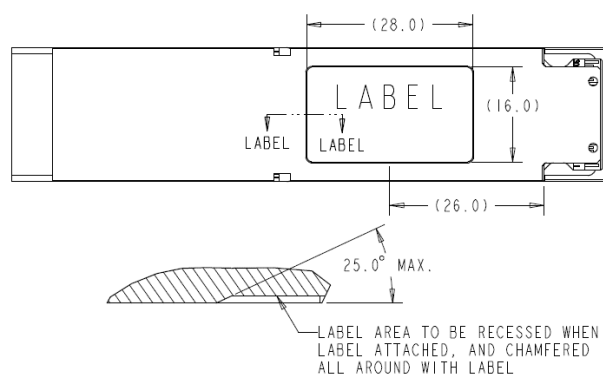
Designator	Description	Figure
A	Width of Module	Figure 3-2
B	Forward stop of Module	Figure 3-2; also see Figure 3-7
C	Bottom surface of Module	Figure 3-2
D	Width of Module pc board	Figure 3-17
E	Signal pad leading edge of Module pc board	Figure 3-17
F	Top surface of Module pc board	Figure 3-17

Figure 3-2 shows the dimensions of the OSFP module, including overall lengths, front envelopes and EMI contact area. Note that the module is shown with a typical latch release mechanism without pull tab. Alternate latch release mechanisms are allowed. All dimensions in this specification are in millimeters (mm) unless otherwise noted.



## NOTES:

- [1] FRONT OF THE MODULE, PULL TAB AND OTHER COMPONENTS CAN EXTEND 1.6MM MAX FROM THE BOTTOM OF THE MODULE AND CAN HAVE UP TO 22.93mm WIDTH IN THE MAX ENVELOPE SHOWN.
- [2] INDICATED SURFACES (ALL 4 SIDES) TO BE CONDUCTIVE FOR CONNECTION TO CHASSIS GROUND.
- [3] APPLIES FROM THE TOP OF THE MODULE TO THE BOTTOM OF THE MODULE, INSIDE THE CAGE.

**Figure 3-2: OSFP overall dimensions**

SECTION LABEL-LABEL (MAGNIFIED VIEW).

**Figure 3-3: OSFP label reference location**

Figure 3-3 shows the recommended label location. Figure 3-4 shows the corner radius of the module.

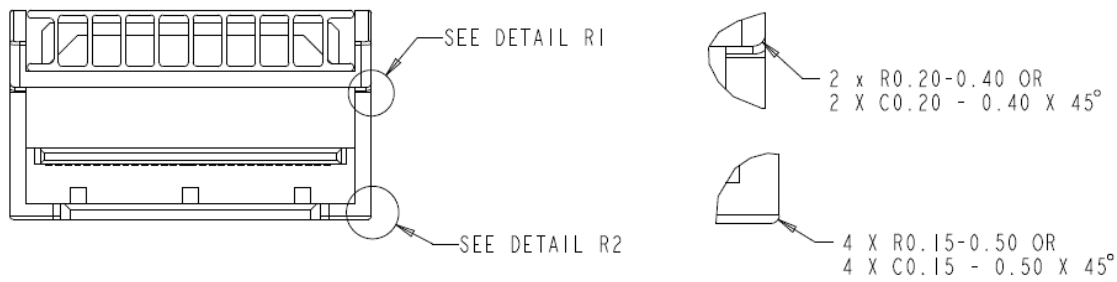


Figure 3-4: OSFP corner radius

### 3.2 OSFP Nose

To mate with an electrical connector located in the cage, an OSFP module shall have a protruded printed circuit board (PCB) with contact pads. A structure consisting of upper and lower lips forms a nose (i.e. back of the module) that serves as a guard to protect the PCB. Figure 3-5 through Figure 3-11 show the dimensional requirements of the nose, including the shape of the lip, connector mating area, forward stop, ventilation holes and location of the signal pads.

Figure 3-7 shows the location of the forward stop, consisting of the left and right vertical side walls of the bottom case of the module, which interact with features in the connector cage to stop the module when it is fully inserted. The vertical side walls shall extend at least 7.0 mm upward as measured from the bottom of the module for the forward stop feature.

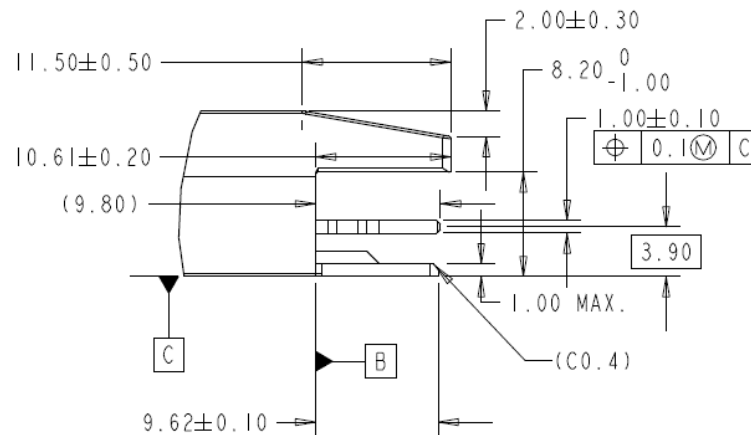


Figure 3-5: OSFP nose, side view

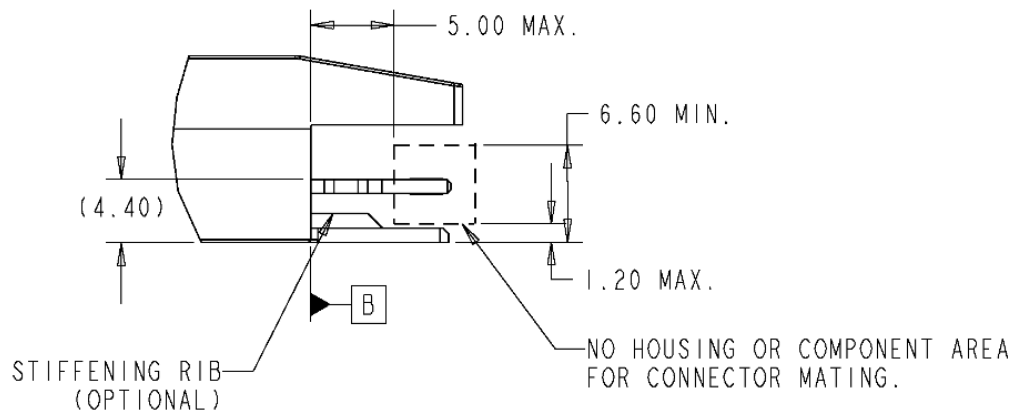


Figure 3-6: OSFP nose, side view, no component area

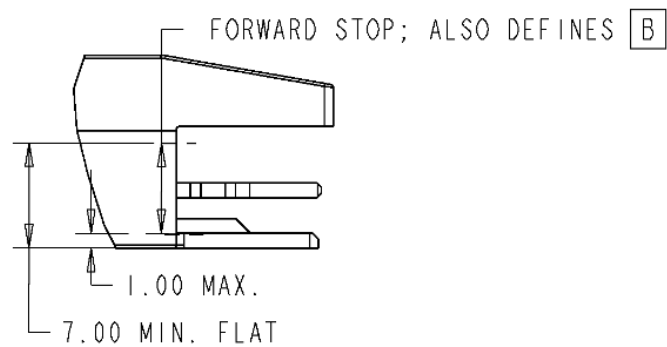


Figure 3-7: OSFP nose, side view, location of the forward stop

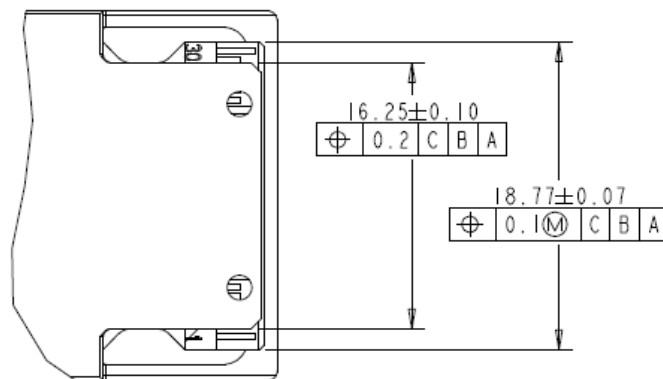


Figure 3-8: OSFP nose, bottom view

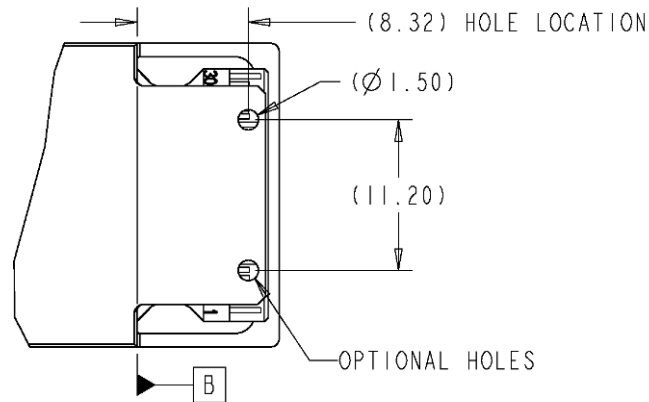


Figure 3-9: OSFP nose, bottom view, optional signal pad inspection holes

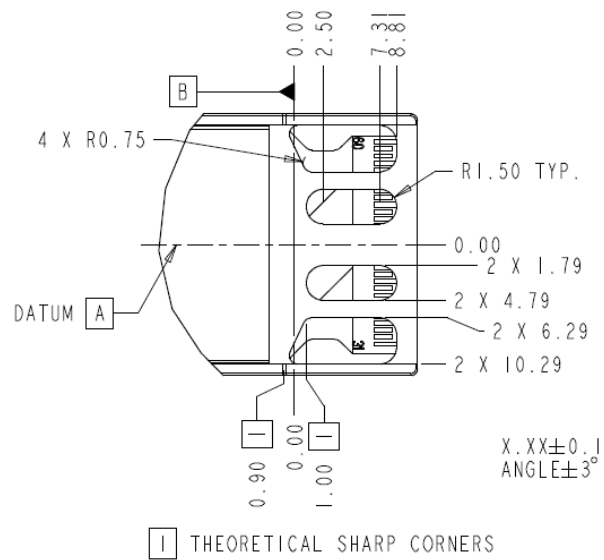


Figure 3-10: OSFP nose, Top view: Dimension for Ventilation holes

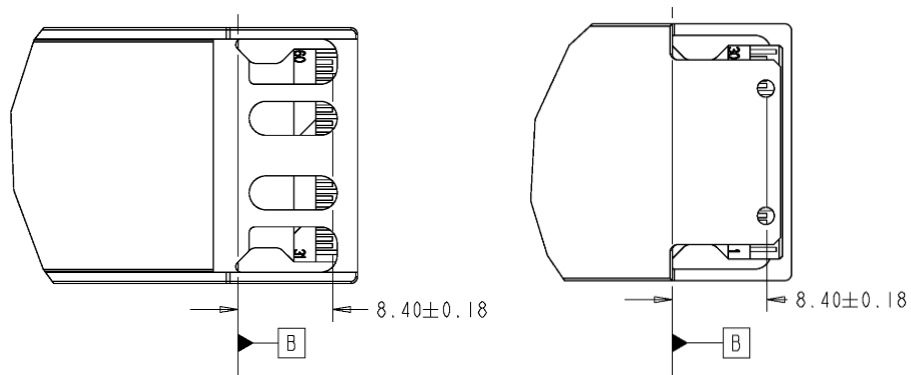


Figure 3-11: Signal pad location to module (left: top view, right: bottom view)



### 3.3 Heat Sink, Closed Top

In order to dissipate heat, the module allows for airflow along its length. Figure 3-12 shows requirements for the heat sink location in order to avoid collision with the keying feature in the cage and also ensure proper contact with ground and an optional thermal interface. Refer to Figure 4-12 for details of the key feature located in the cage.

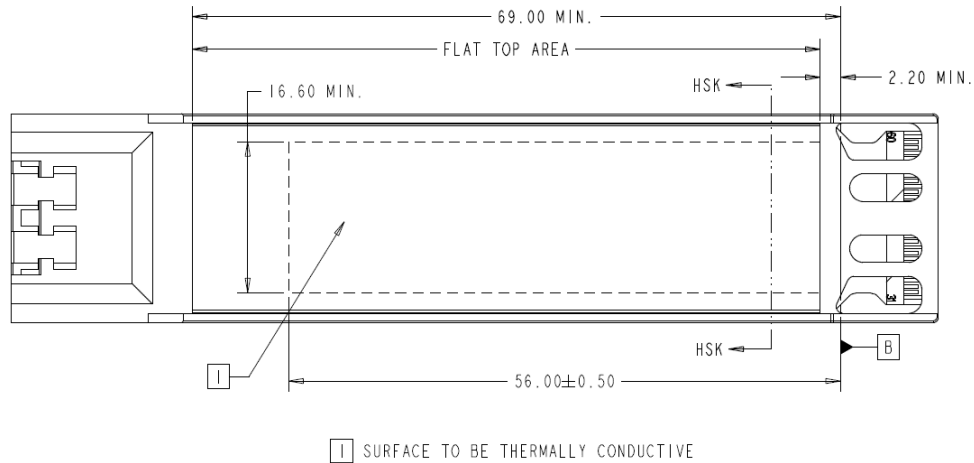


Figure 3-12: Heat sink, top view

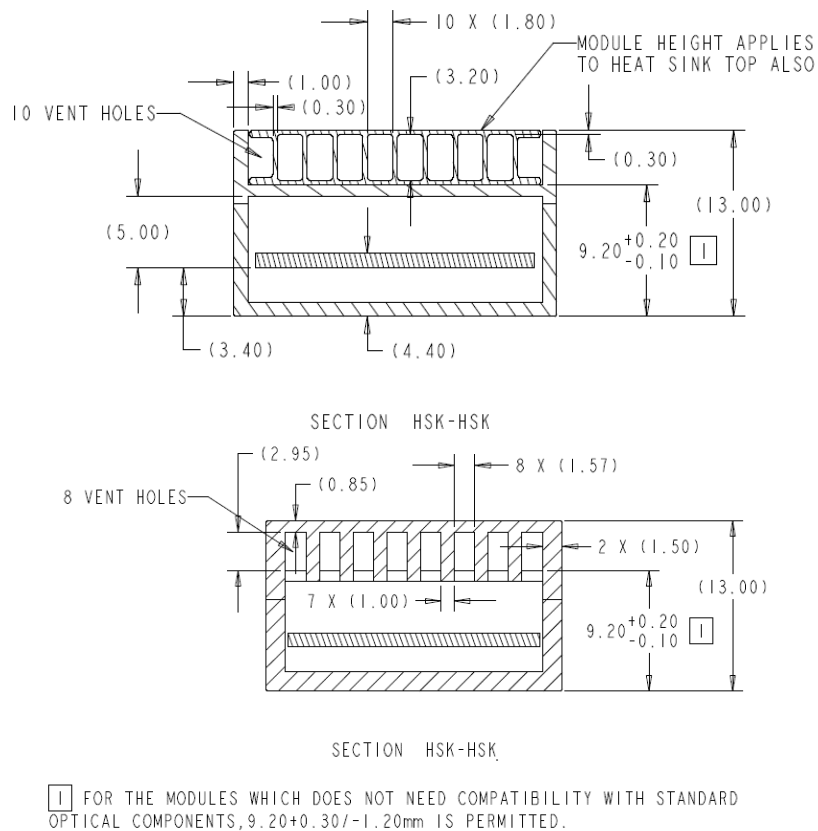


Figure 3-13: Examples of heat sink design (See Figure 3-12 for cross-section location)

Figure 3-13 presents two examples of heat sink design. Either may be considered for use. Alternate designs different from examples presented may also be used, but any heat sink design shall allow for an amount of airflow as defined in Section 8.2.

### 3.4 Heat Sink, Open Top

Modules which have a non-closed top, i.e. open top, are allowed only when the heat sink fins are designed to meet the dimensional requirements outlined in Figure 3-14 through Figure 3-16 in order to prevent EMI finger damage and to ensure proper EMI shielding. Height and length of the heat sink may differ from reference height presented, but still shall allow an amount of airflow as defined in Section 8.2.

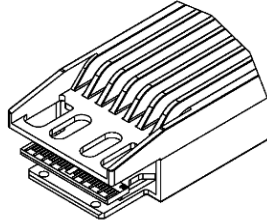


Figure 3-14: Open top heat sink (Isometric view)

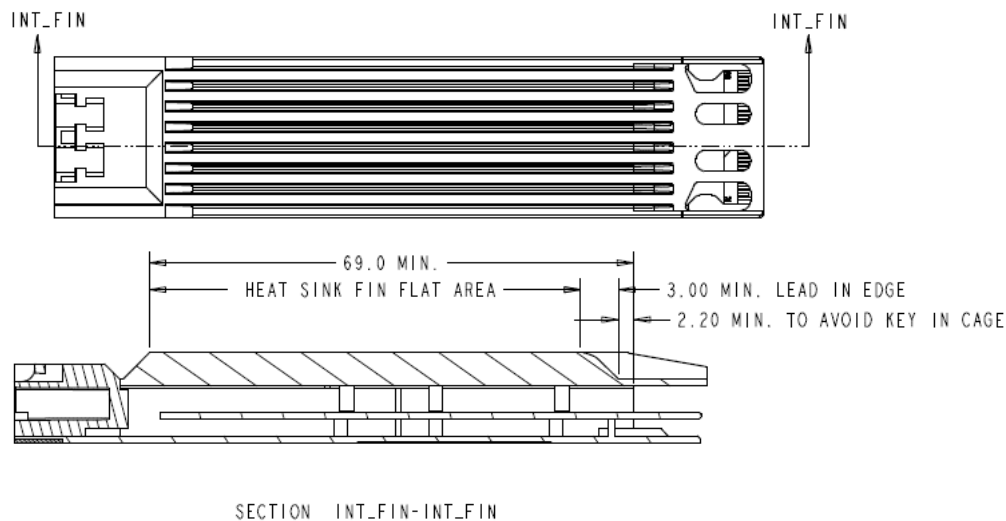
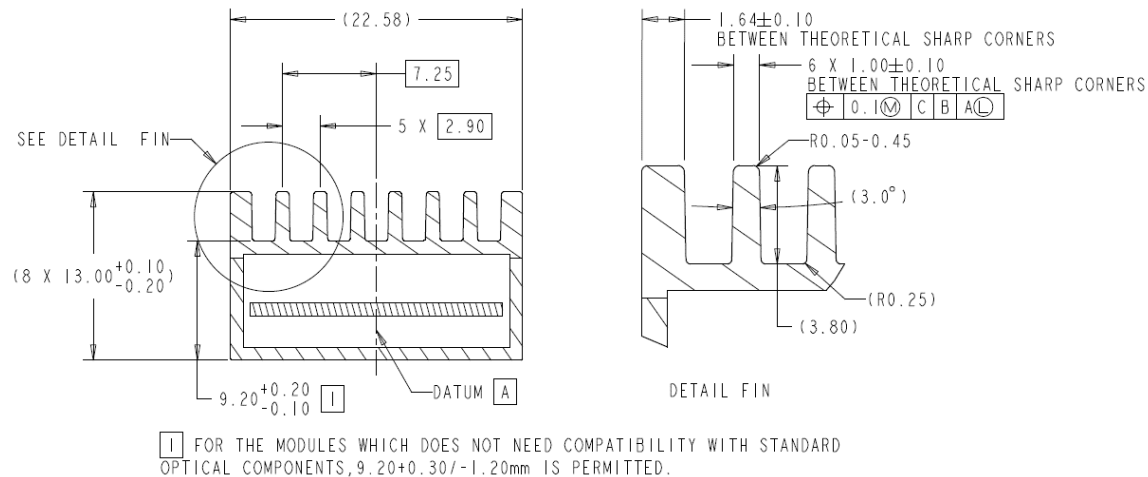


Figure 3-15: Heat sink location



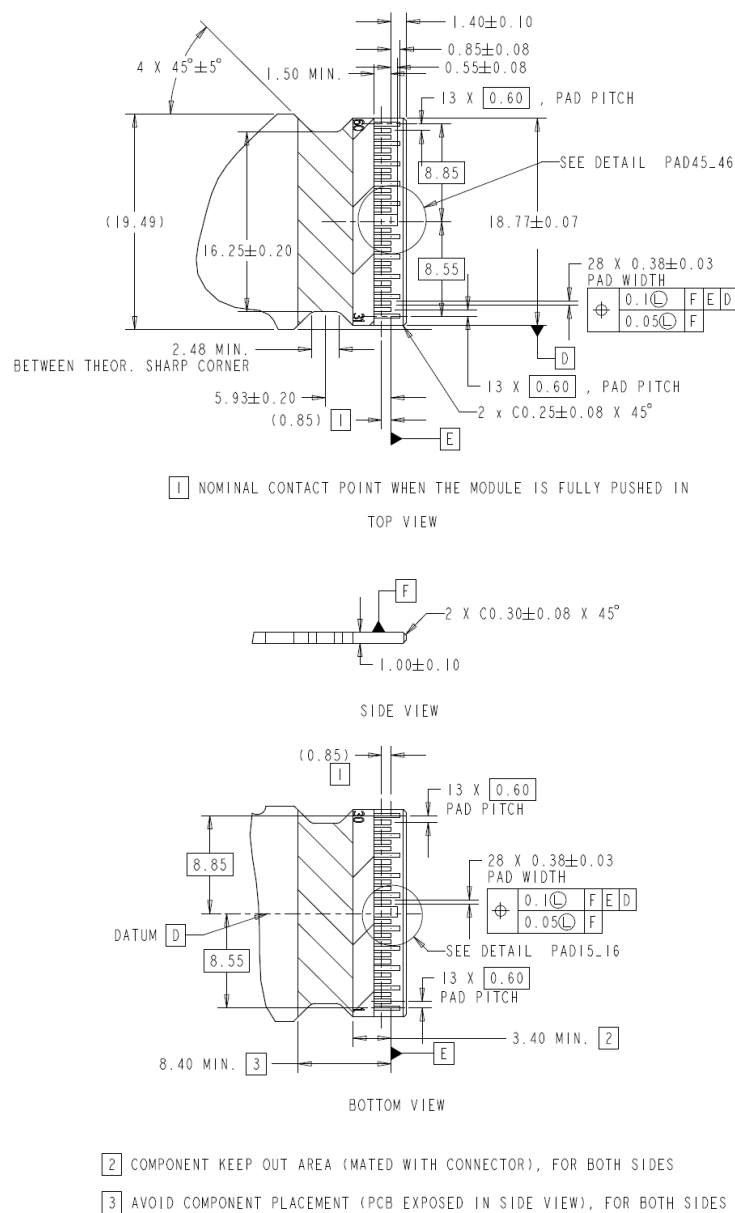
The top and bottom internal EMI fingers are specified per this fin pitch, as depicted in Figure 4-9. It is possible to add airflow passages to the bottom of the module with this fin pitch for thermal management of high power modules.

### 3.5 Card-edge Design (Module Electrical Interface)

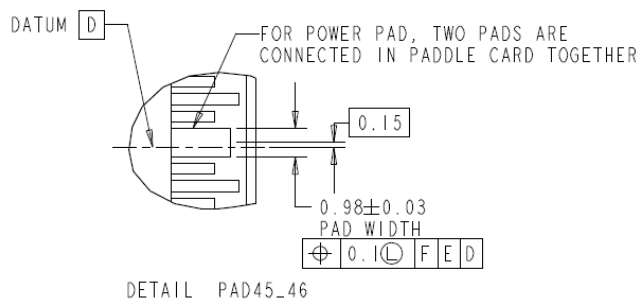
The OSFP module contains a PCB with contact pads (i.e. module PC board; paddle card) that mate with a connector as specified in Section **Error! Reference source not found.** of this document. Critical dimensions for the contact pads are shown in Figure 3-17 through Figure 3-19. The contact pads on the PCB are designed for sequence mating during module insertion as follows:

- First mate: ground contacts
- Second mate: power contacts
- Third mate: signal contacts

During module removal, contact disconnects happen in reverse order of the above, e.g. signal contacts break first.



**Figure 3-17: OSFP module pc board (card-edge)**



**Figure 3-18: OSFP card-edge, detail of power pad (pads 45/46)**

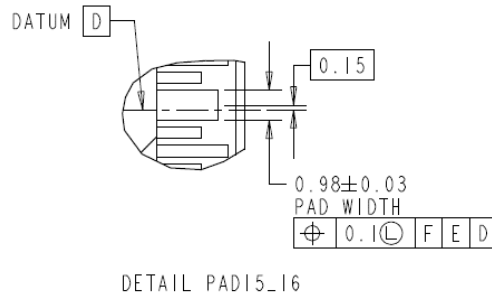


Figure 3-19: OSFP card-edge, detail of power pad (pads 15/16)

### 3.6 Contact Pad Plating Requirements

The contact pad plating shall meet the durability requirements of Section 7.1 and Section 7.2. The recommended plating specification is 0.762  $\mu\text{m}$  minimum gold over 3.81  $\mu\text{m}$  minimum nickel. Other plating systems are allowed provided they meet or exceed the requirements of Section 7.1 and 7.2.

### 3.7 Module Latch Feature

For latching, the module shall have latching pockets and a latch release mechanism at both sides as shown in Figure 3-20, Figure 3-21 and Figure 3-22. Dimensional details of the cage flap can be found in Figure 4-18 and Figure 4-19 .

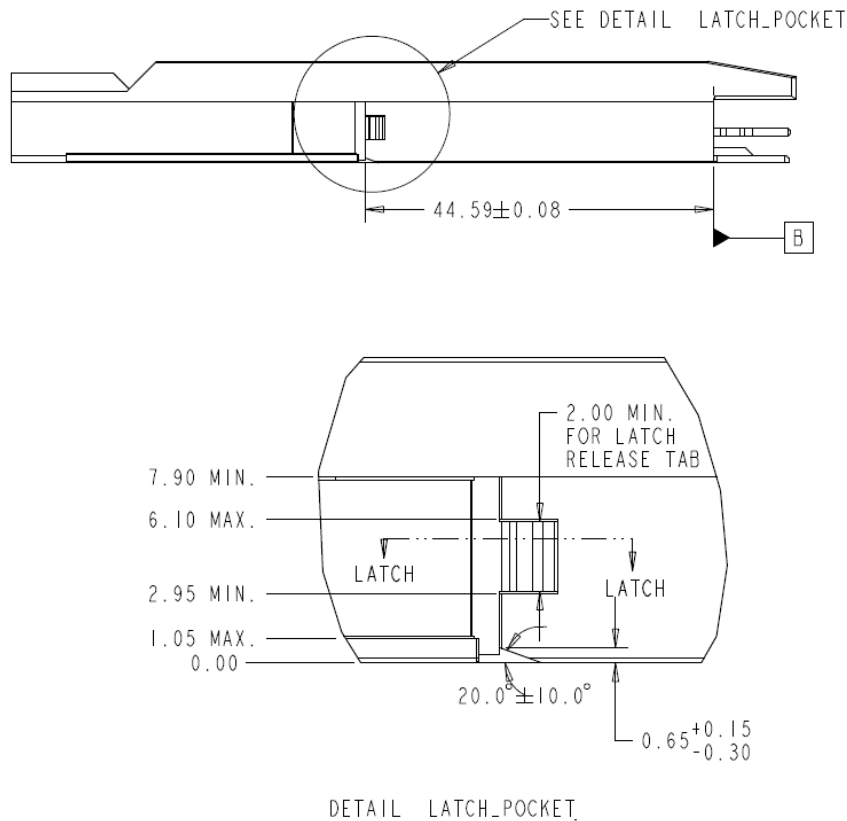
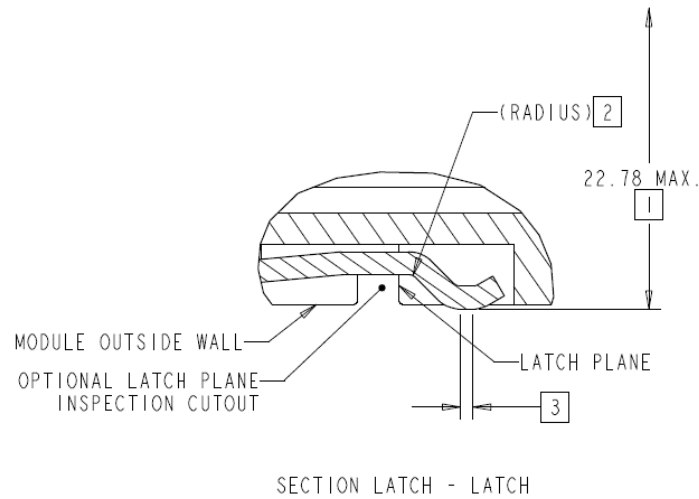
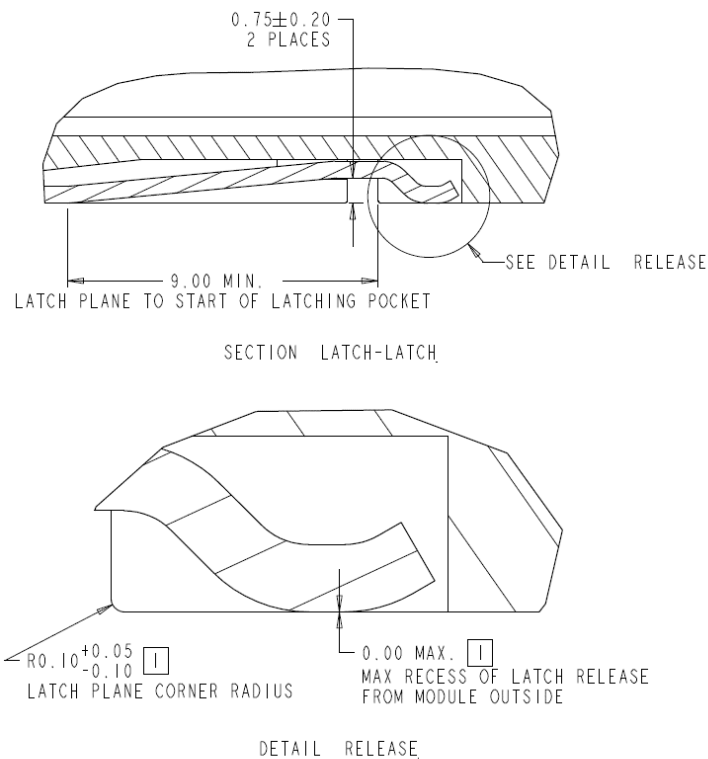


Figure 3-20: Latch pocket location



- [1] MAXIMUM OUTSIDE ENVELOPE BETWEEN TWO OPPOSITE LATCHES
- [2] MINIMUM INNER RADIUS 0.50MM RECOMMENDED
- [3] FLAT AREA OF MINIMUM 0.50MM RECOMMENDED

**Figure 3-21: Latch release max width and latching pocket round**



- [1] ALTERNATIVE DESIGN ALLOWED IF RELIABLE LATCH RELEASE CAN BE ACHIEVED

**Figure 3-22: Latch release minimum width and latching pocket length**

### 3.8 Module Color Code

The module shall adhere to a color code by application of color to its pull-tab or other appropriate method. The color code to be applied is given in Table 3-2.

*Table 3-2: OSFP color code*

Product Type	Example PMD	Color	Pantone Code (Recommended)
OSFP copper cables	400G-CR8	Black	N/A
OSFP AOC Cables	400G-AOC	Grey	422U
OSFP 850nm solutions	400G-SR8, SR4.2	Beige	475U
OSFP 1310nm solutions for up to 500m	400G DR4	Yellow	107U
OSFP 1310nm solutions for up to 2km	400G FR4, FR8	Green	354C
OSFP 1310nm solutions for up to 10km	400G LR8	Blue	300U
OSFP 1310nm solutions for up to 40km	400G ER8	Red	1797U
OSFP 1550nm solutions for up to 80km	400G ZR8	White	N/A

### 3.9 Touch Temperature

Module surfaces outside of the cage must comply with applicable touch temperature requirements. If the temperature of the module case will exceed applicable short-term touch limits, then a means to prevent contact with the case during the handling of the module shall be provided. Refer to UL 60950-1 and NEBS GR-63.

## 4 Single Row Surface Mount Technology OSFP Connector and Its Cage: Mechanical Specification

In this section, the configuration of a single row SMT (Surface Mount Technology) connector and its cage are presented.

### 4.1 Overview

Figure 4-1 gives an overview of a 1x1 and 1x4 cage without modules installed. Figure 4-2 depicts a 1x1 cage with an OSFP module in the fully inserted position.

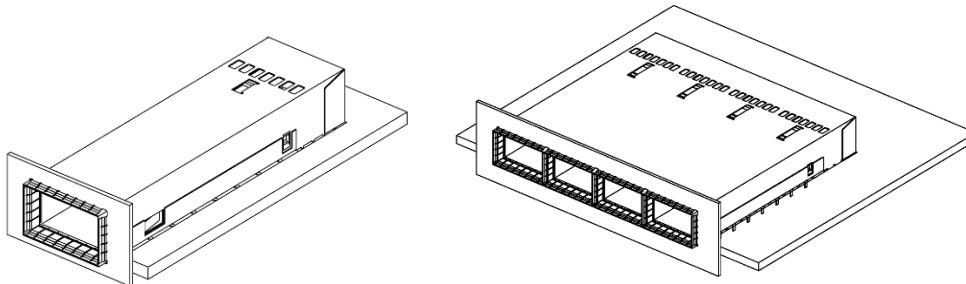


Figure 4-1: 1x1 and 1x4 cage, host PCB and panel

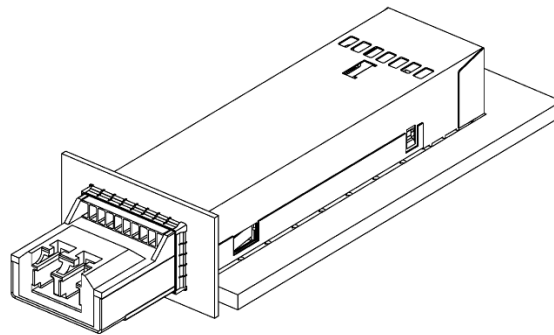


Figure 4-2: OSFP module in a 1x1 cage

In the cage and connector mechanical drawings included throughout this specification, the datum as defined in Table 4-1 shall apply. For datum of the module, see Table 3-1.

Table 4-1: Descriptions of the cage and connector mechanical datum

Designator	Description	Figure
G	Forward stop of Cage	Figure 4-3
H	Seating plane of Cage on host pc board	Figure 4-3
J	Width of inside of Cage	Figure 4-4
K	Connector guide post #1	Figure 4-7; Figure 4-22
L	Cage Pin #1	Figure 4-3
M	Top surface of host pc board	Figure 4-13
N	Host pc board through hole #1 to accept Connector guide post	Figure 4-13
P	Host pc board through hole #2 to accept Connector guide post	Figure 4-14
R	Host pc board through hole #1 to accept Cage Pin	Figure 4-14
S	Width of Connector	Figure 4-22
T	Front surface of Connector	Figure 4-22
U	Seating plane of Connector	Figure 4-22



## 4.2 Cage Dimensions and Positioning Pin

Figure 4-3 through Figure 4-6 shows cage datum, positioning pin, port size and cage height. In addition, Figure 4-7 shows nominal dimensions between the module and the cage when the module is fully inserted. Note that the compliant pins in the cage are placed to support belly-to-belly applications. For ganged cages, some compliant pins shall be shorter to support the belly-to-belly application properly. Figure 4-8 shows the length of the compliant pins for a 1x4 cage. Figure 4-16 shows the host PCB board layout for a 1x4 cage.

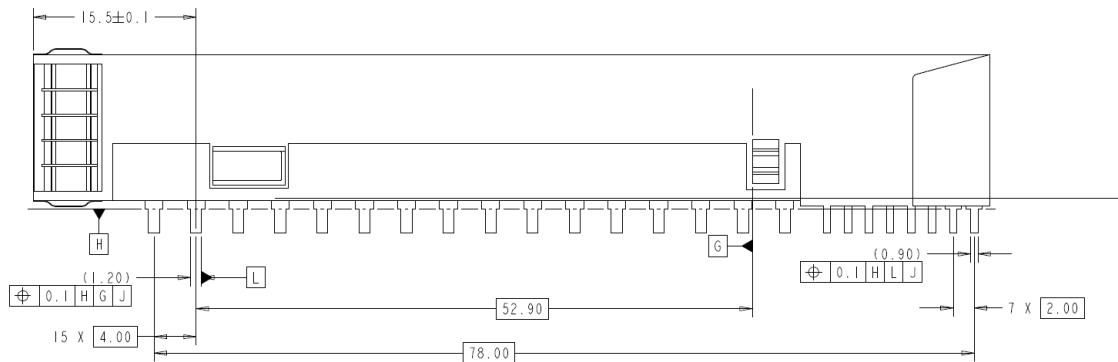


Figure 4-3: Cage positioning pins and forward stop

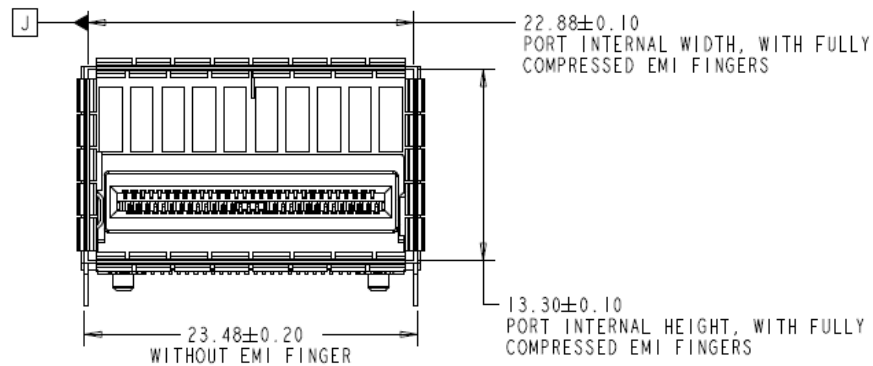


Figure 4-4: Port internal width and height

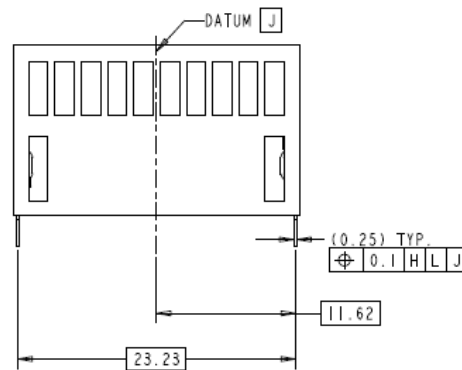


Figure 4-5: Cage positioning pins

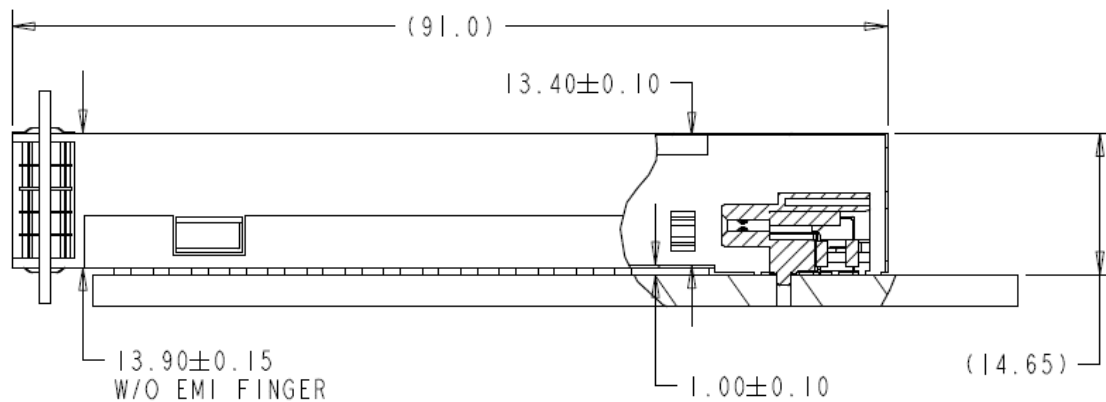
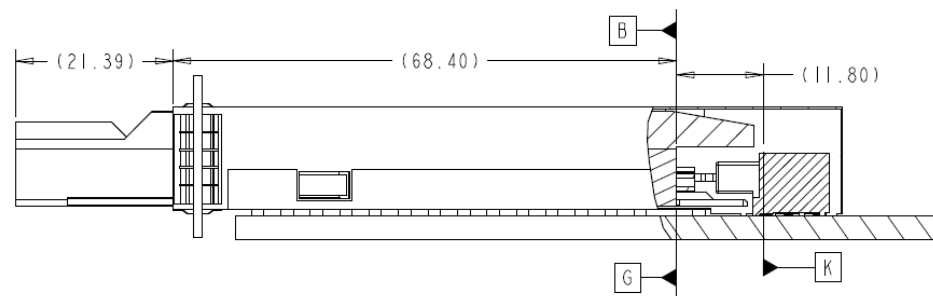


Figure 4-6: Side view of a 1x1 cage with vertical cage dimensions



DATUM B: MODULE FORWARD STOP  
 DATUM G: CAGE FORWARD STOP  
 DATUM K: CONNECTOR GUIDE POST

THIS FIGURE SHOWS THE DATUM ALIGNMENT BETWEEN CONNECTOR, CAGE AND MODULE AND ALSO SHOWS THE REFERENCE DIMENSION OF THE MODULE INSIDE CAGE, WHEN THE MODULE IS FULLY PUSHED IN.

Figure 4-7: Side view of a 1x1 cage with axial reference dimensions

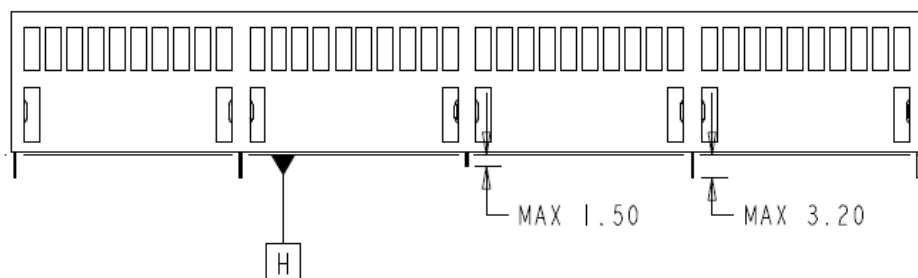


Figure 4-8: Length of the compliant pins into the board, for belly-to-belly application

### 4.3 EMI Finger Pitches

Figure 4-9 gives EMI finger dimensions to be used for the internal side of top and bottom EMI fingers. These pitches are designed such that the OSFP module as described in Section 3.4 is compatible. Fingers for the left, right, and outside of the cage shall be designed to ensure appropriate EMI shielding, but finger pitch is not specified. This EMI

finger pitch specification shall be applied to the stacked SMT cage (Section 5) and stacked press-fit cage (Section 6).

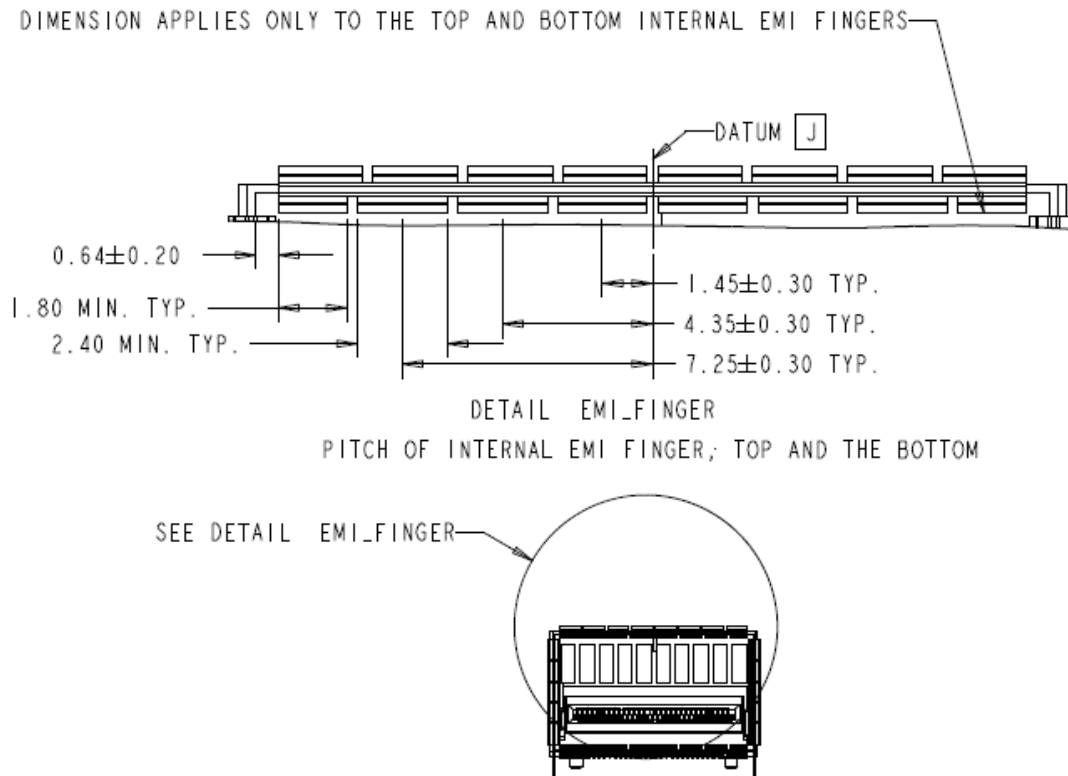


Figure 4-9: Internal EMI finger, top and bottom

#### 4.4 Ventilation Hole, Key and Stop

Figure 4-10 shows the key and forward stop features. The keying feature will prevent the module from being inserted upside down.

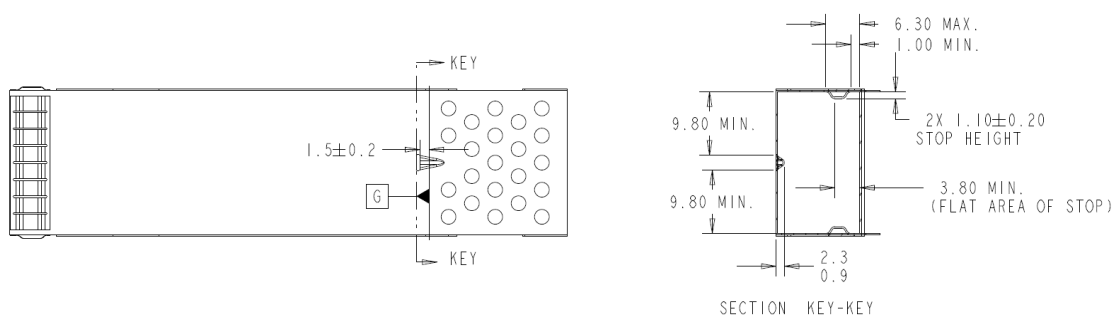
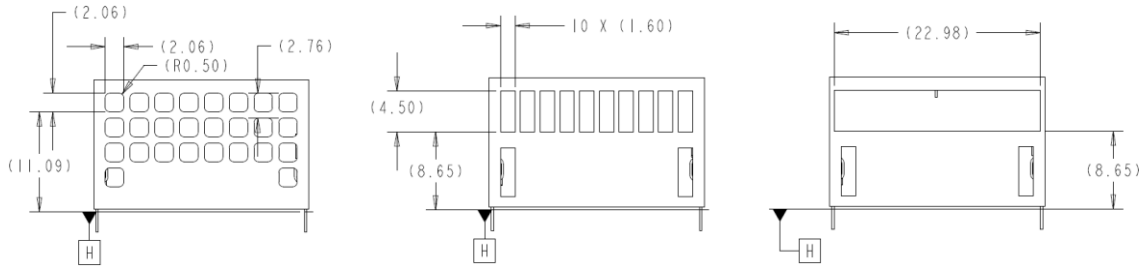
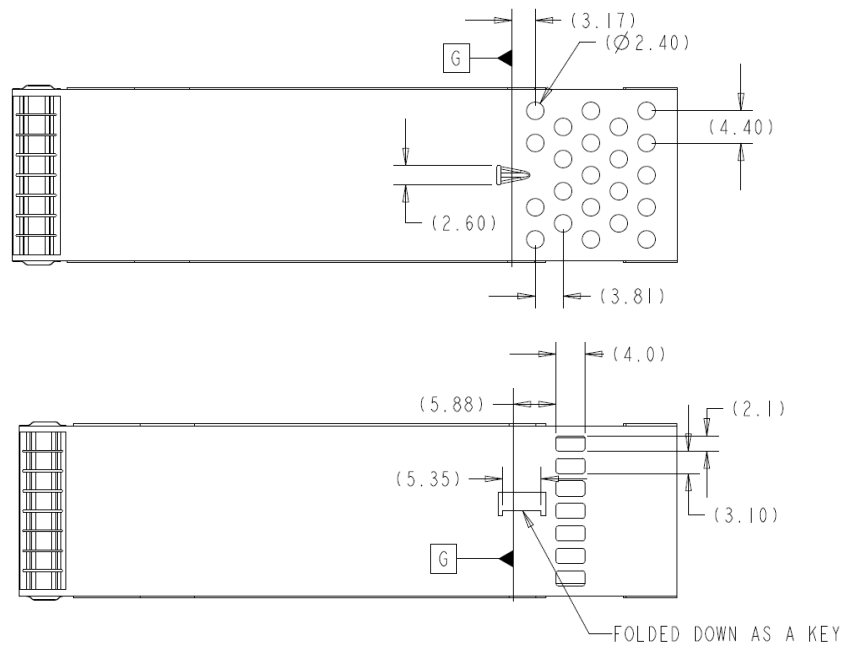


Figure 4-10: Key and stop

The cage should have ventilation holes to allow airflow. Refer to Figure 4-11 and Figure 4-12 for examples of ventilation hole details.



*Figure 4-11: Rear ventilation holes, three example designs*



*Figure 4-12: Top ventilation holes, two example designs*

#### 4.5 Host PCB Layout – 1x1 Cage

The host PCB layout pattern to accept a 1x1 cage is detailed in Figure 4-13 through Figure 4-15.

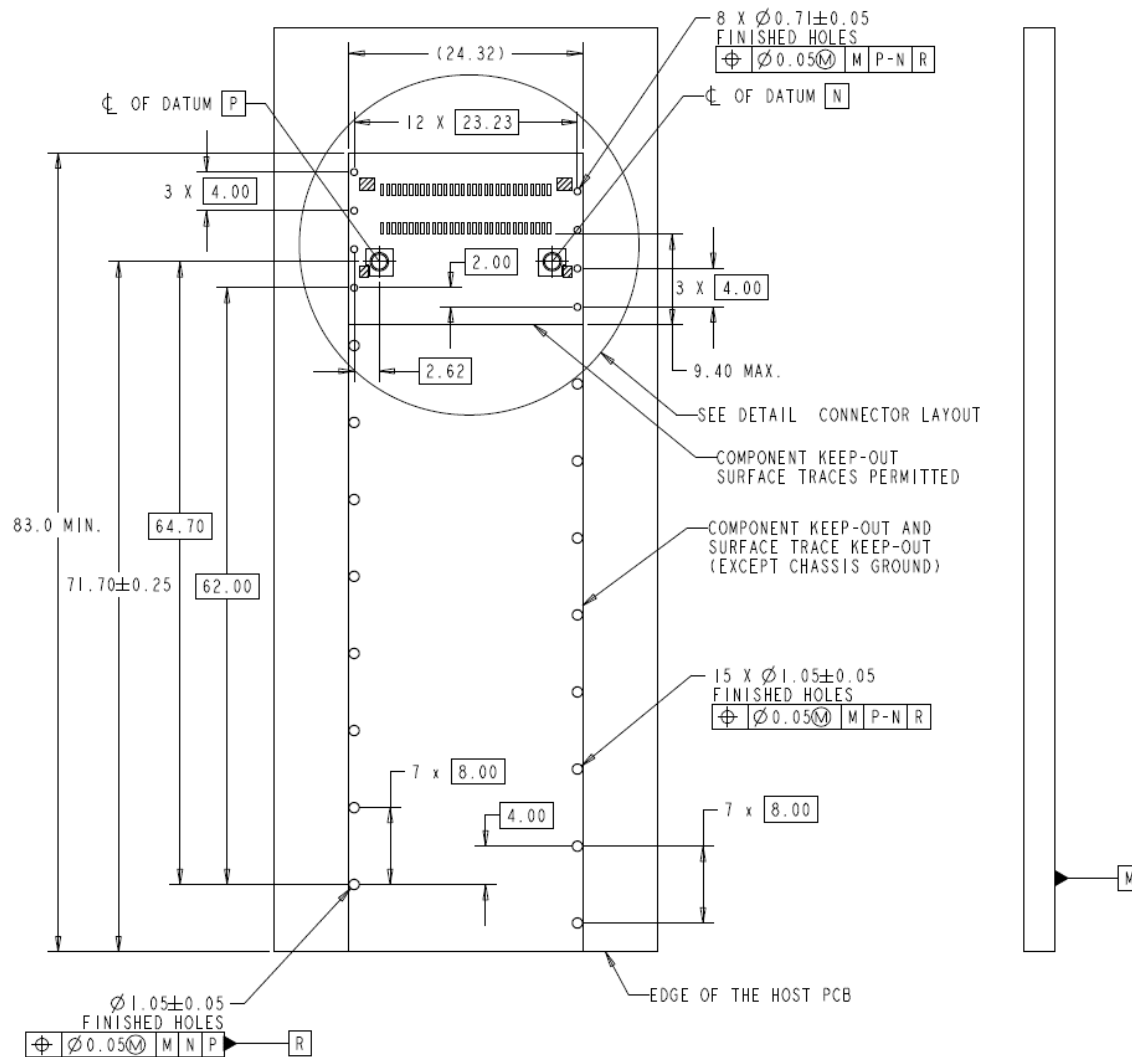
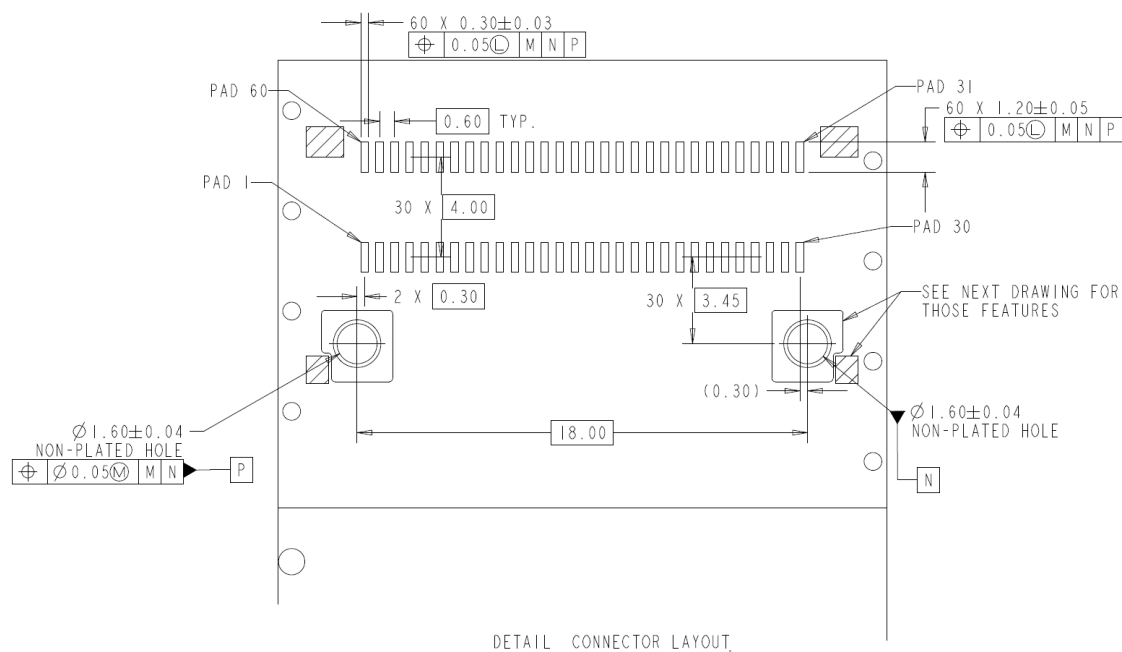
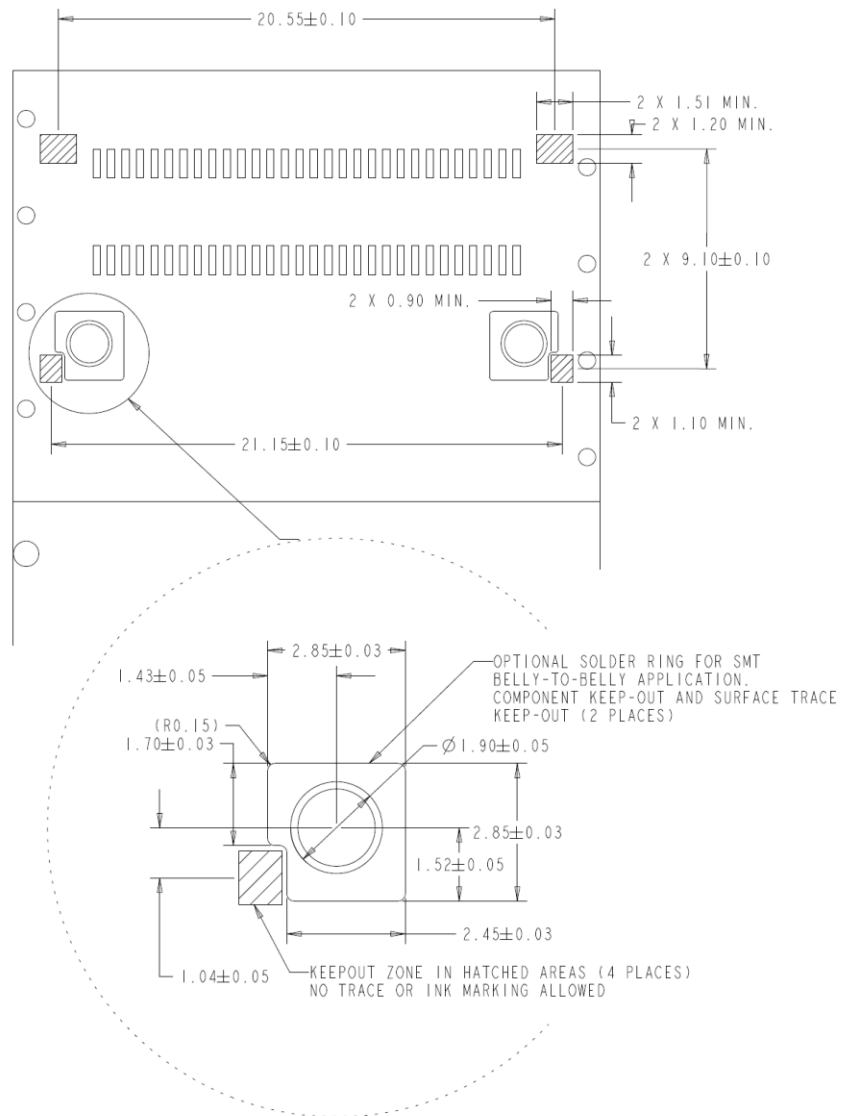


Figure 4-13: Host PCB layout for 1x1 cage



*Figure 4-14: Host PCB layout, details*

Figure 4-15 shows keep out areas and optional solder rings. The solder rings are for SMT belly-to-belly applications, thus applying solder to the area is optional. The keep out areas are there in order to prevent interference with the connector in Figure 4-22. The keep out areas should be kept in the layout in all cases regardless of whether solder is applied to the optional solder ring area.



**Figure 4-15: Solder ring for belly-to-belly application**

#### 4.6 Host PCB Layout – 1x4 Cage

For a 1x4 cage, the host PCB layout shall have a 23.23mm horizontal pitch from cage-to-cage as in Figure 4-16.

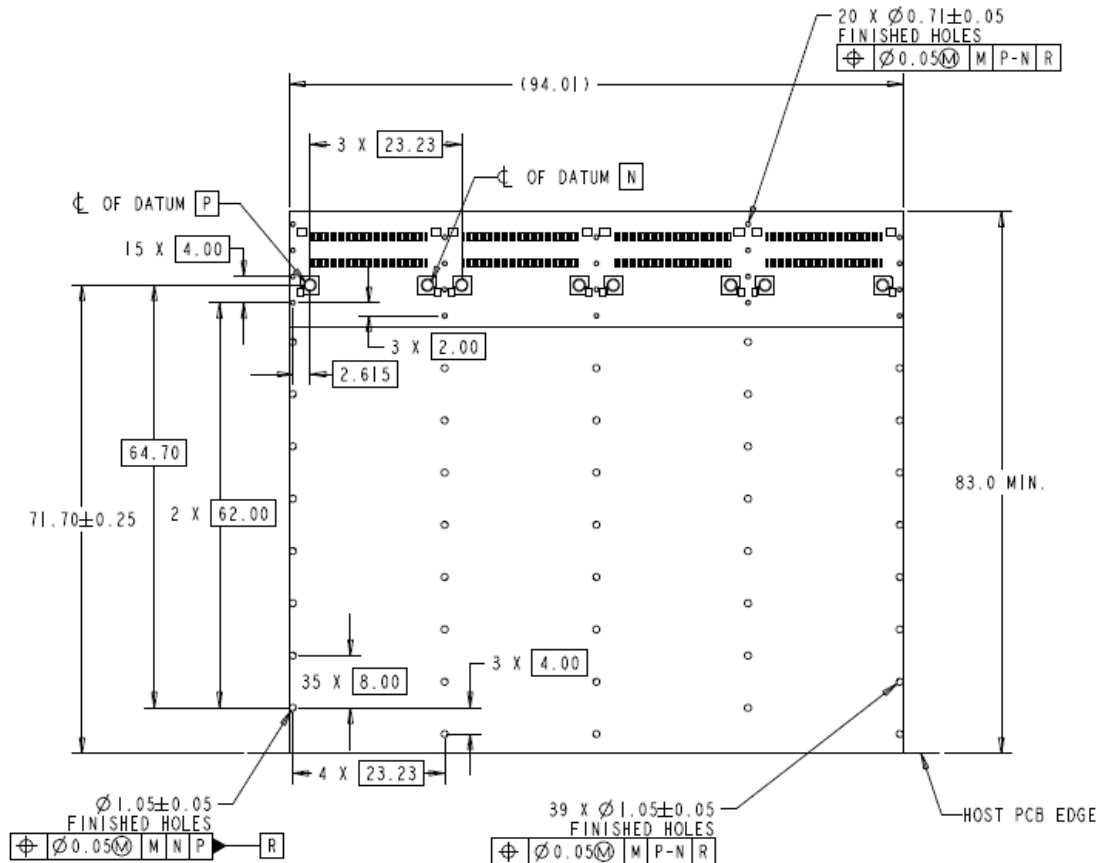
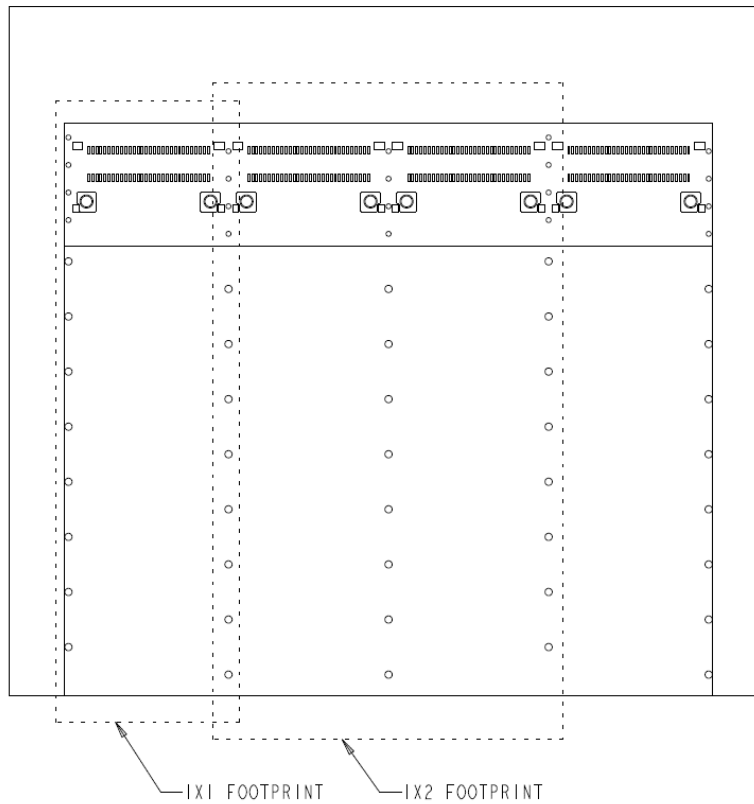


Figure 4-16: Host PCB layout for 1x4 cage



Figure 4-17 compares the host PCB layout between the 1x1, 1x2 and 1x4. The details of the 1x2 PCB layout are not given in this document.



*Figure 4-17: Comparison of host PCB layout between 1x1, 1x2 and 1x4*

#### 4.7 Latch Flaps in Cage

In the cage, flaps as shown in Figure 4-18 and Figure 4-19 shall be on both sides of the cage to latch the module into the cage. Flaps are shown in a 1x1 cage but can be applied to a ganged cage such as a 1x4 cage or any 1xN cage.

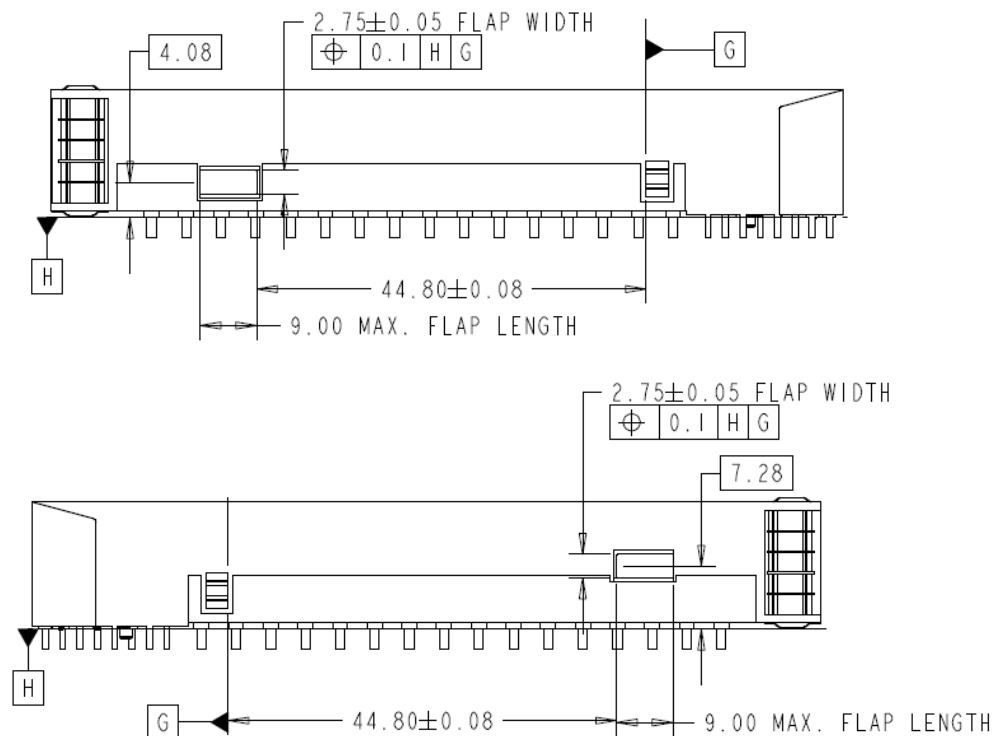


Figure 4-18: Latch feature, left and right side

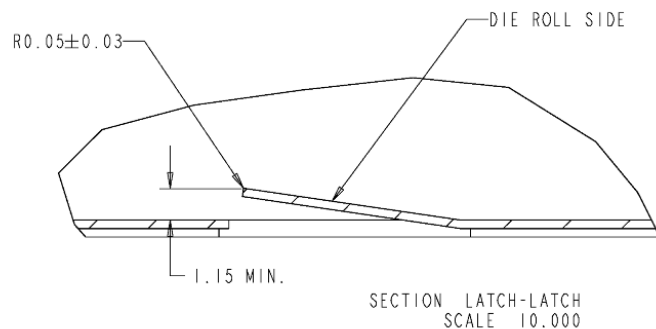


Figure 4-19: Latch flap, cross-sectional view from top

#### 4.8 Bezel Panel Cut-Out

The EMI spring fingers of the cage shall make contact to the inside of the bezel panel cut out in order to make ground contact. Figure 4-20 and Figure 4-21 show recommended dimensions of the bezel panel cut-out. As the horizontal pitch of the cage is 23.23mm, the bezel cut out width of 1x2 shall be 47.51mm while the detailed design is not depicted here.

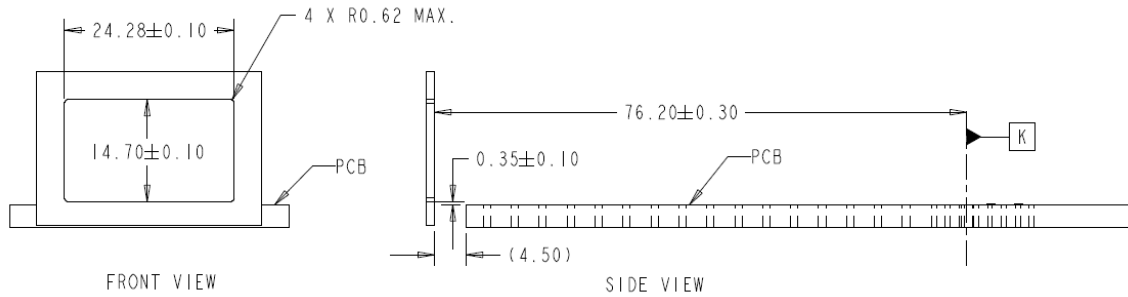


Figure 4-20: Bezel design and location for 1x1 cage

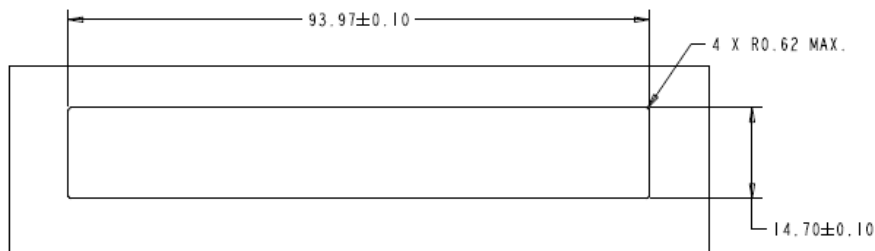


Figure 4-21: Bezel design for 1x4 cage

#### 4.9 Single Row SMT Connector

The electrical connector shall have the following dimensions to properly receive the module as well as allowing for air to pass over the module to the outside. The tail direction of the connector is specified as shown.

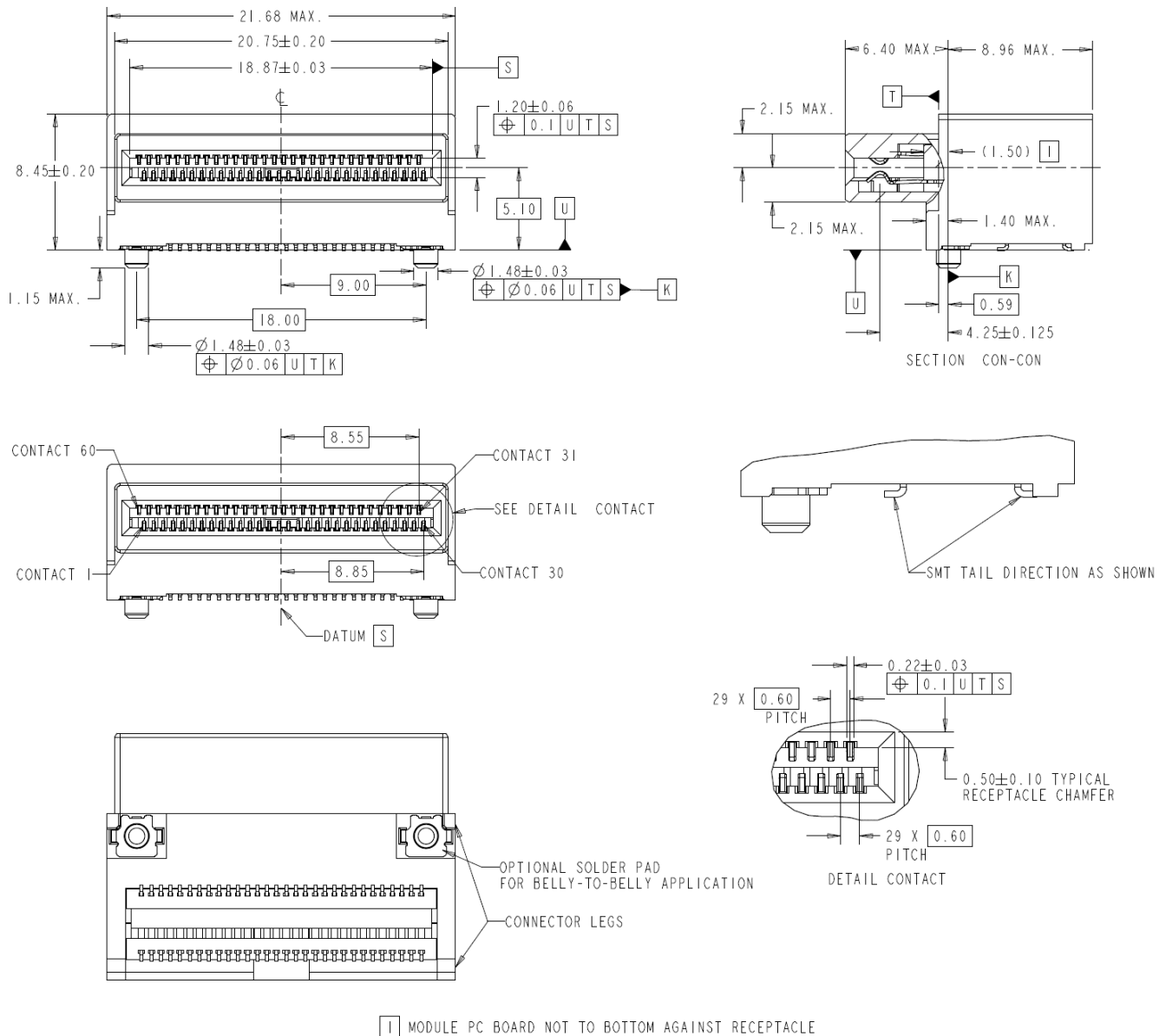


Figure 4-22: Surface mount connector

#### 4.10 Blank Plug

Any unused or empty port of a cage shall have a blank plug. The blank plug shall serve to minimize EMI while at the same time allowing for airflow comparable to a module. See Figure 4-23 for a recommended design. Blank plug shall be used on the stacked SMT (Section 5) and Stacked press-fit cage (Section 6).

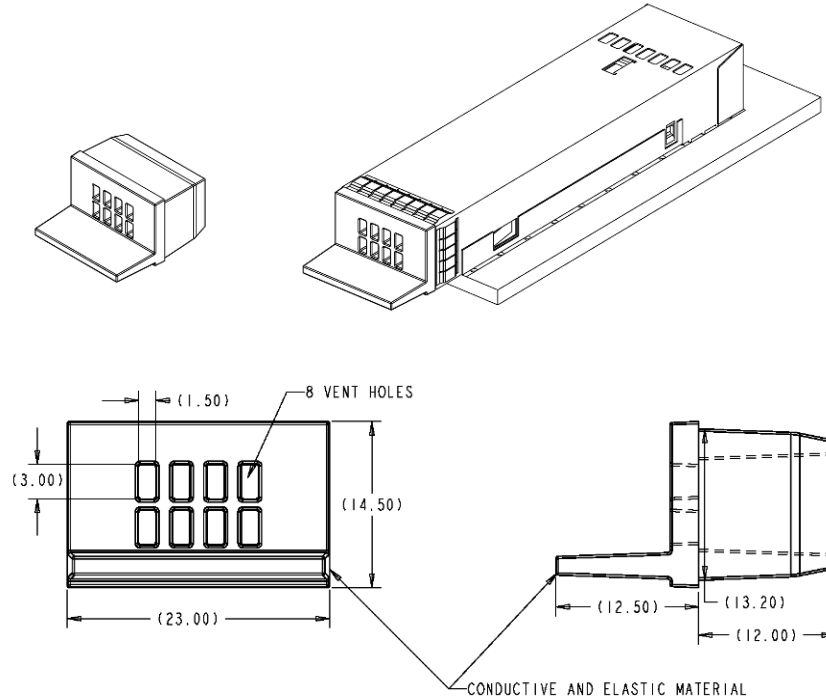


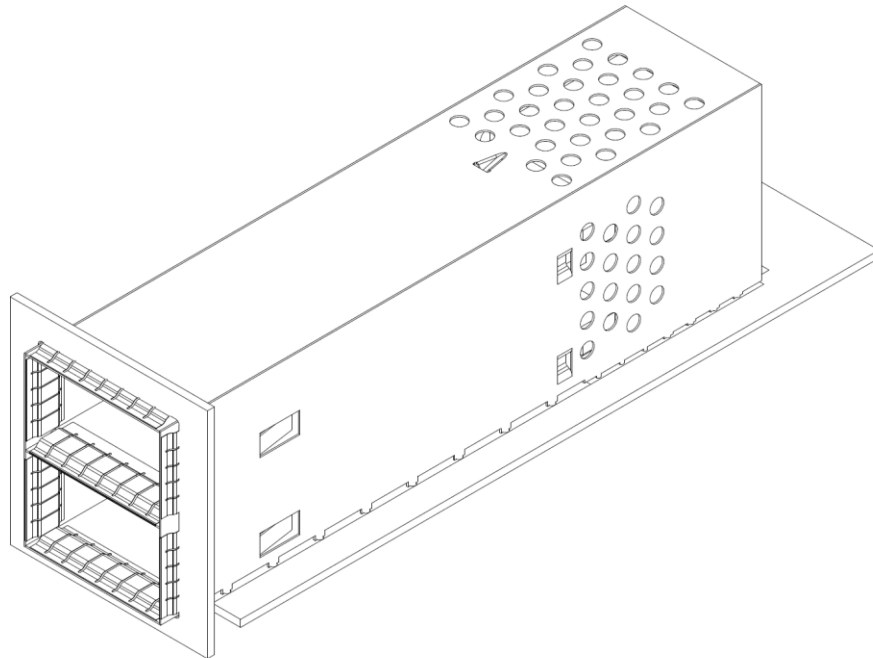
Figure 4-23: OSFP blank plug (reference design)

## 5 Stacked Surface Mount Technology Connector and Its Cage

In this section, the configuration of stacked SMT connector and cage are presented.

### 5.1 Overview

Figure 5-1 gives an overview of a 2x1 SMT connector, cage, host PCB and the panel.



*Figure 5-1: Stacked SMT 2x1 cage with host PCB and the panel*

In the mechanical drawings of this section, the datum as defined in Table 5-1 shall apply. Note that the same designators are used for the corresponding features of the single row SMT connector and its cage, as in Table 4-1.

*Table 5-1: Descriptions of the Stacked SMT cage and connector mechanical datum*

Designator	Description	Figure
G	Forward stop of Cage	Figure 5-2
H	Seating plane of Cage on host pc board	Figure 5-2
J	Width of inside of Cage	Figure 5-3
K	Connector guide post #1	Figure 5-18
L	Cage Pin #1	Figure 5-2
M	Top surface of host pc board	Figure 5-9
N	Host pc board through hole #1 to accept Connector guide post	Figure 5-9
P	Host pc board through hole #2 to accept Connector guide post	Figure 5-9
R	Host pc board through hole #1 to accept Cage Pin	Figure 5-9
U	Seating plane of Connector	Figure 5-18

Latch, stop and keying features of the cage are not specified in the mechanical drawings in this section. For those features, the same specification as the single row SMT connector and its cage in section 4 shall apply.

## 5.2 Cage Dimensions and Positioning Pin

Figure 5-2 through Figure 5-4 show cage datum, positioning pin, port size, and cage height. Figure 5-5 shows that the middle row compliance pins in the 1x4 cage should be shorter than the others to support belly-to-belly applications.

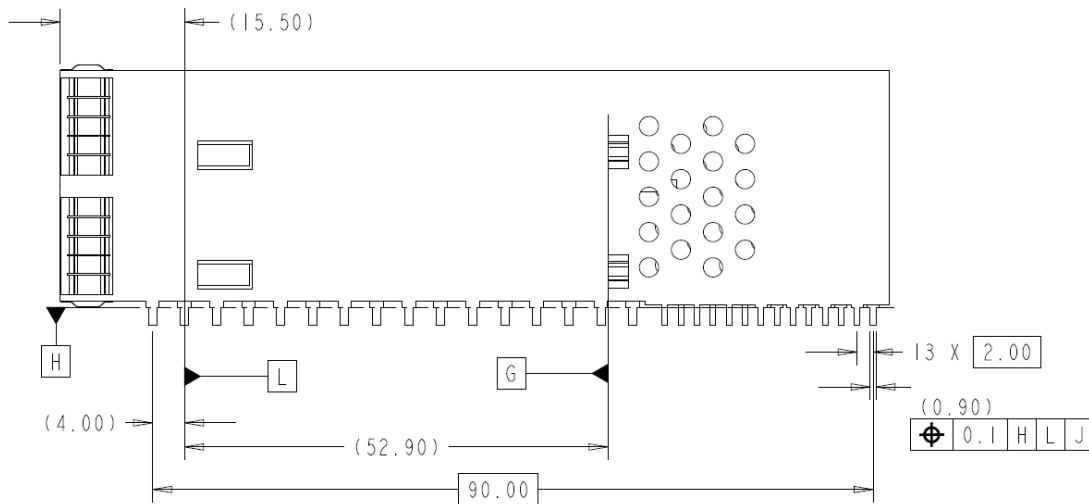


Figure 5-2: Cage positioning pins and forward stop

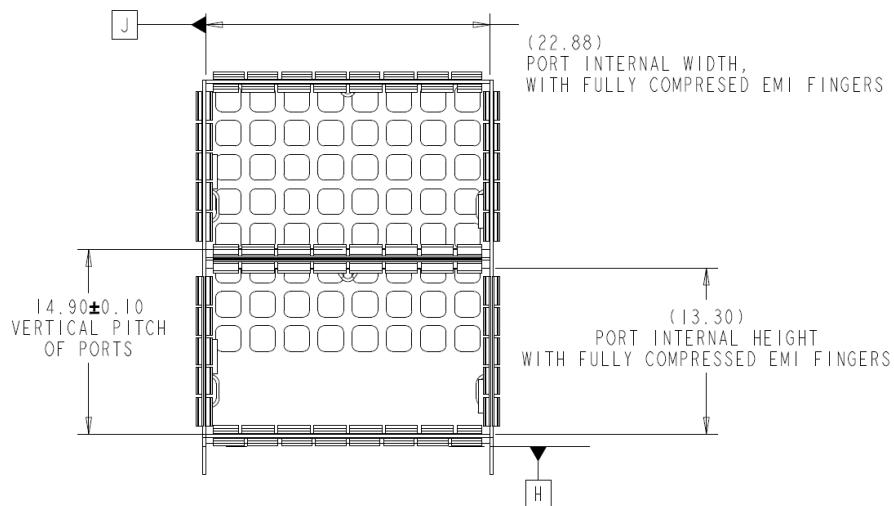


Figure 5-3: Port internal width, height and vertical pitch

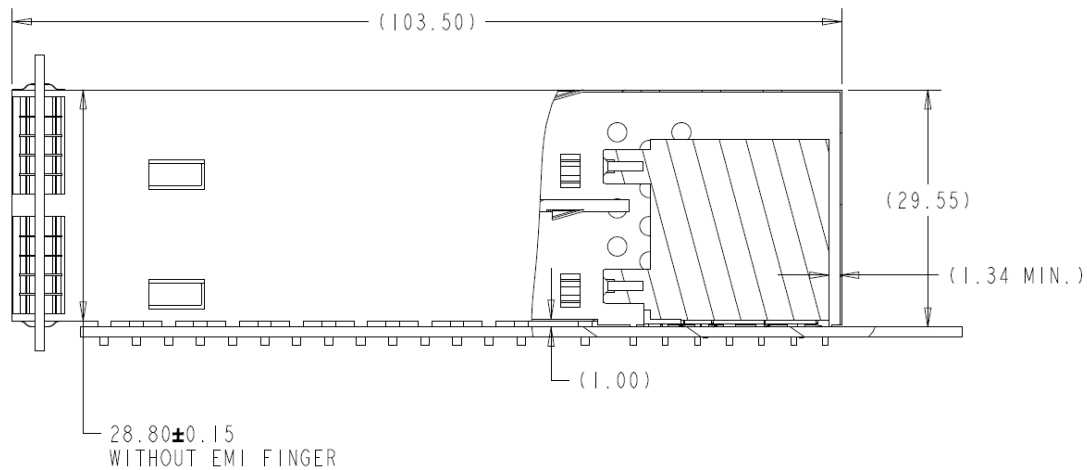


Figure 5-4: Side view of 2x1 cage with vertical cage dimensions

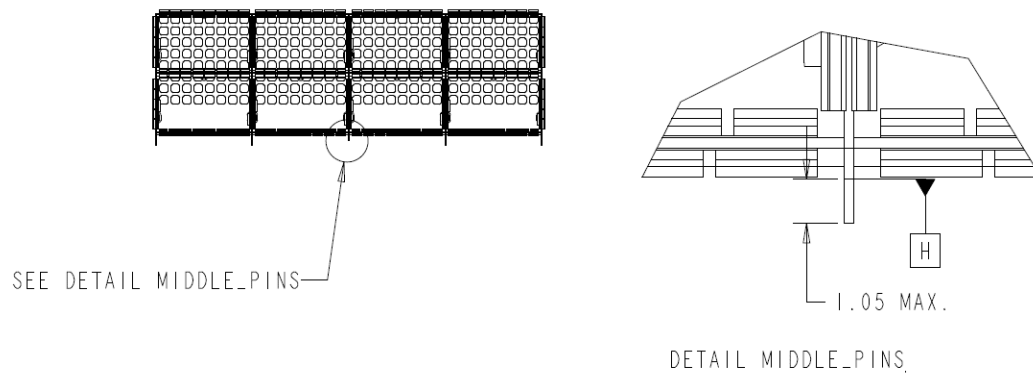


Figure 5-5: Length of the compliance pins at the middle, for belly-to-belly applications

### 5.3 Ventilation Holes

Cage should have ventilation holes to allow sufficient airflow. Figure 5-6, Figure 5-7 and Figure 5-8 show an example design.

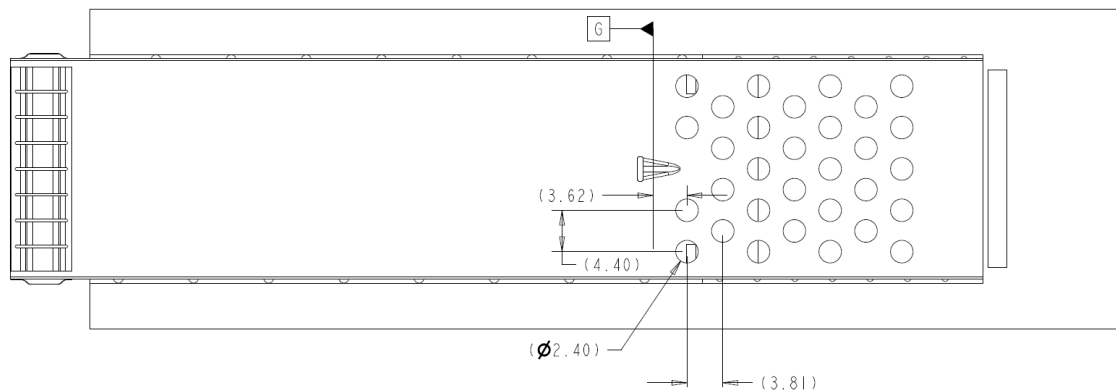
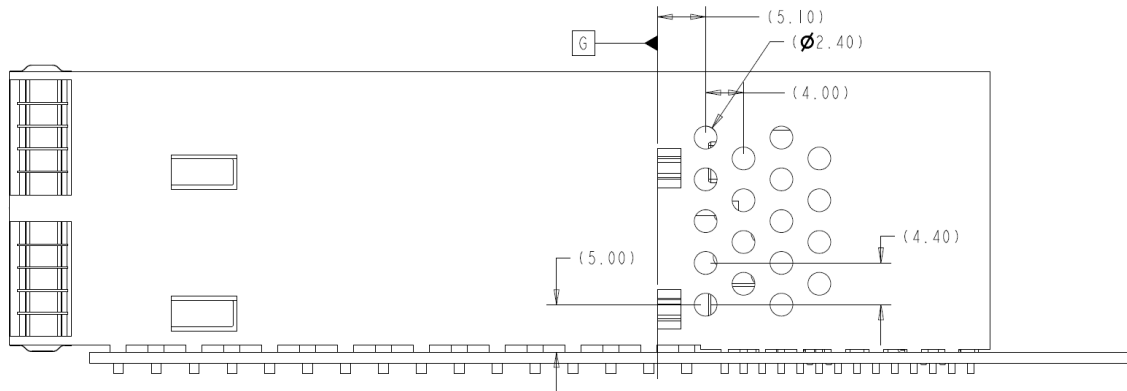
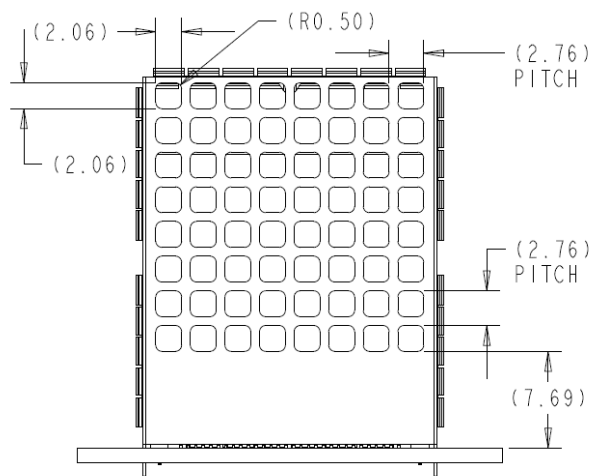


Figure 5-6: Top ventilation, example design





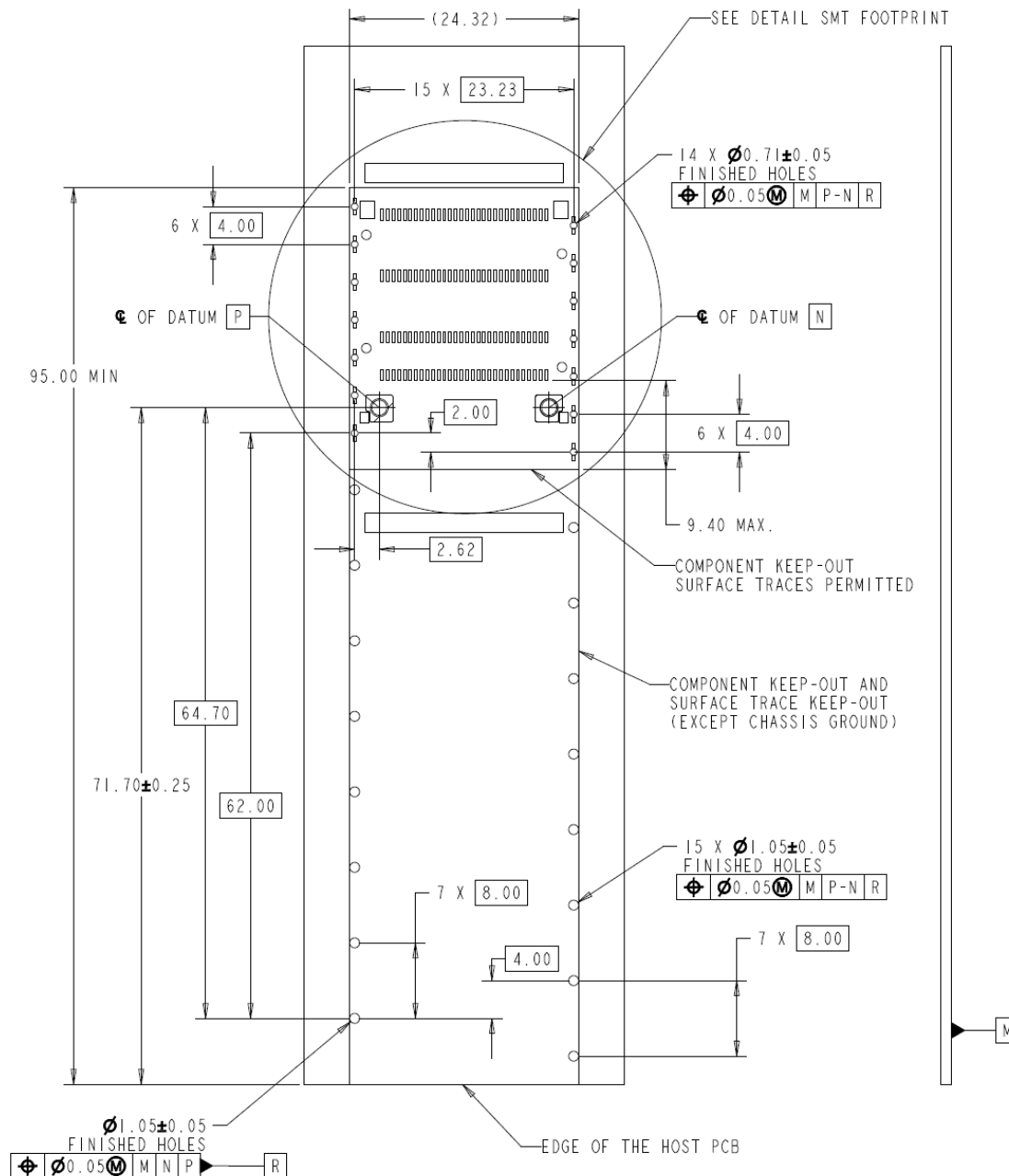
*Figure 5-7: Side ventilation, example design*



*Figure 5-8: Rear ventilation, example design*

#### 5.4 Host PCB Layout – 2x1 Cage

The host PCB layout pattern for 2x1 SMT connector and cage are presented in this section. Note that pads 1 to 60 correspond to pins 1 to 60 of the OSFP in the lower port as in Figure 11-1, while pads 61 to 120 correspond to pins 1 to 60 of the OSFP in the upper port.



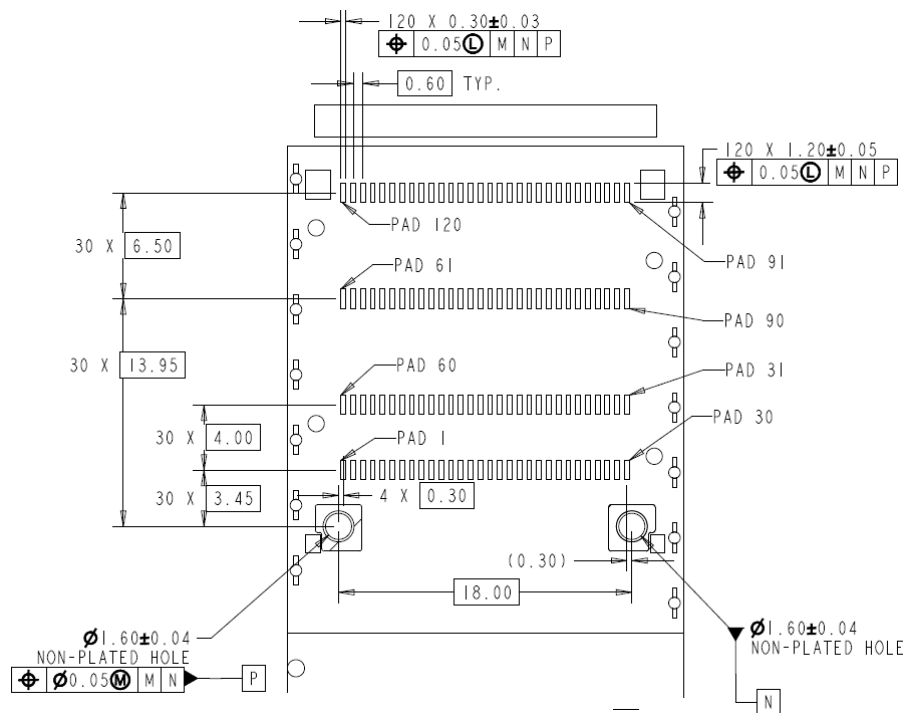


Figure 5-10: Host PCB layout, details

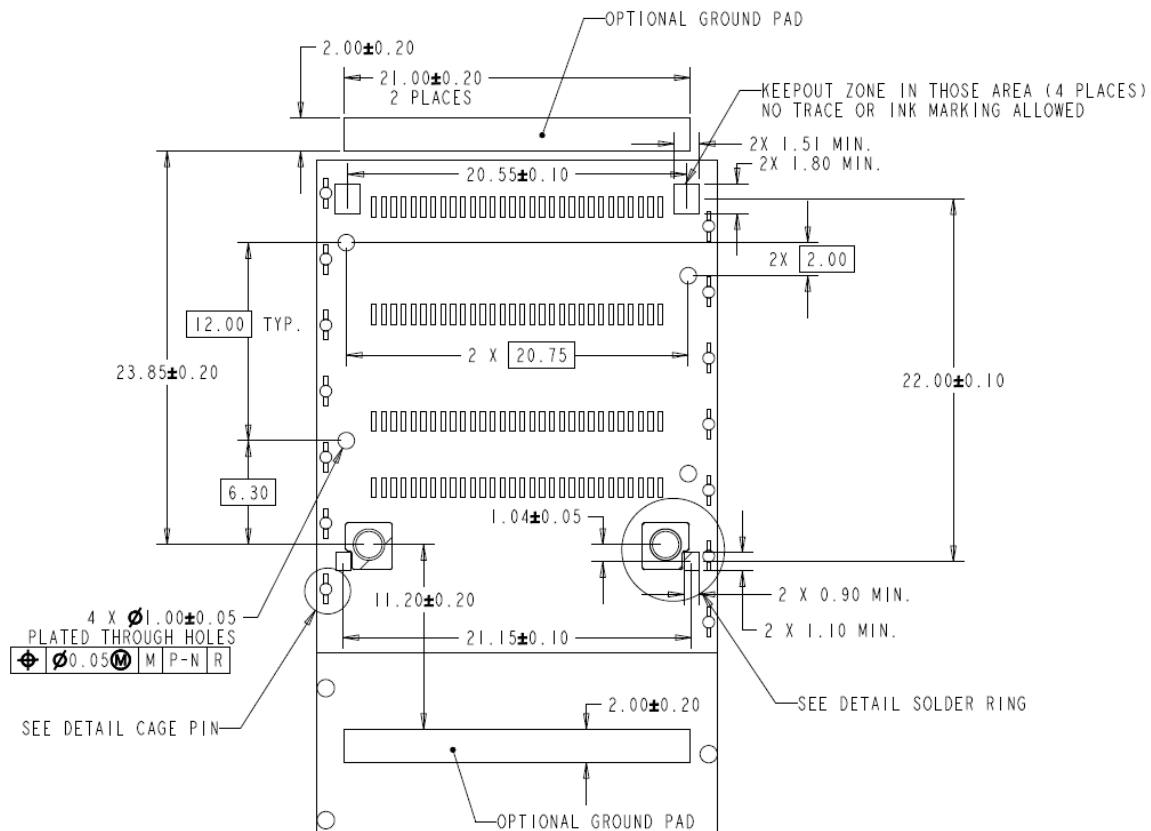


Figure 5-11: Layout for peg, retaining feature and ground pad

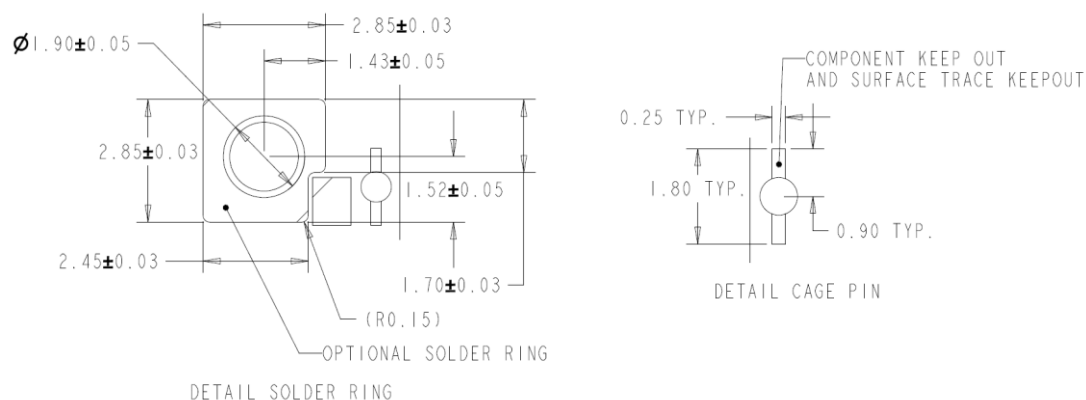


Figure 5-12: Details of optional solder ring (left) and cage pin keepout (right)

## 5.5 Host PCB Layout – 2x4 Cage

In this section, host PCB layout for the ganged cage is presented in a 2x4 cage host layout. Figure 5-14 shows the comparison of 2x1, 2x2 and 2x4, while the detailed layout specification of the 2x2 is not provided here.

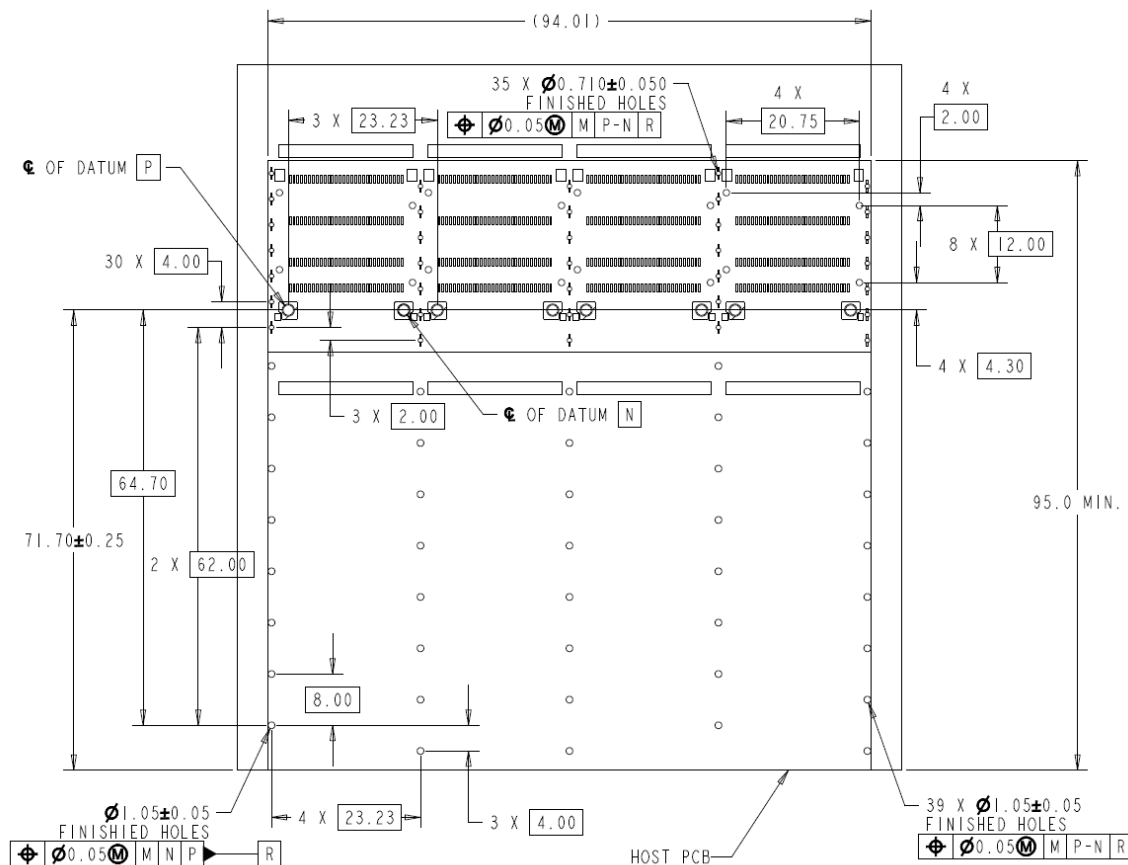


Figure 5-13: Host PCB layout for 2x4 cage

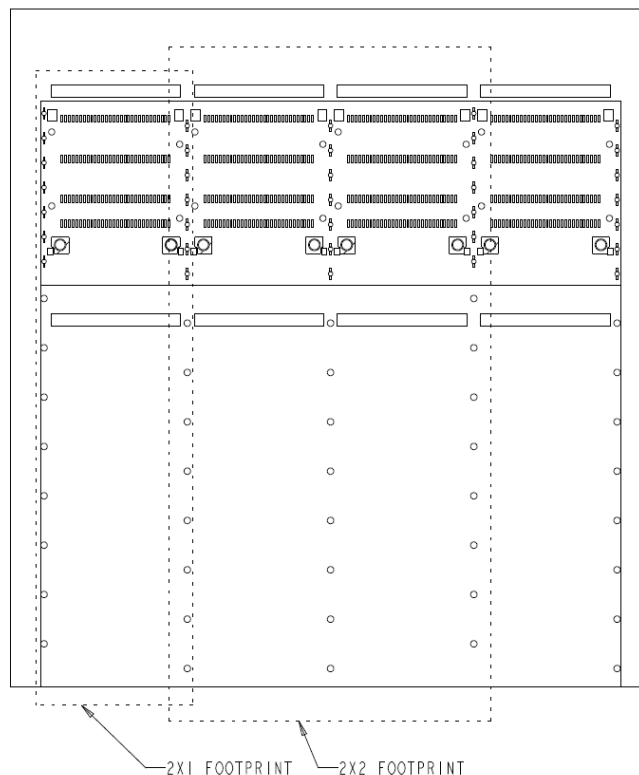


Figure 5-14: Comparison of SMT stacked 2x1, 2x2 and 2x4

## 5.6 PCB Thickness and Footprint for Belly-to-Belly Application

In this section, the minimum PCB thickness for the belly-to-belly application is shown, along with its host PCB layout. The cage and connector should be able to support a minimum PCB thickness as specified in Figure 5-15.

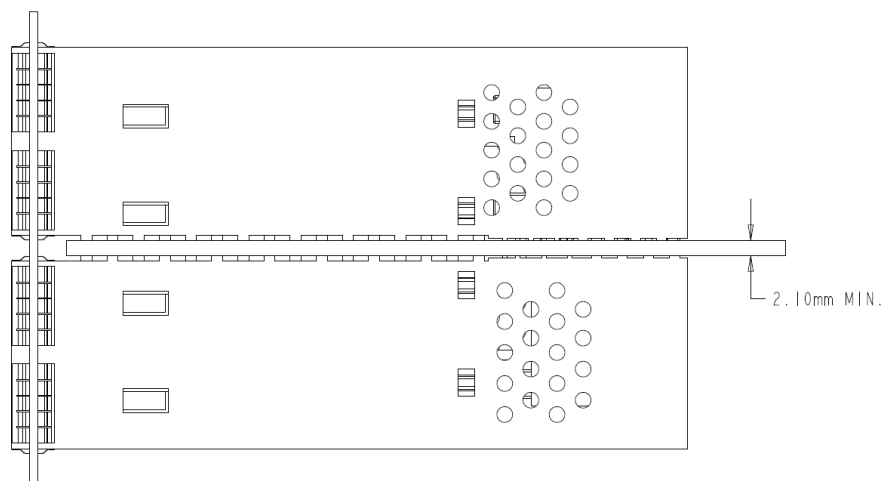


Figure 5-15: PCB thickness for belly-to-belly applications

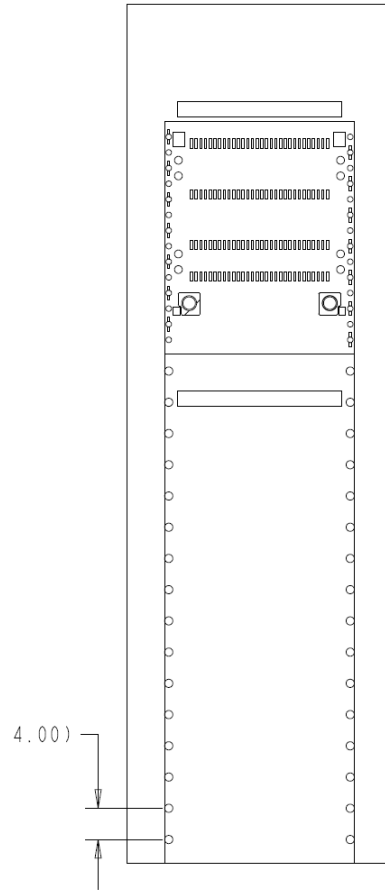


Figure 5-16: The host PCB layout for the 2x1 belly-to-belly applications

## 5.7 Stacked SMT Connector

Figure 5-17 to Figure 5-19 show the maximum mechanical envelope of the stacked SMT connector. Actual connector shape shall be smaller than this envelope. Figure 5-20 shows an example design, where the connector is optimized to provide better airflow to bottom row. For the contact and peg dimensions, specifications as defined in the section 4.9 for the single row SMT connector shall be applied.

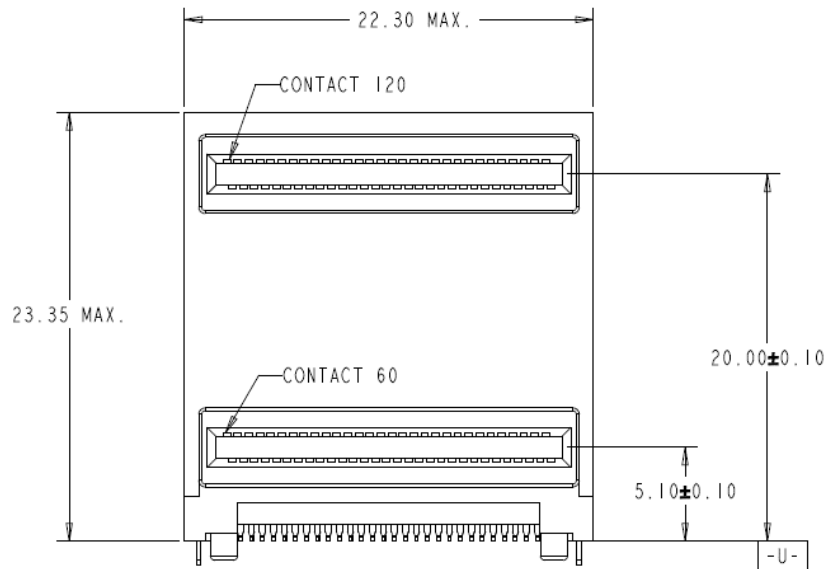


Figure 5-17: Stacked SMT connector, front view

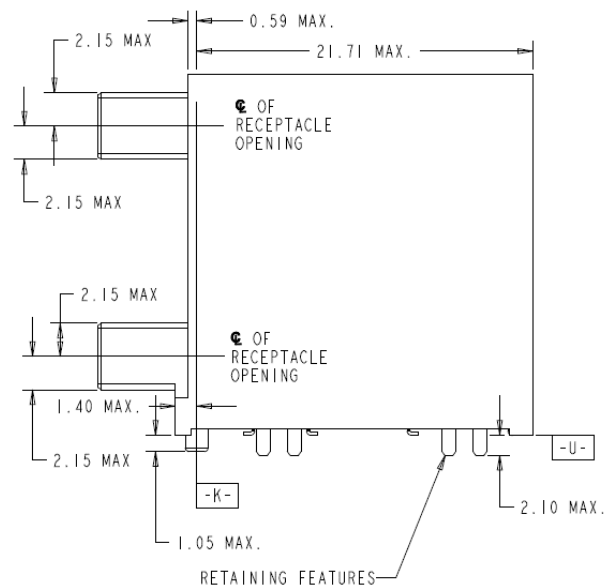


Figure 5-18: Stacked SMT connector, side view

For the retaining feature in Figure 5-18, the feature should be designed to allow proper retaining of the connector during and after soldering. The SMT tail direction shall be as defined in Figure 5-19.

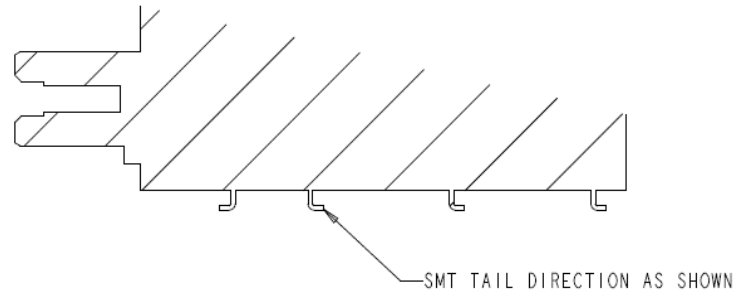


Figure 5-19: SMT tail direction

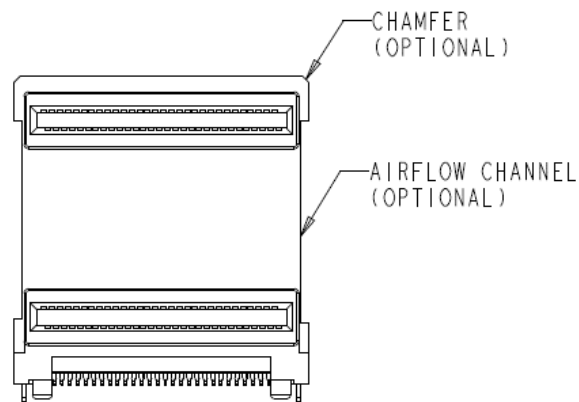


Figure 5-20: Example of actual connector design

## 5.8 Bezel Panel Cut-Out

In this section, the recommended shape for the bezel to make contact with the EMI finger of the cage is presented.

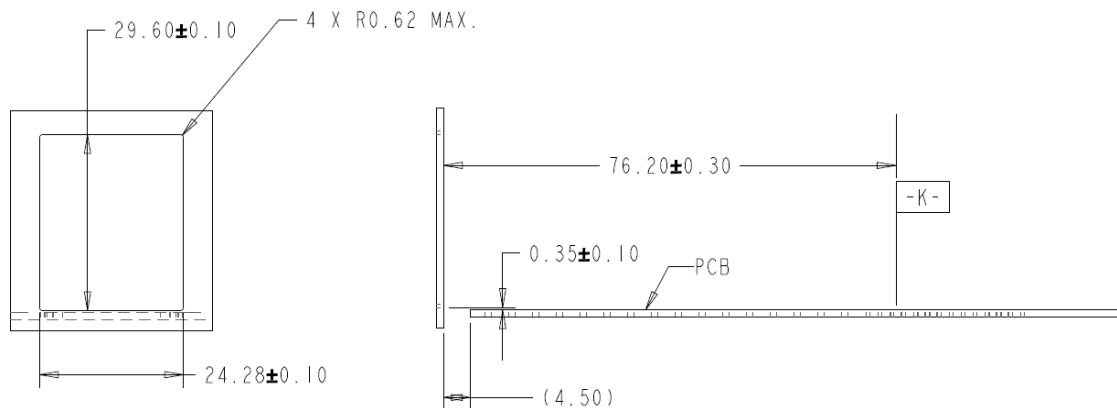


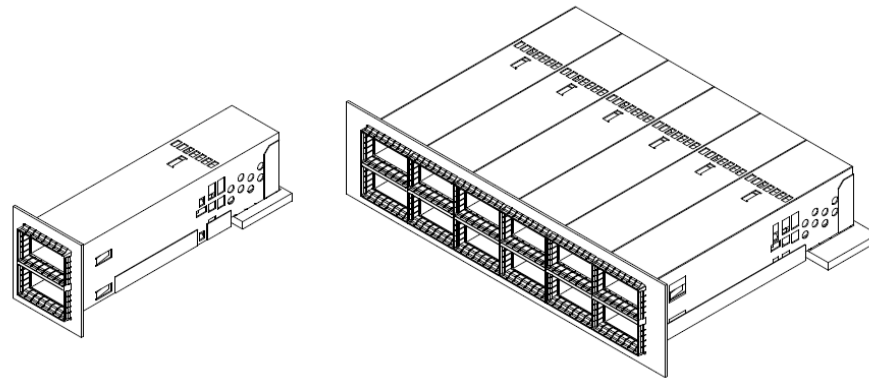
Figure 5-21: Bezel design and location for SMT 2x1 Cage



## 6 Press-fit Stacked OSFP Connector and cage Mechanical Specification

In this section, the press-fit stacked connector and cage for OSFP is described.

### 6.1 Overview



*Figure 6-1: Overview of stacked cage, 2x1 and 2x6*

In Figure 6-1, stacked cages of 2x1 and 2x6 are shown to demonstrate the stacked ganged cage. Both of the cages are shown with host PCB board and front panel. For stacked cage, additional datum as defined in Table 6-1 shall apply.

*Table 6-1: Descriptions of the module mechanical datum*

Designator	Description	Figure
V	Centerline of the Connector Peg	Figure 6-15
Y	Rear Surface of the Connector	Figure 6-15

### 6.2 Cage Dimensions and Positioning Pin

Figure 6-2 shows the location of the cage positioning pins and the forward stop. Note that the host PCB have significant distance from the front of the cage. In Figure 6-3, the vertical pitch of the stacked cage is defined. To ensure sufficient strength of the cage compliant pins, two material thickness of 0.40mm and 0.25mm are used in the reference design of the cage. 0.40mm thickness is used where the cage compliant pins are used. Figure 6-4 shows reference dimensions of the cage when assembled with host PCB and OSFP module.

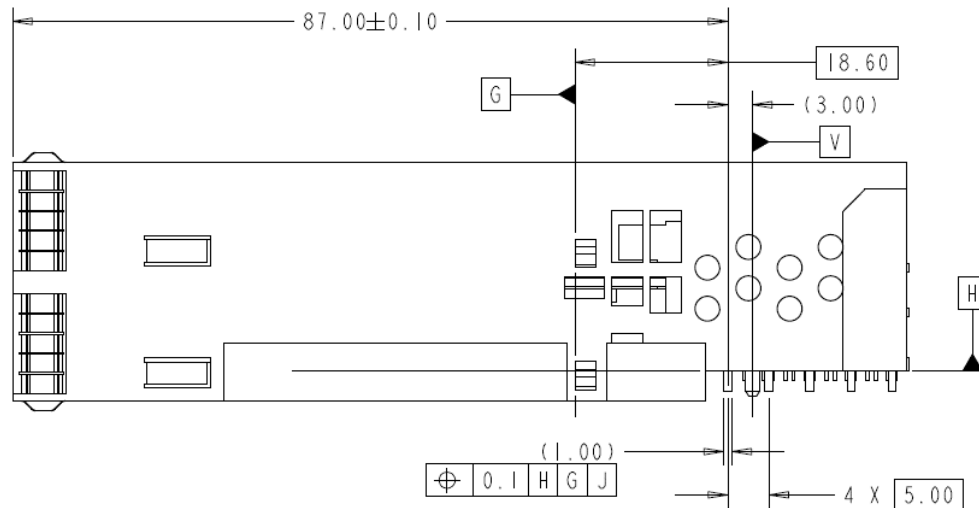


Figure 6-2: Stacked cage positioning pins and forward stop

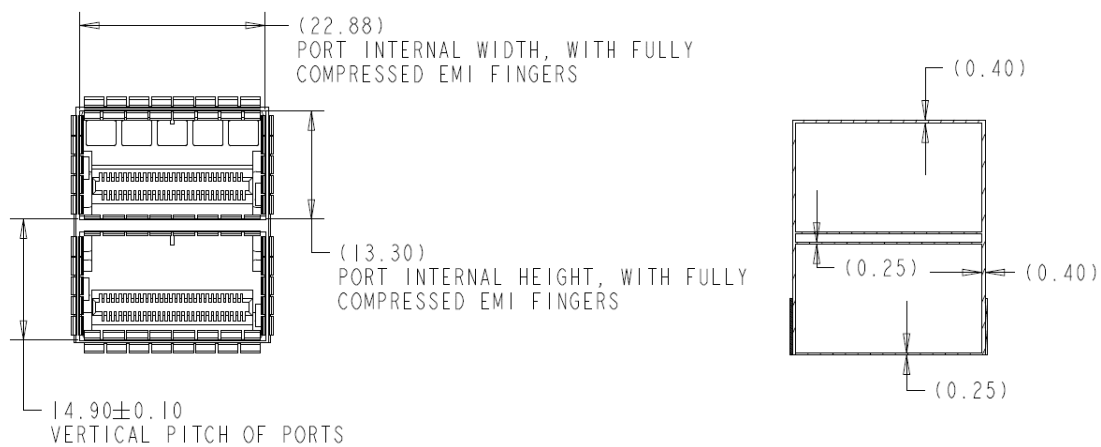


Figure 6-3: Stacked cage, port internal size, pitch and wall thickness

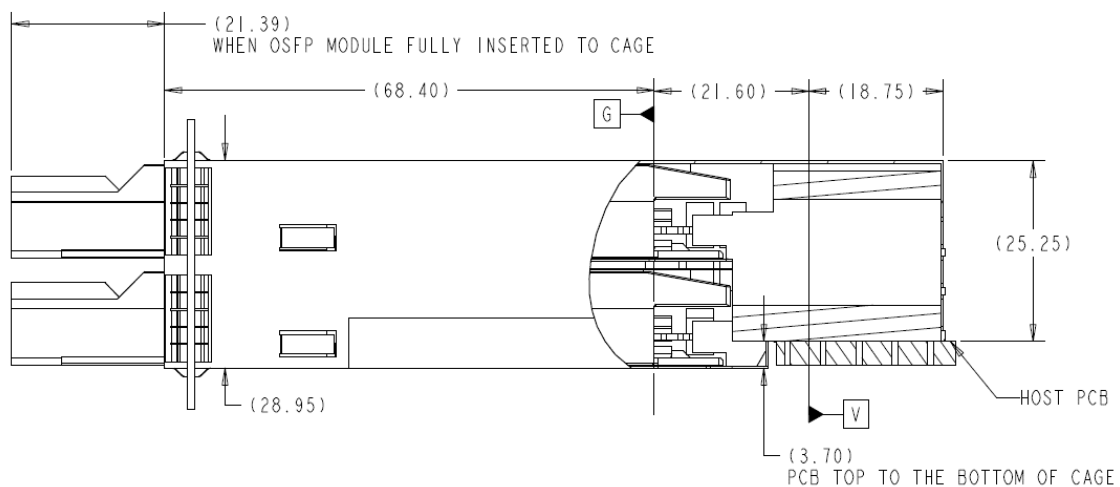


Figure 6-4: Cage with OSFP module, reference dimensions

### 6.3 Ventilation Holes

For proper cooling of the OSFP module in the stacked cage, the cage shall have appropriate ventilation holes. From Figure 6-5 to Figure 6-8, the ventilation holes required in the stacked ganged cage are described. The vent holes are designed not only to help with airflow from front to back of the cage, but also to help with airflow between the top and bottom rows of the cage, airflow between neighboring ports and to the bottom of the cage.

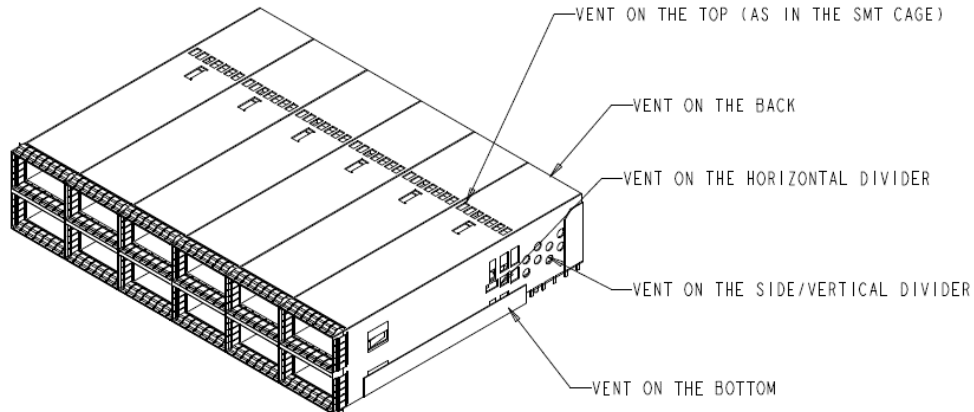


Figure 6-5: Overview of ventilation holes in the stacked cage

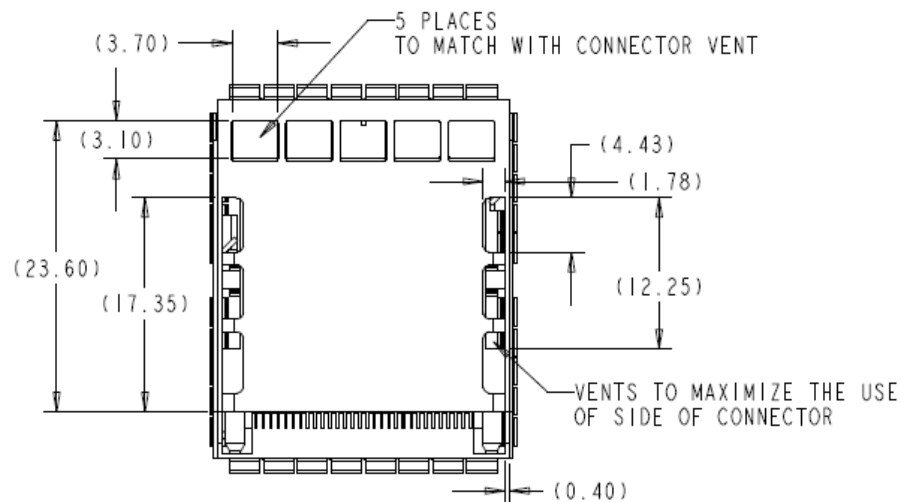
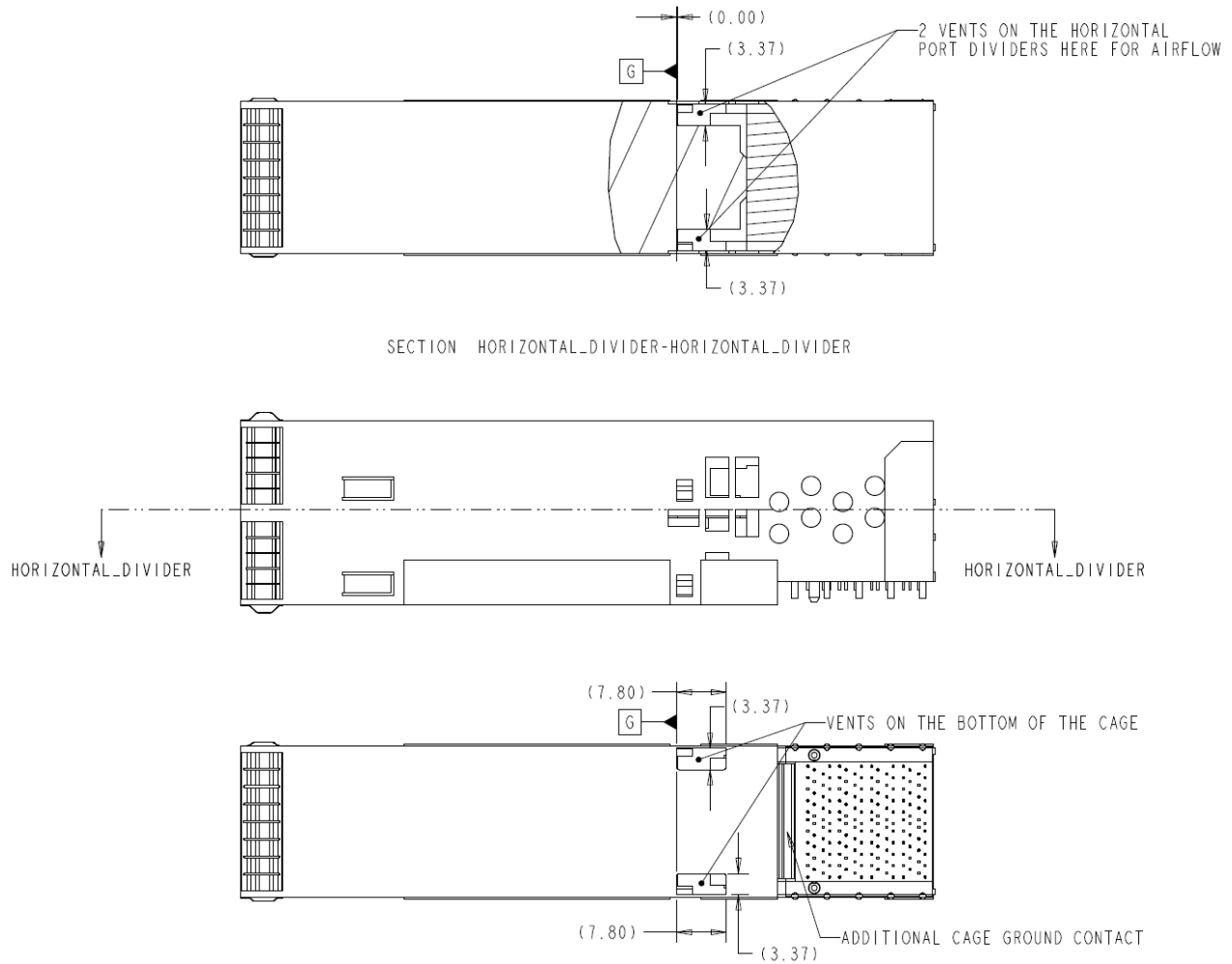
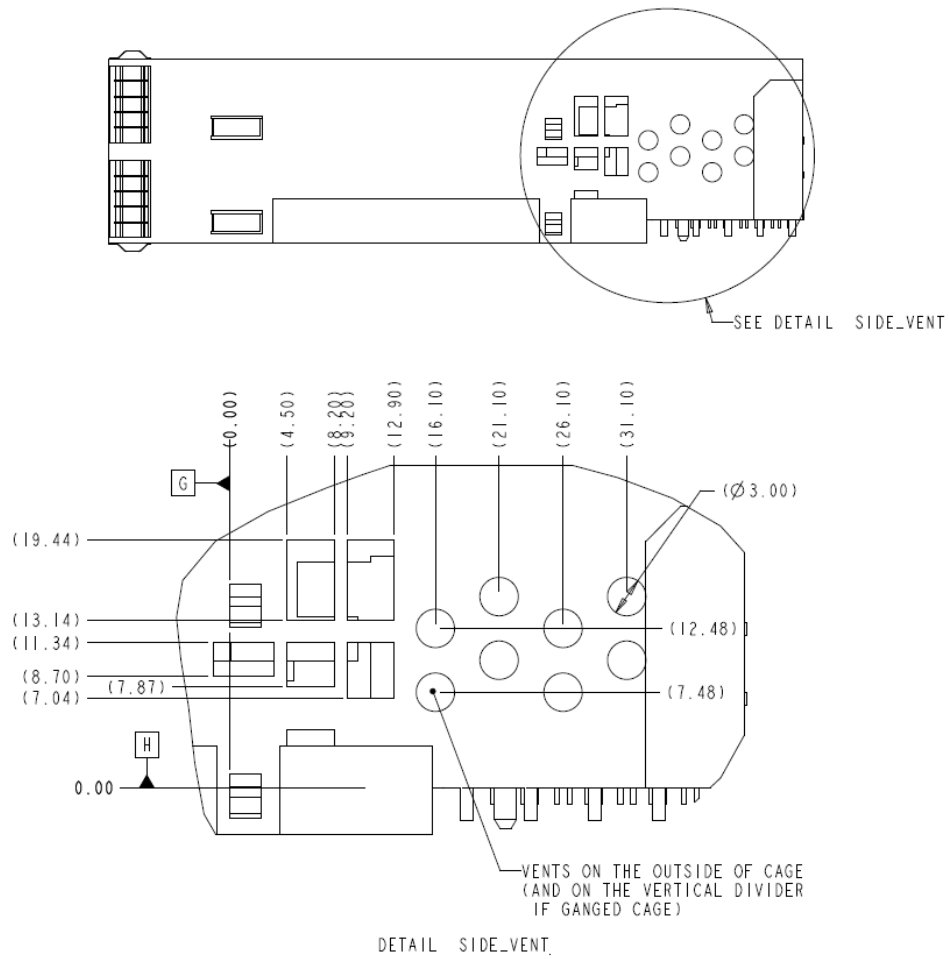


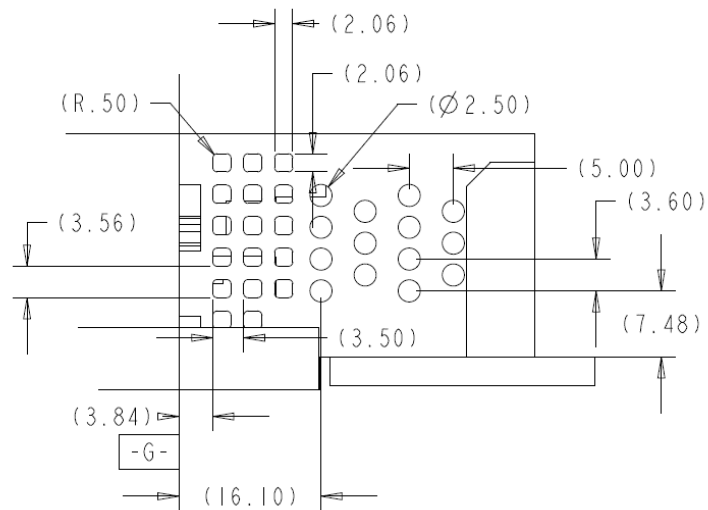
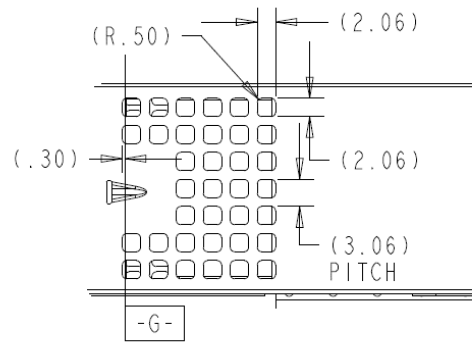
Figure 6-6: Ventilation holes at the back of the cage



*Figure 6-7: Ventilation holes in the horizontal divider and bottom*



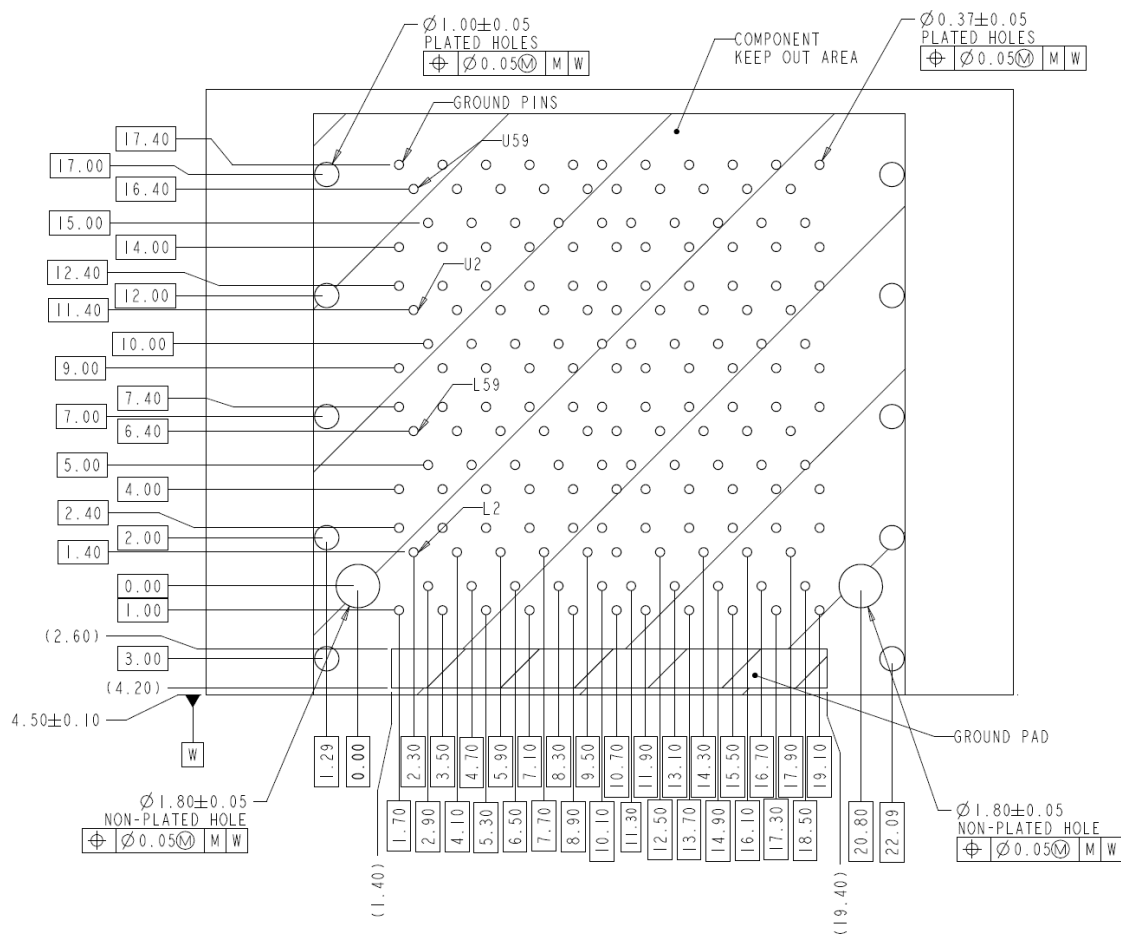
*Figure 6-8: Ventilation holes in the side of the cage, and vertical divider*



*Figure 6-9: Ventilation holes in the top (above view) and side (bottom view) of the cage, alternative example*

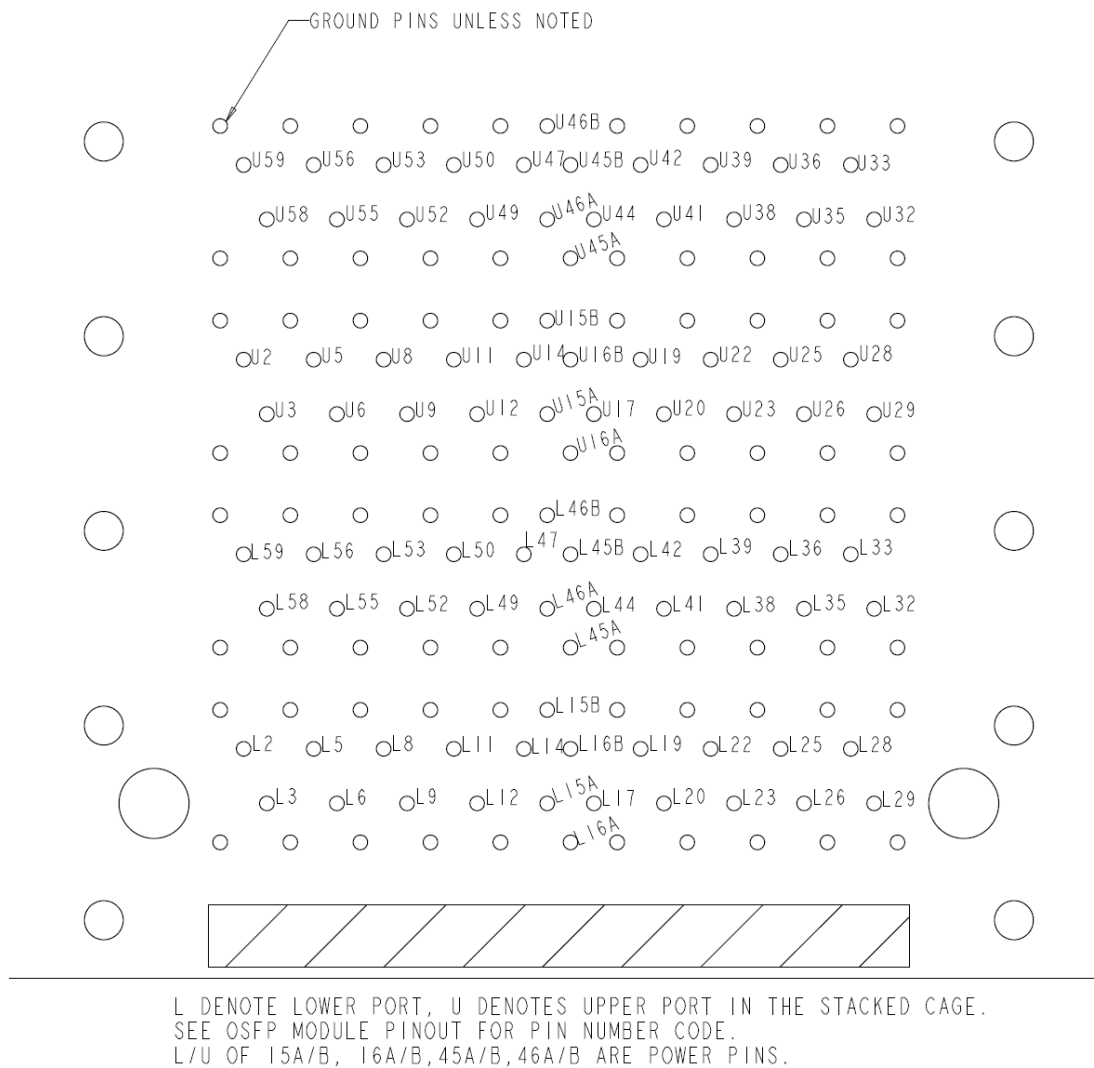
Figure 6-9 shows an alternative example design for top and side vent hole.

## 6.4 Host PCB Layout – 2x1 Cage



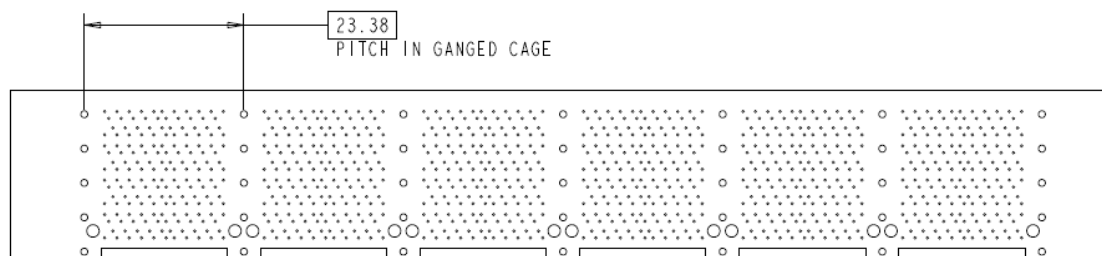
L2: PIN 2 OF THE LOWER PORT. U59: PIN 59 OF THE UPPER PORT.  
SEE OSFP MODULE PIN OUT FOR PIN NUMBER CODE AND DETAIL FIGURE.

**Figure 6-10: Host PCB layout for stacked connector**



## 6.5 Host PCB Layout – Ganged Stacked Cage

As shown in the Figure 6-12, ganged stacked cages shall have a pitch of 23.38mm.





## 6.6 Bezel Panel Cut-out

Figure 6-13 shows the bezel cut out for a 2x1 cage. Figure 6-14 shows bezel cut out for a 2x6 cage.

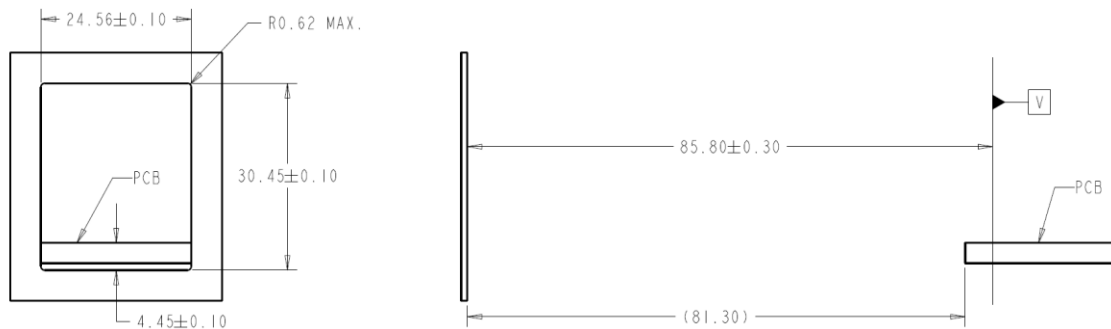


Figure 6-13: Bezel design and location for 2x1 cage

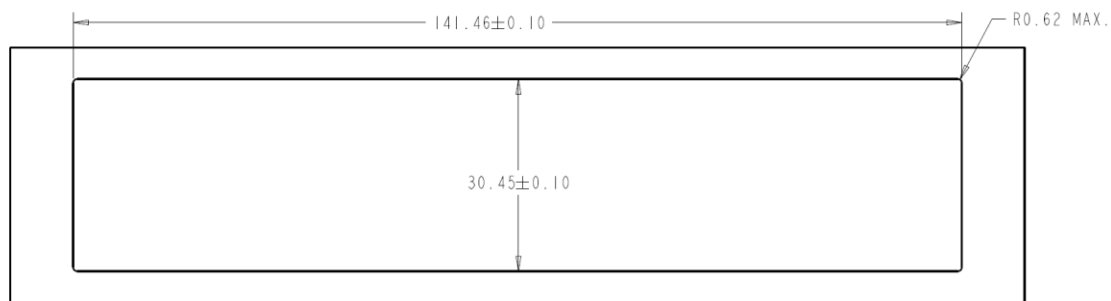


Figure 6-14: Bezel design for 2x6 cage

## 6.7 Electrical Connector for Stacked Cage (Press-fit)

The stacked electrical connector shall have the following dimensions to properly receive the module as well as allowing for air to pass over the module to the outside.

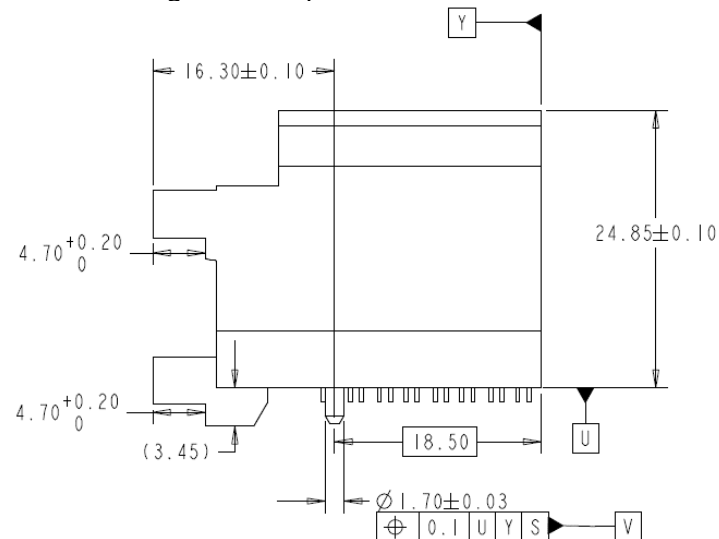


Figure 6-15: Stacked connector, side view

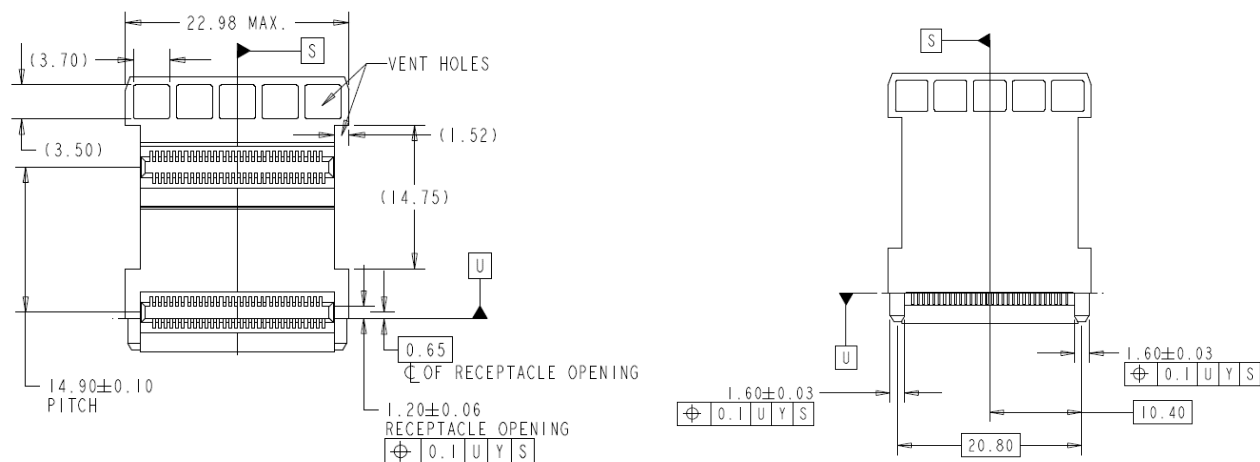


Figure 6-16: Stacked connector, front and back view

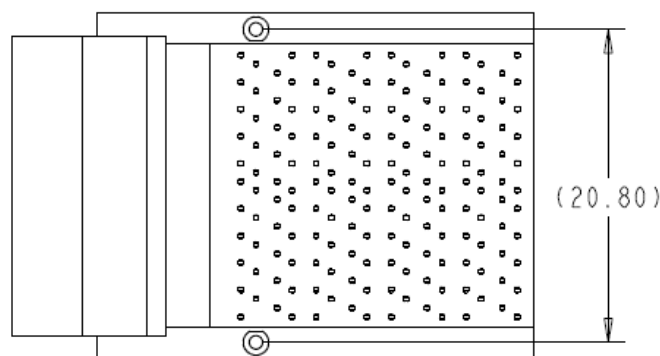


Figure 6-17: Stacked connector, bottom view

## 7 Plug-in and Removal of an OSFP Module

### 7.1 Insertion, Extraction, and Retention Forces for an OSFP Module

Table 7-1: Insertion, extraction, and retention forces for an OSFP module

Measurement	Minimum	Maximum	Units	Comments
OSFP Module Insertion	N/A	40	N	Module to be inserted into connector and cage with latch mechanism engaged.
OSFP Module Extraction	N/A	30	N	Module to be removed from connector and cage with latching mechanism disengaged.
OSFP Module Retention in Cage	125	N/A	N	No functional damage to module, connector, or cage with latching mechanism activated.

## 7.2 Durability

The required number of insertion and removal cycles as applicable to the OSFP module and its mating connector and cage are found in Table 7-2. The general requirement as applied to the values in the table is that no functional damage shall occur to the module, connector or cage.

*Table 7-2: Durability*

Insertion/Removal Cycles into Connector/Cage	Minimum (cycles)	Comments
Module Cycles	50	Number of cycles for an individual module, to be tested with cage, connector, and module; latches may be locked out during testing
Connector/Cage Cycles	100	Number of cycles for the connector and cage with multiple module, to be tested with cage, connector, and module; latches may be locked out during testing

## 8 Thermal Performance

### 8.1 Thermal Requirements

The OSFP module shall operate within one or more of the case temperature ranges defined in Table 8-1. The temperature ranges are applicable between 60m below sea level and 1800m above sea level.

*Table 8-1: Temperature Range Classes*

Class	Case Temperature
Standard	0 through 70°C
Reduced	20 through 60°C
Extended	-5 through 85°C
Industrial	-40 through 85°C
Custom	Custom temperature range. Module shall be able to post temperature range to host via management interface.

### 8.2 OSFP Module Airflow Impedance Curve

Figure 8-1 shows a typical airflow impedance range of an OSFP (module only) as measured along or through its heat sink. This typical range of airflow impedance can be used as a reference in an OSFP module's heat sink design and system design.

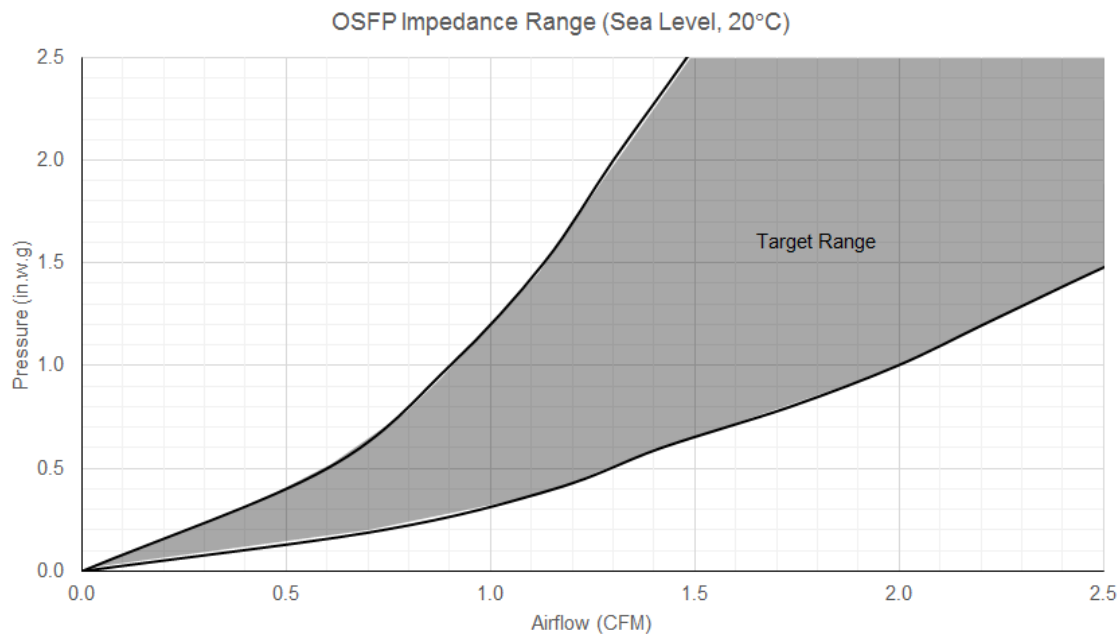


Figure 8-1: Target range of impediment to airflow of an OSFP module (20C, Sea Level)

### 8.3 Module Airflow Impedance Test Jig

The impedance range of Figure 8-1 was created using a jig as shown in Figure 8-2 and Figure 8-3. The jig is designed to support airflow along the heat sink as well as leakage around the module. A positive stop located within the jig's cavity ensures that the module is inserted into the jig at the same depth as with a cage.

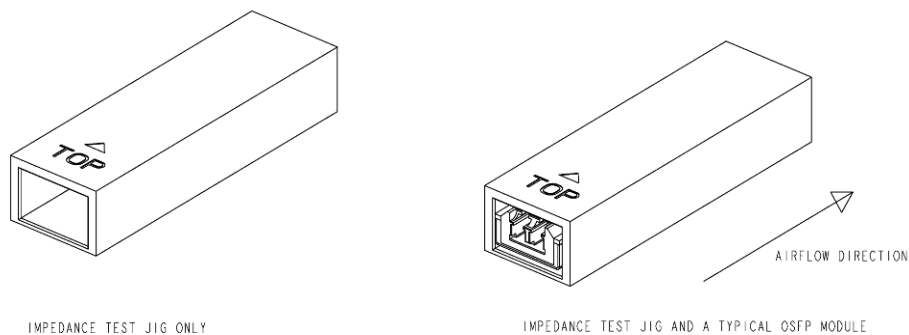


Figure 8-2: Impedance test setup

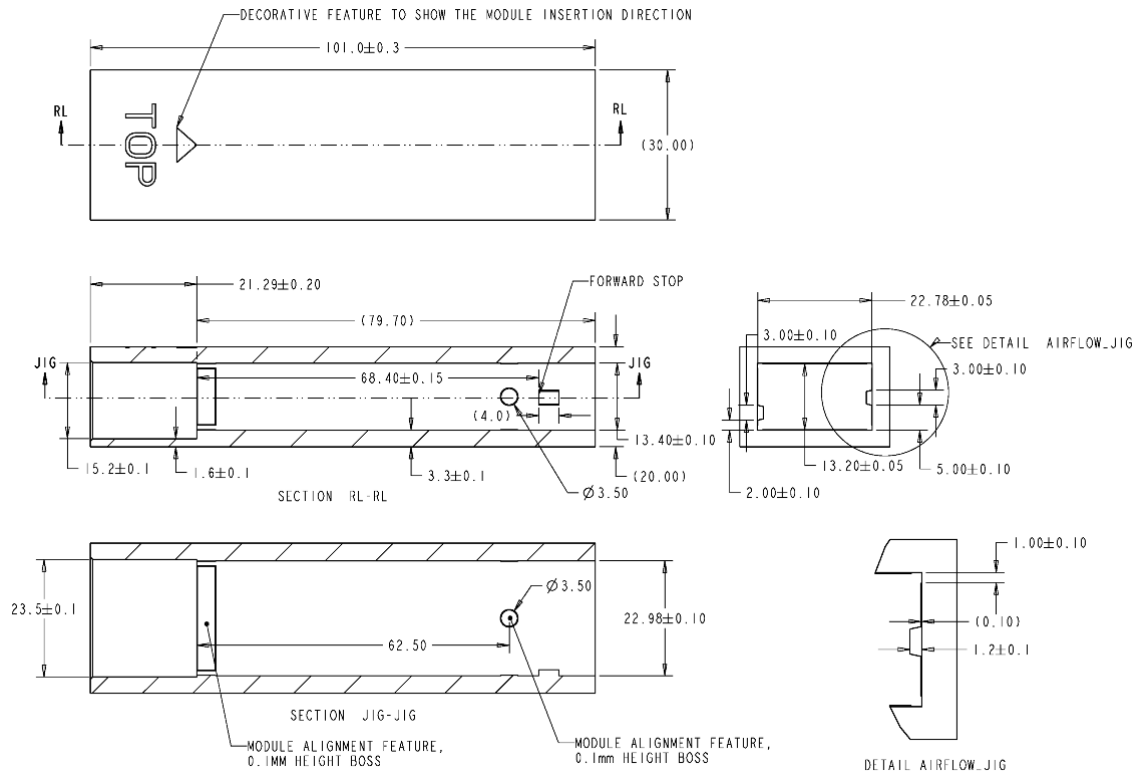


Figure 8-3: Impedance test jig

## 9 OSFP Riding Heat Sink Module and Cage Mechanical Specification

### 9.1 Overview

OSFP Riding Heat Sink (OSFP-RHS) is a 9.5mm high pluggable module which does not have an integrated heat sink as shown in the Figure 9-1 and Figure 9-2. In place of OSFP's integrated heat sink, OSFP-RHS cage shall have a riding heat sink. To prevent insertion of OSFP-RHS into a standard OSFP cage, the shape and location of the positive stop has been changed. See Table 9-1 for a comparison between the OSFP-RHS and OSFP.

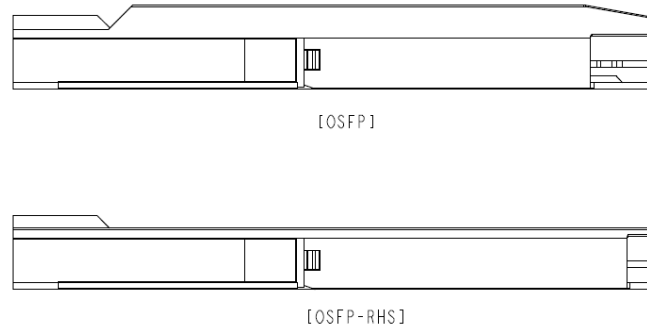


Figure 9-1: Side view of a typical OSFP (top) and a typical OSFP-RHS (bottom)

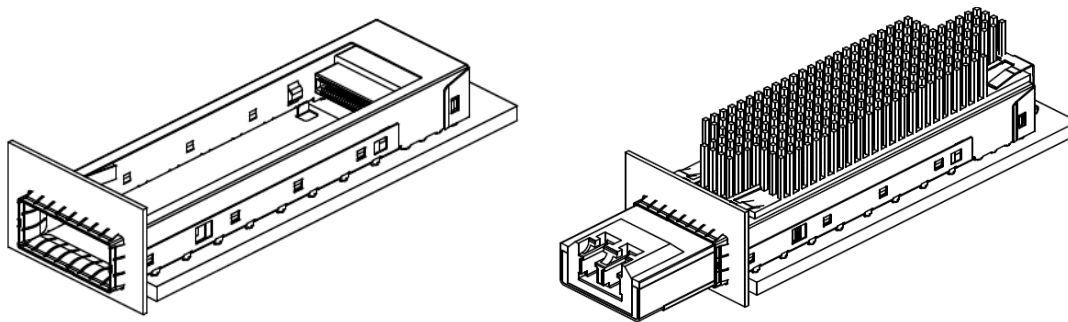


Figure 9-2: OSFP-RHS cage only (left) and OSFP-RHS cage with module and riding heat sink (right)

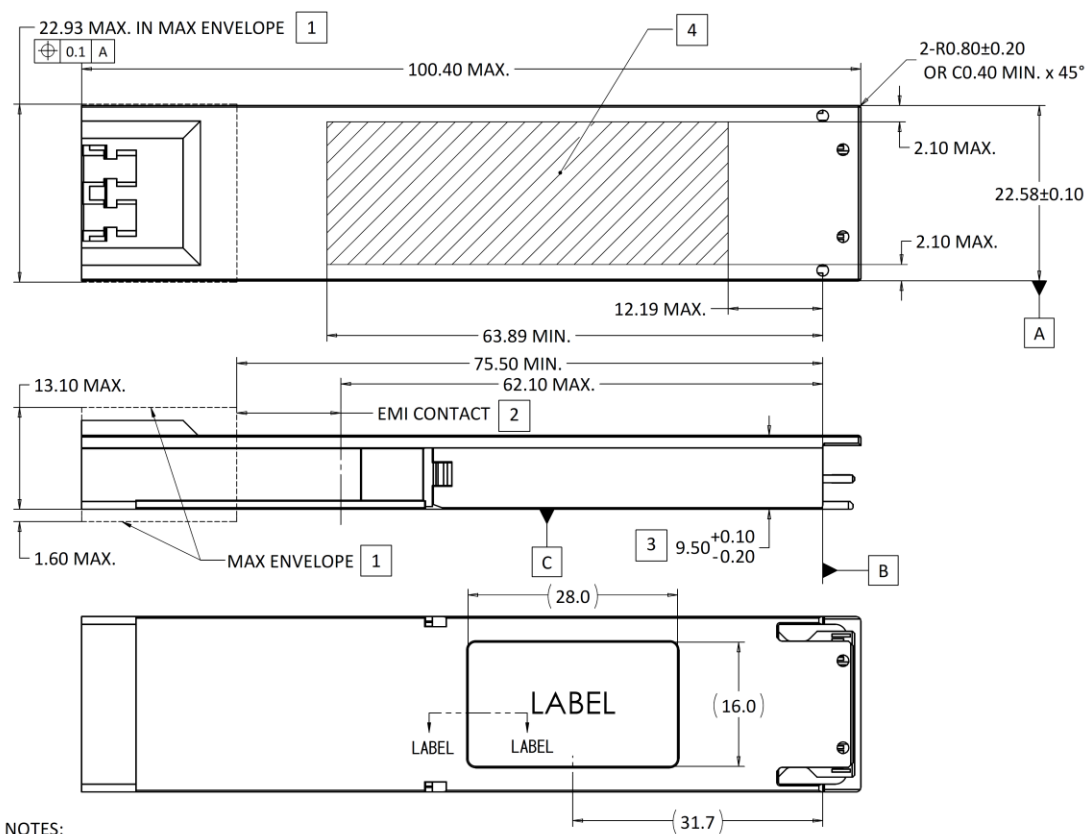
Table 9-1: Comparison of OSFP-RHS to OSFP

OSFP-RHS feature	Comment
Module	9.5mm height without heat sink and different positive stop; for the feature which is not explicitly specified for OSFP-RHS, same specification as of OSFP shall be applied.
Connector	Identical with Surface Mount Connector
Host PCB Board Layout	Identical with Surface Mount type
Cage	Port height/positive stop/bezel cutout is different with OSFP
Insertion/Extraction/Retention	Increased 15N from OSFP; see Table 9-3
Durability	Identical with OSFP
Thermal Requirement	Identical with OSFP
Airflow Requirement	Not applicable (Section 8.2 is not applied)
Electrical and Management interface	Identical with OSFP

In the following sections the dimensions of the OSFP-RHS will be defined.

## 9.2 OSFP-RHS Module Mechanical Specification

Figure 9-3 shows the overall dimension of an OSFP-RHS module from a top view. The reference datum definition is identical with Table 3-1, but note that the location of the datum B (forward stop of the module) is shifted 6mm to prevent an OSFP-RHS from being fully inserted into an OSFP cage as described in section 4 or 5.



### NOTES:

- 1 FRONT OF THE MODULE, PULL TAB AND OTHER COMPONENTS CAN EXTEND 1.60 mm MAX FROM THE BOTTOM AND 13.1 mm MAX FROM THE BOTTOM WITH UP TO 22.93 mm WIDTH IN THE MAX ENVELOPE SHOWN.
- 2 INDICATED SURFACES (ALL 4 SIDES) TO BE CONDUCTIVE FOR CONNECTION TO CHASSIS GROUND.
- 3 APPLIES FROM THE TOP OF THE MODULE TO THE BOTTOM OF THE MODULE, INSIDE THE CAGE.
- 4 SURFACE TO BE THERMALLY CONDUCTIVE. REFER SECTION 8.3 FOR FLATNESS AND ROUGHNESS REQUIREMENTS.

Figure 9-3: Overview of the OSFP-RHS and heat sink contact area

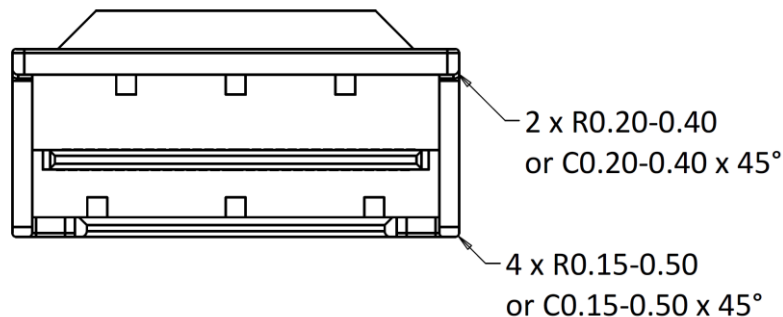


Figure 9-4: Corner radius of OSFP-RHS in back view

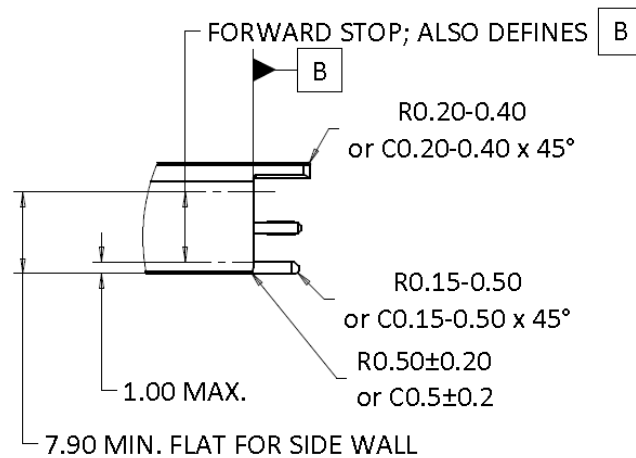


Figure 9-5: OSFP-RHS forward stop

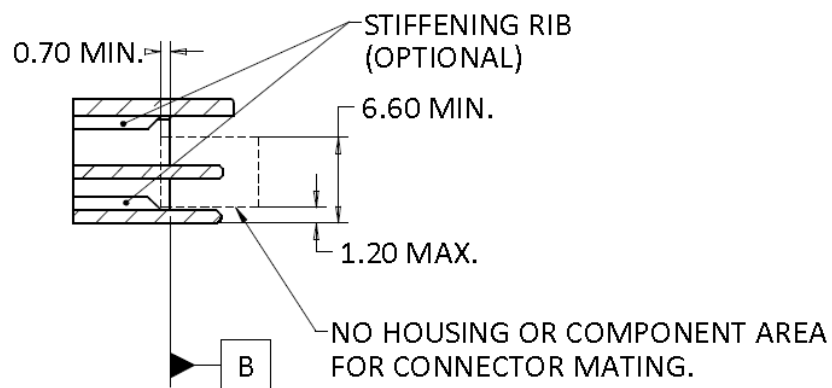


Figure 9-6: Connector keep out area in side view

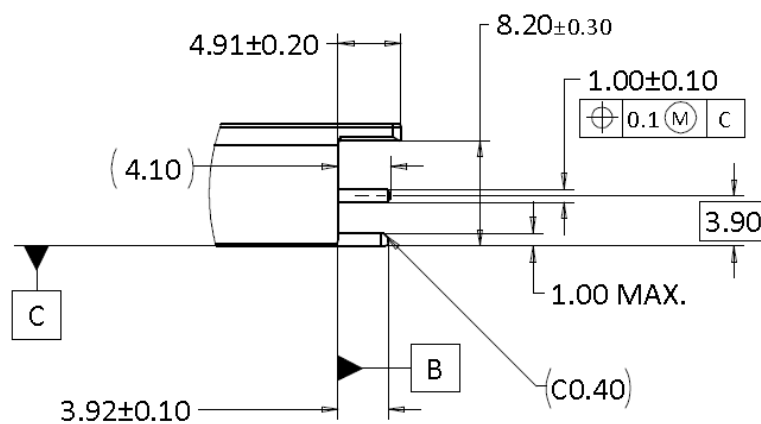


Figure 9-7: Nose of OSFP-RHS



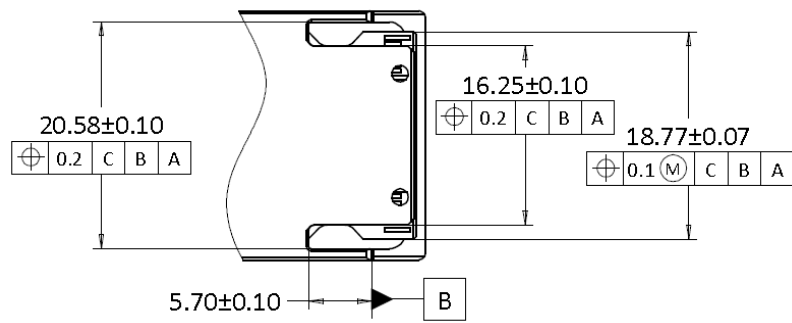


Figure 9-8: Paddle card position (bottom view of module)

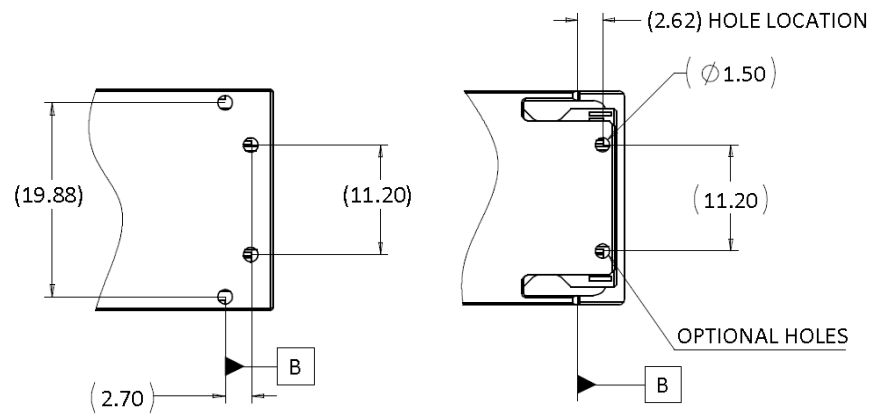


Figure 9-9: Location of inspection holes

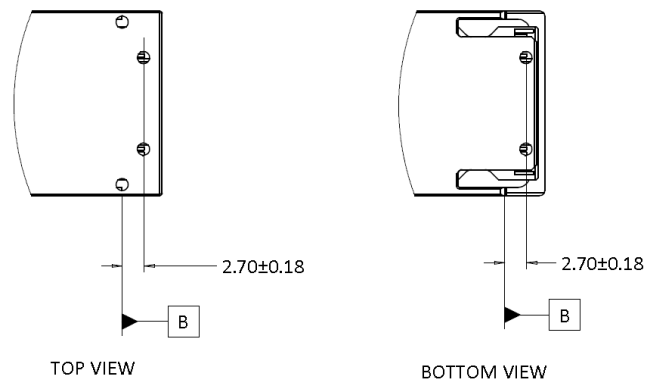


Figure 9-10: Signal pad location with respect to the forward stop

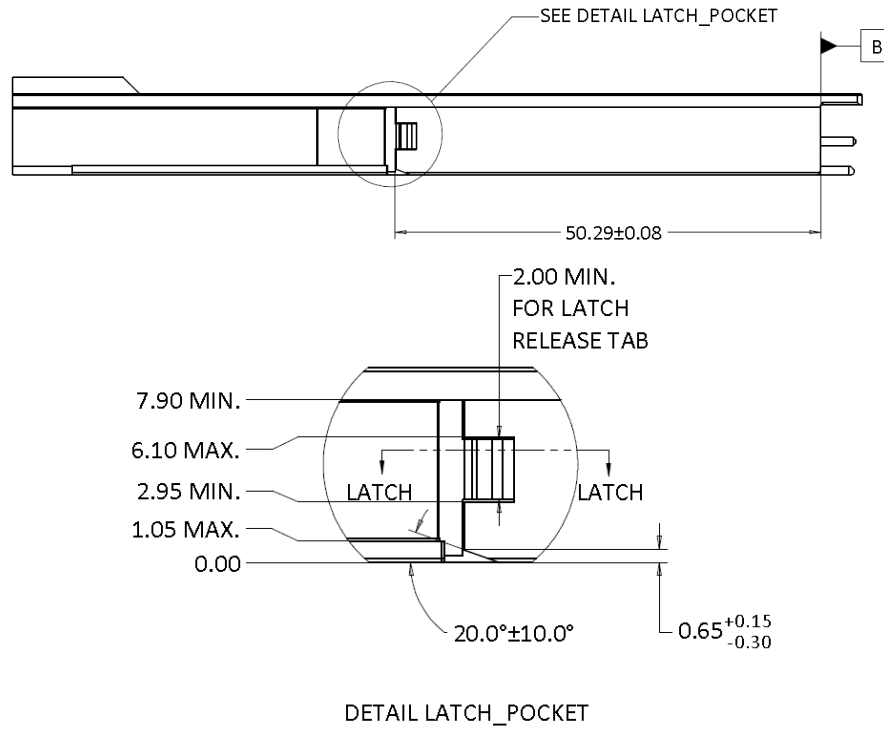
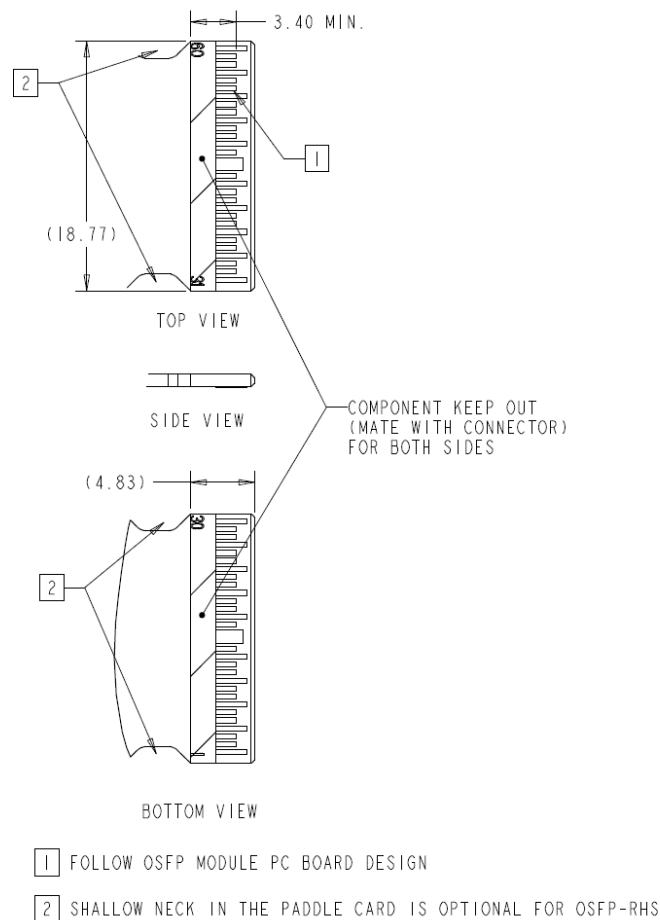


Figure 9-11: Latch pocket details of an OSFP-RHS (See section 3.7 for latch cross-section)

### 9.3 OSFP-RHS Paddle Card

Interface of the paddle card which mate with connector of an OSFP-RHS is identical with OSFP. Note that, as shown in the Figure 9-12, the shallow neck and the component place avoid area is not required in the OSFP-RHS. This is because the positive stop of the OSFP-RHS is shifted to the rear side of the module.



*Figure 9-12: Paddle card of an OSFP-RHS*

### 9.4 OSFP-RHS Thermal Interface Surface Requirements

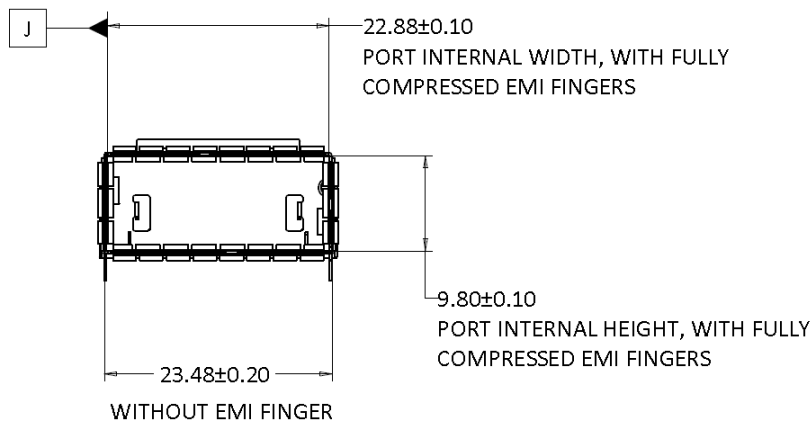
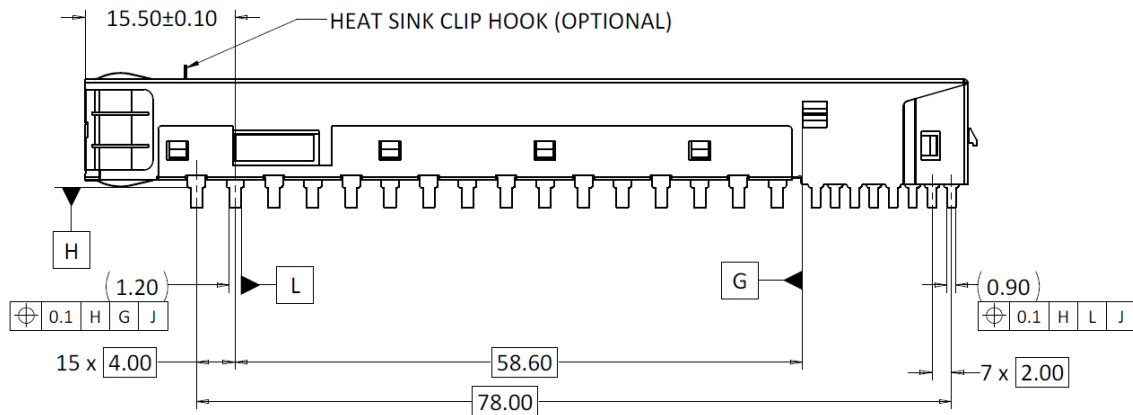
The top surface of an OSFP-RHS which may be in contact with the riding heat sink assembly shall be compliant with specifications in Table 9-2.

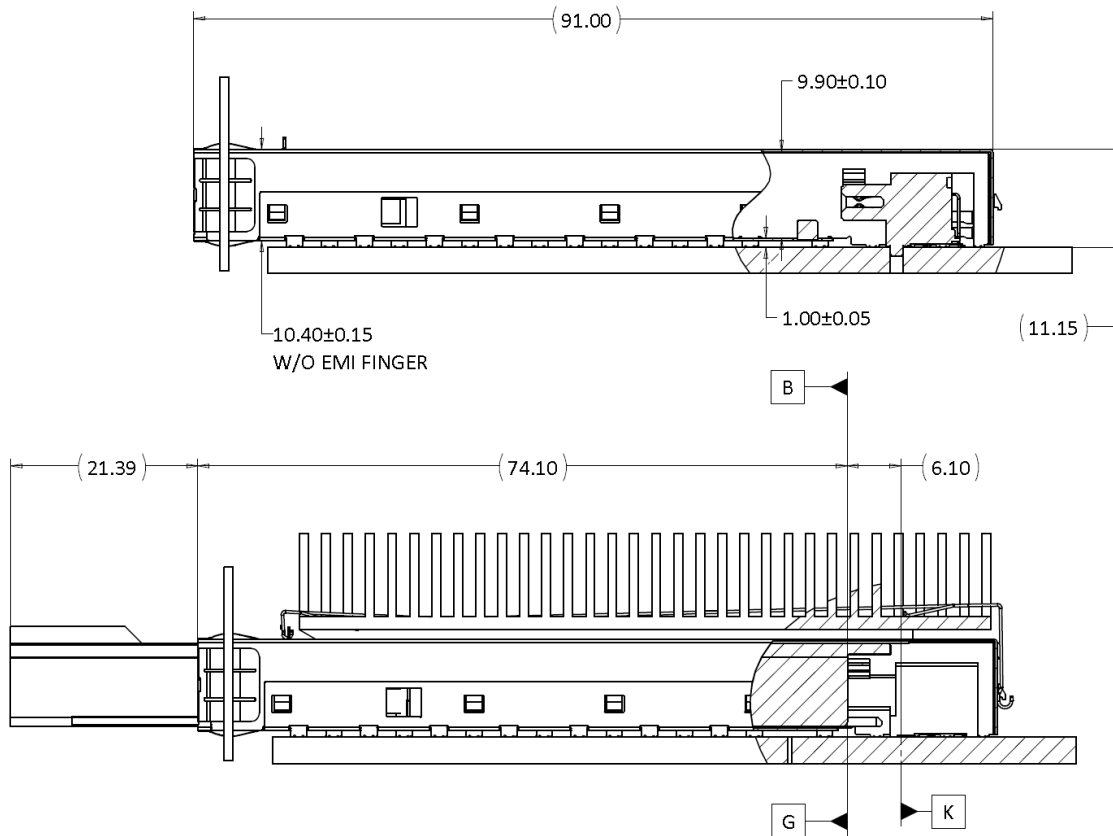
*Table 9-2: Surface Flatness and Roughness of Module*

OSFP-RHS Power (Max)	Surface Flatness	Surface Roughness
Equal or less than 5W	0.15mm or better	Ra 3.2 $\mu$ m or better
More than 5W	0.12mm or better	Ra 1.6 $\mu$ m or better

## 9.5 OSFP-RHS Cage Mechanical Specification

An OSFP-RHS cage has a lower height than an OSFP cage and makes use of a riding heat sink for cooling. The forward stop feature in an OSFP-RHS cage is shifted compared with an OSFP cage to match with an OSFP-RHS module. See Figure 9-13 to Figure 9-20 for the mechanical specification of the cage for OSFP-RHS. The host PCB foot print is identical with OSFP. Its latch feature is identical, except its geometrical reference (forward stop) has been moved.





DATUM B: MODULE FORWARD STOP  
DATUM G: CAGE FORWARD STOP  
DATUM K: CONNECTOR GUIDE POST

*Figure 9-15: Side view of a 1x1 cage with vertical cage dimensions*

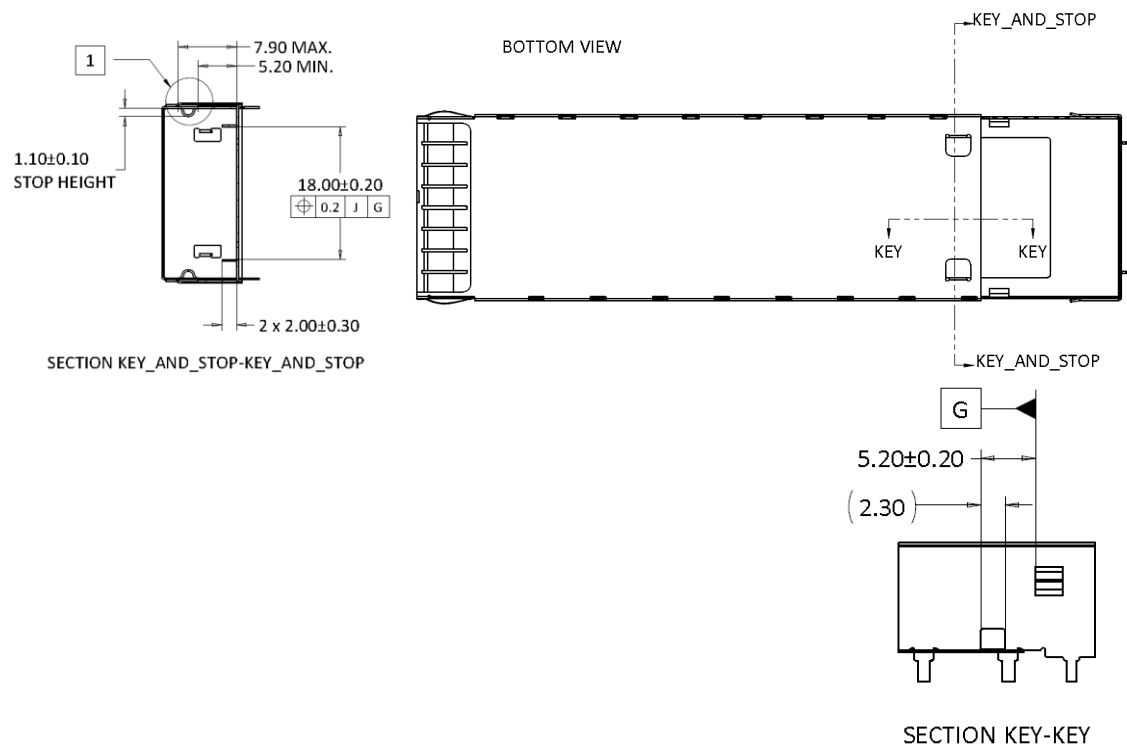
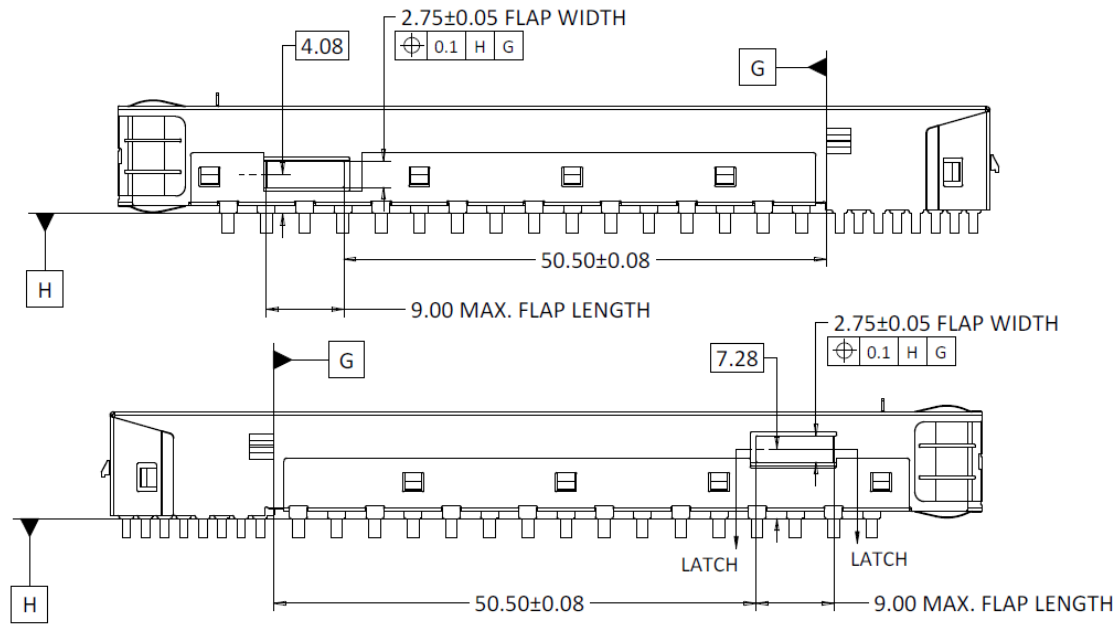
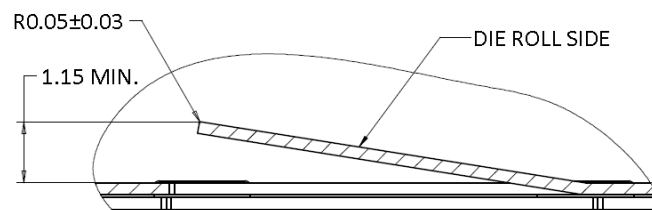


Figure 9-16: Keying feature in OSFP-RHS



NOTES:

- 1 CARE NOT TO INTERFERE WITH THE CONNECTOR.



SECTION LATCH-LATCH

Figure 9-17: Latch feature for OSFP-RHS cage

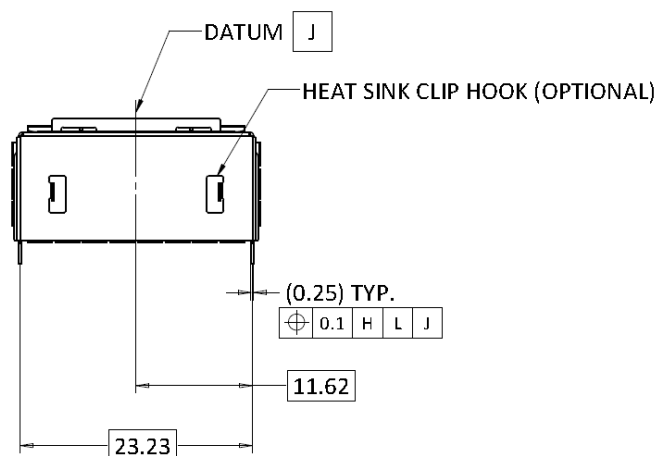


Figure 9-18: Heat sink clip hook design (reference only).

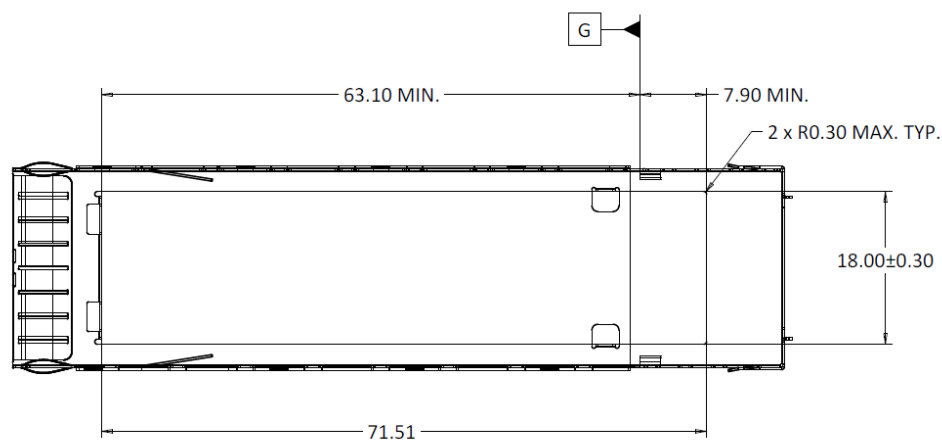


Figure 9-19: Cutout for a riding heat sink in the OSFP-RHS cage

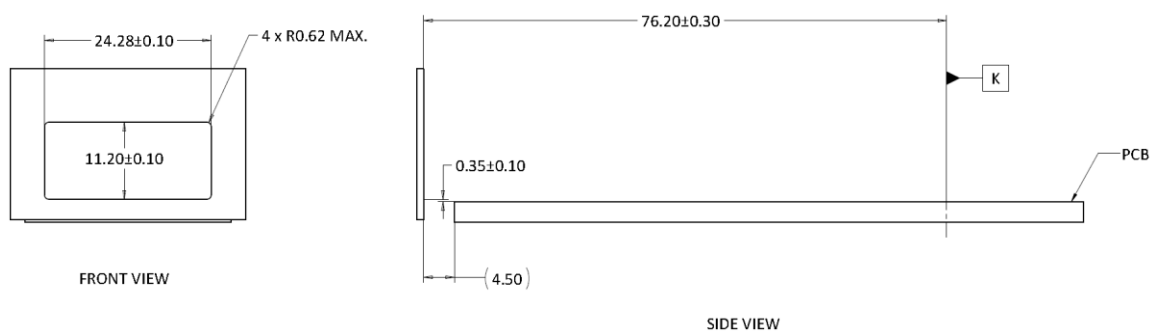


Figure 9-20: Bezel cutout for the OSFP-RHS cage

## 9.6 Maximum Heat Sink Down Force for an OSFP-RHS Cage

The cage should be designed so that the force which will be applied from the riding heat sink to an OSFP-RHS module shall not exceed 36N downward.

## 9.7 Insertion, Extraction, and Retention Forces for an OSFP-RHS Module

Table 9-3 shows the insertion, extraction and extraction force for an OSFP-RHS module.

Table 9-3: Insertion, extraction, and retention forces for an OSFP-RHS module

Measurement	Minimum	Maximum	Units	Comments
OSFP-RHS Module Insertion	N/A	55	N	Module to be inserted into connector and cage with latch mechanism engaged.
OSFP-RHS Module Extraction	N/A	45	N	Module to be removed from connector and cage with latching mechanism disengaged.
OSFP-RHS Module Retention in Cage	125	N/A	N	No functional damage to module, connector, or cage with latching mechanism activated.



**9.8 Custom Height OSFP-RHS**

There may be a custom OSFP-RHS with height different than 9.5mm but otherwise having all other attributes of OSFP-RHS. Details of such custom height OSFP-RHS are not provided in this specification.

## 10 Optical PMD Block Diagrams

Below sub-sections illustrate block diagrams for a sampling of optical physical medium dependent sublayers (PMDs) that can be realized in an OSFP form factor. These block diagrams are meant to serve as guidelines for better understanding of the form factor and are by no means exhaustive.

### 10.1 Optical PMD for parallel single mode fiber: 400G-DR4

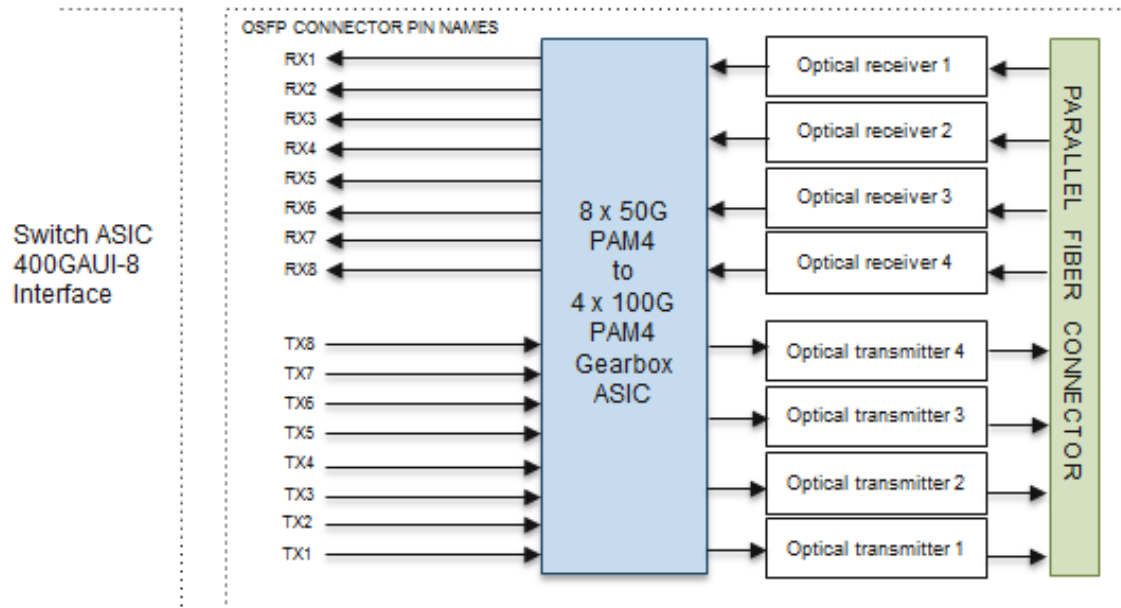


Figure 10-1: Block diagram for 400G-DR4

### 10.2 Optical PMD for parallel multi mode fiber: 400G-SR8

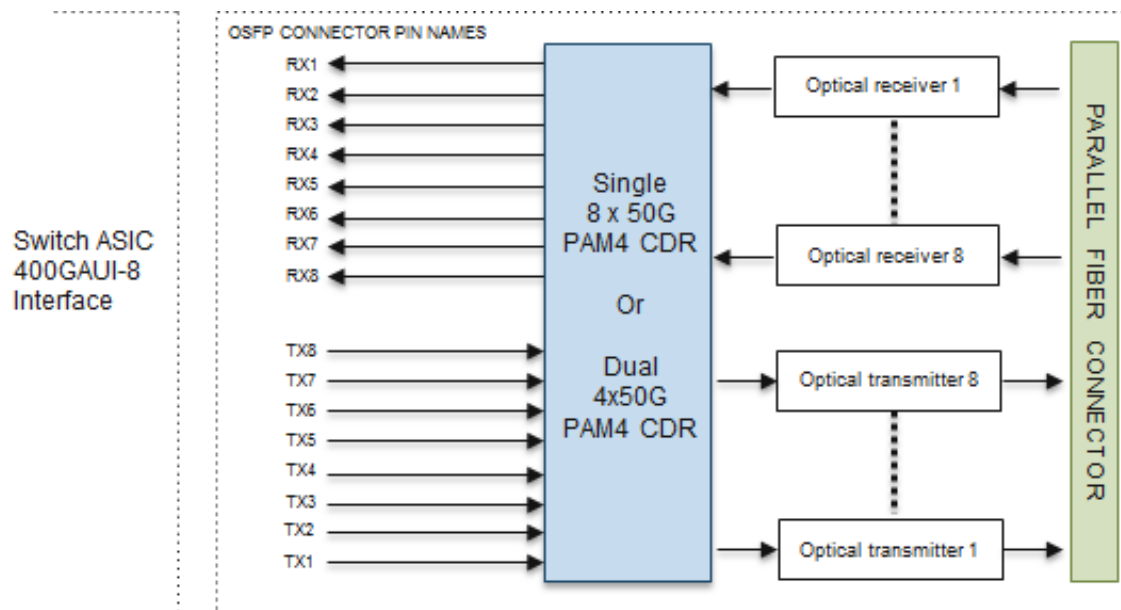


Figure 10-2: Block diagram for 400G-SR8

### 10.3 Optical PMD for parallel multi mode fiber: 400G-SR4.2

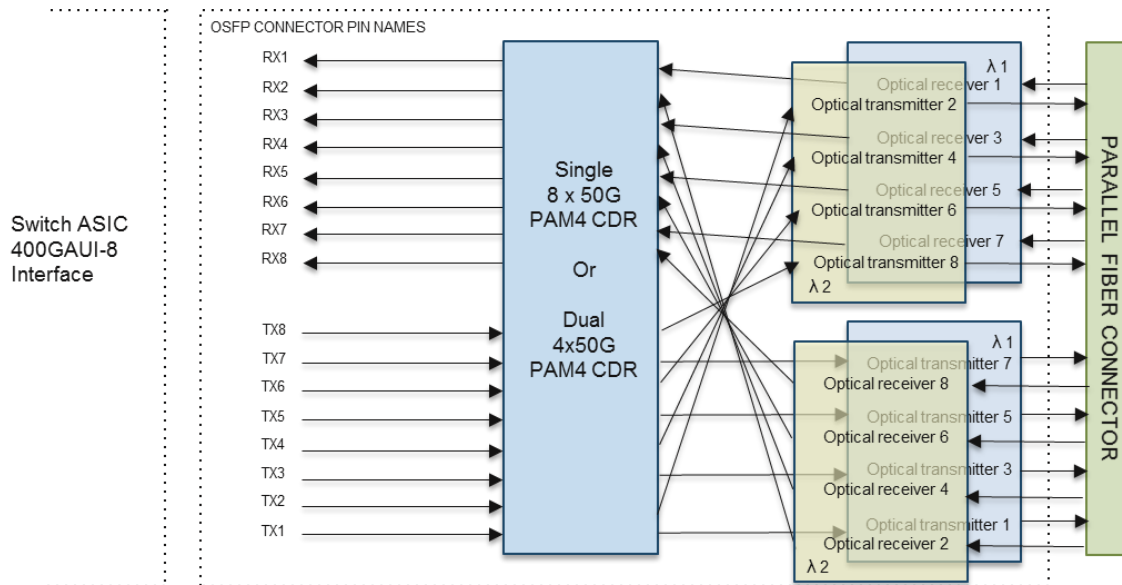


Figure 10-3: Block diagram for 400G-SR4.2

### 10.4 Optical PMD for duplex single mode fiber: 400G-FR4

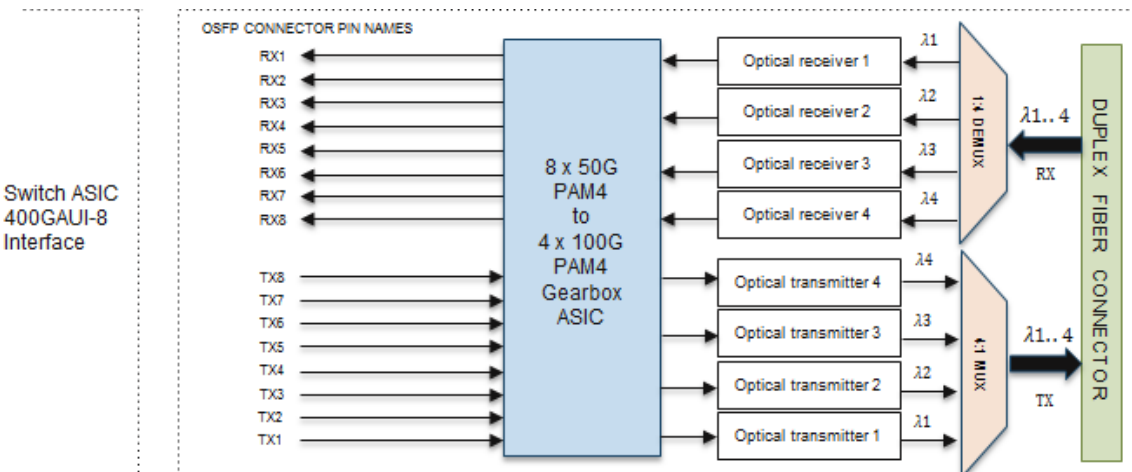


Figure 10-4: Block diagram for 400G-FR4

### 10.5 Optical PMD for duplex single mode fiber: 400G-FR8/LR8

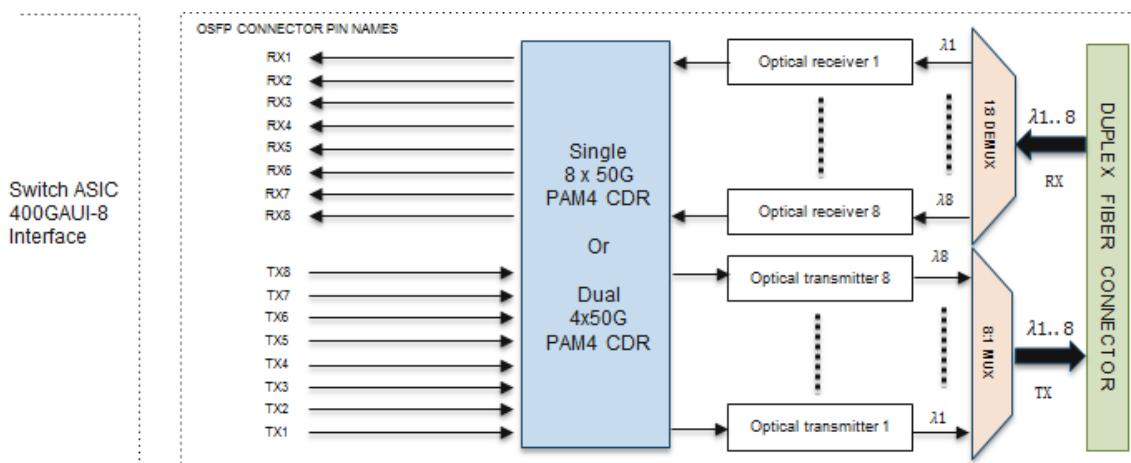


Figure 10-5: Block diagram for 400G-FR8/LR8

### 10.6 Optical PMD for dual duplex single mode fiber: 2x200G-2xFR4

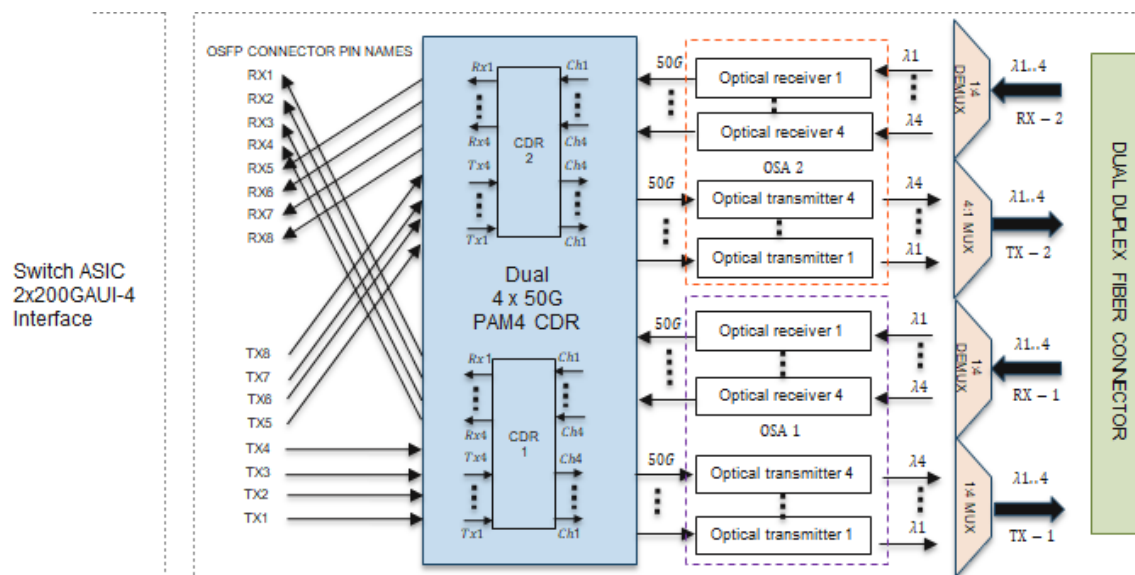


Figure 10-6: Block diagram for 2x200G-2xFR4

### 10.7 Optical PMD for dual duplex single mode fiber: 2x100G-2xCWDM4

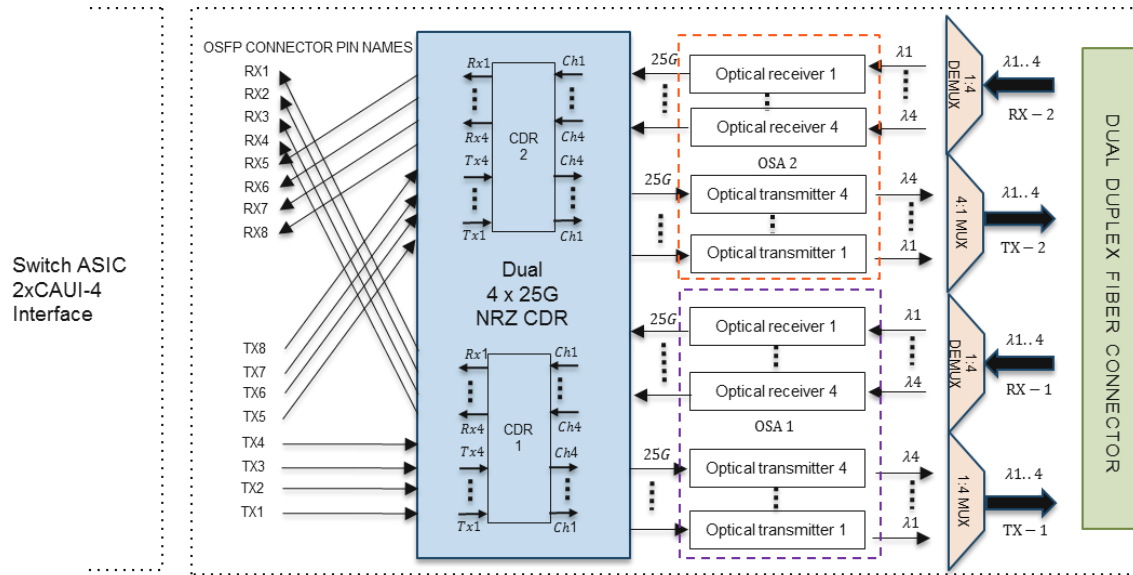


Figure 10-7: Block diagram for 2x100G-2xCWDM4

## 10.8 OSFP Optical Interface

### 10.8.1 Duplex LC Optical Interface

Figure 10-8 shows channel orientation of the optical connector when a duplex LC connector as in IEC 61754-20 is used in an OSFP module. The view is from the front of a typical OSFP module, but actual OSFP module design of the heat sink or height of the optical connector may be different from shown.

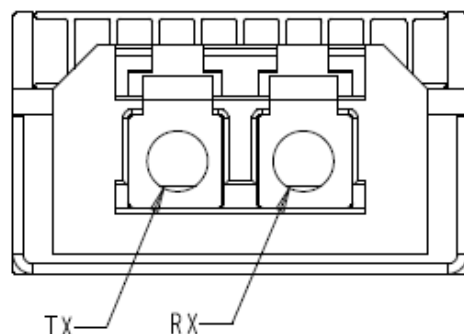
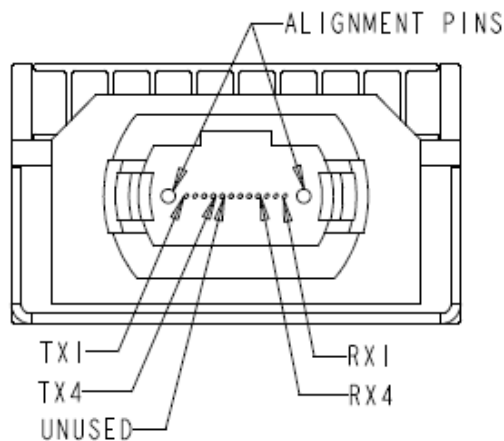


Figure 10-8: Optical receptacle and channel orientation for duplex LC connector

### 10.8.2 MPO-12 Optical Interface

Figure 10-9 shows channel orientation of the optical connector when a male MPO-12 connector as in the IEC 61754-7-1 is used in an OSFP module for applications except 400G-SR4.2.



Channels Tx1 Tx2 Tx3 Tx4 x x x x Rx4 Rx3 Rx2 Rx1  
(x: unused position)

Figure 10-9: Optical receptacle and channel orientation for MPO-12 connector

Figure 10-10 shows the channel orientation of the optical connector and signal lane mapping when a male MPO-12 connector is used in an OSFP module for 400G-SR4.2 application. There are two signals on two different wavelengths traveling on opposite directions inside each single fiber, as in the example shown in the section 10.3.

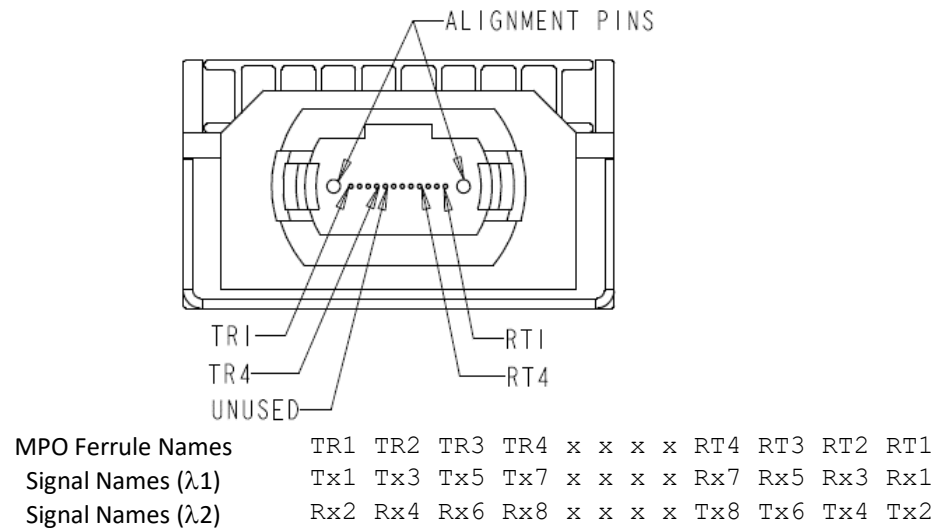


Figure 10-10: Optical receptacle and channel orientation for MPO-12 for 400G-SR4.2

10.8.3 MPO-16 Optical Interface

Figure 10-11 shows channel orientation of the optical connector when a male MPO-16 connector as in the TIA-604-18 is used in an OSFP module.

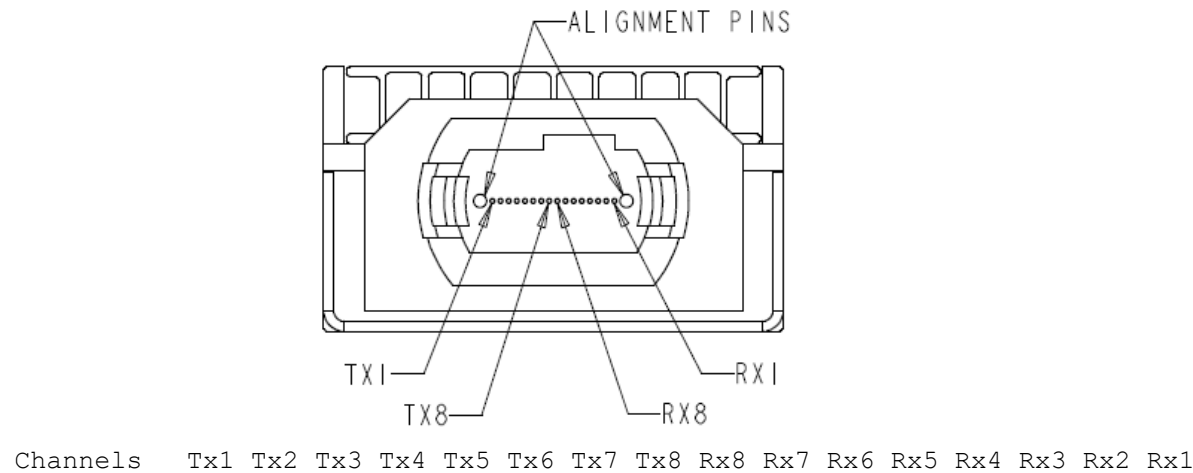
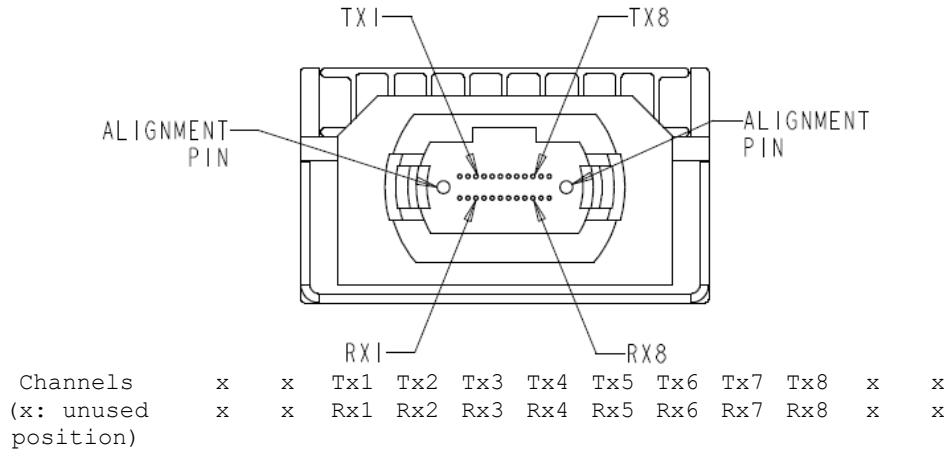


Figure 10-11: Optical receptacle and channel orientation for MPO-16 connector

10.8.4 MPO-12 Two Row Optical Interface

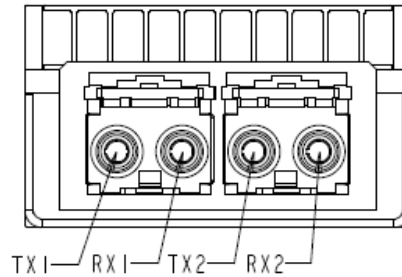
Figure 10-12 shows channel orientation of the optical connector when a male MPO-12 Two Row connector as in the TIA-604-18 is used in an OSFP module.



*Figure 10-12: Optical receptacle and channel orientation for MPO-12 Two Row connector*

#### 10.8.5 Dual CS Optical Interface

Figure 10-13 shows channel orientation of the optical connector when a dual CS connector is used in an OSFP module. Receptacle 1 (Tx1, Rx1) and receptacle 2 (Tx2, Rx2) are connected with two separate independent duplex fiber cables.



*Figure 10-13: Optical receptacle and channel orientation for dual CS connector*



10.8.6 Quad MDC Optical Interface

Figure 10-14 shows channel orientation of the optical connector when a quad MDC connector is used in an OSFP module. Receptacle 1 (Tx1, Rx1), receptacle 2 (Tx2, Rx2), receptacle 3 (Tx3, Rx3), and receptacle 4 (Tx4, Rx4) are connected with four separate independent duplex fiber cables.

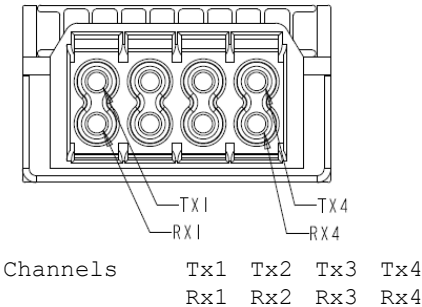


Figure 10-14: Optical receptacle and channel orientation for quad MDC connector for 400G DR-4

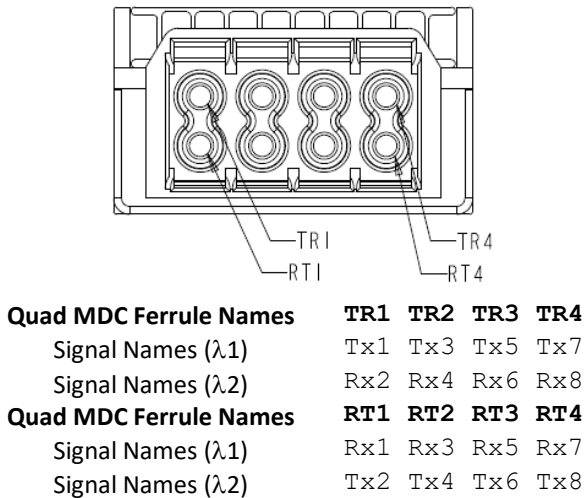


Figure 10-15: Optical receptacle and channel orientation for quad MDC connector for 400G-SR4.2

10.8.7 Quad SN™ Optical Interface

Figure 10-16 shows channel orientation of the optical connector when a quad SN™ connector is used in an OSFP module. Receptacle 1 (Tx1, Rx1), receptacle 2 (Tx2, Rx2), receptacle 3 (Tx3, Rx3), and receptacle 4 (Tx4, Rx4) are connected with four separate independent duplex fiber cables.

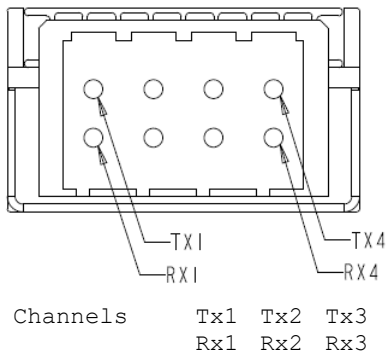


Figure 10-16: Optical receptacle and channel orientation for Quad SN™ connector for 400G-DR4

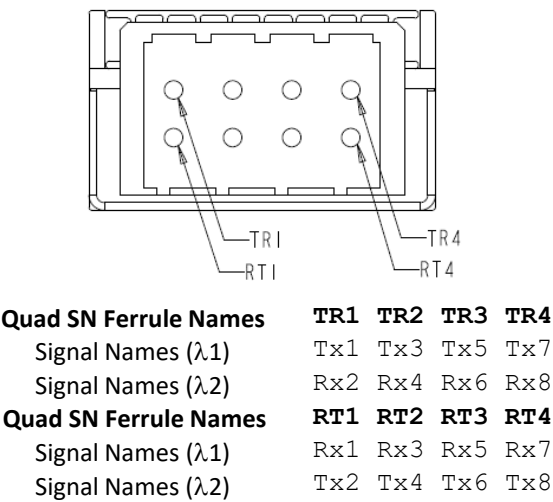


Figure 10-17: Optical receptacle and channel orientation for Quad SN™ connector for 400G SR4.2

## **11 Electrical Interface**

### **11.1 Module Electrical Connector**

The electrical interface of an OSFP module consists of a 60 contacts edge connector as illustrated by the diagram in Figure 11-1. It provides 16 contacts for 8 differential pairs of high-speed transmit signals, 16 contacts for 8 differential pairs of high-speed receive signals, 4 contacts for low-speed control signals, 4 contacts for power and 20 contacts for ground.

The edge connector pads have 3 different pad lengths to enable sequencing of the contacts to protect the module against electrostatic discharge (ESD) and provide reliable power up/power down sequencing for the module during insertion and removal. The ground pads are the longest for first contact, the power pads are the second longest for second contact and the signal pads are the third longest for final contact during insertion.

The chassis ground (case common) of the OSFP module shall be isolated from the module's circuit ground, GND, to provide the equipment designer flexibility regarding connections between external electromagnetic interference shields and circuit ground, GND, of the module. When an OSFP module is not installed, the signals to the connector within the unused cage should be disabled to minimize electromagnetic interference (EMI) emissions.

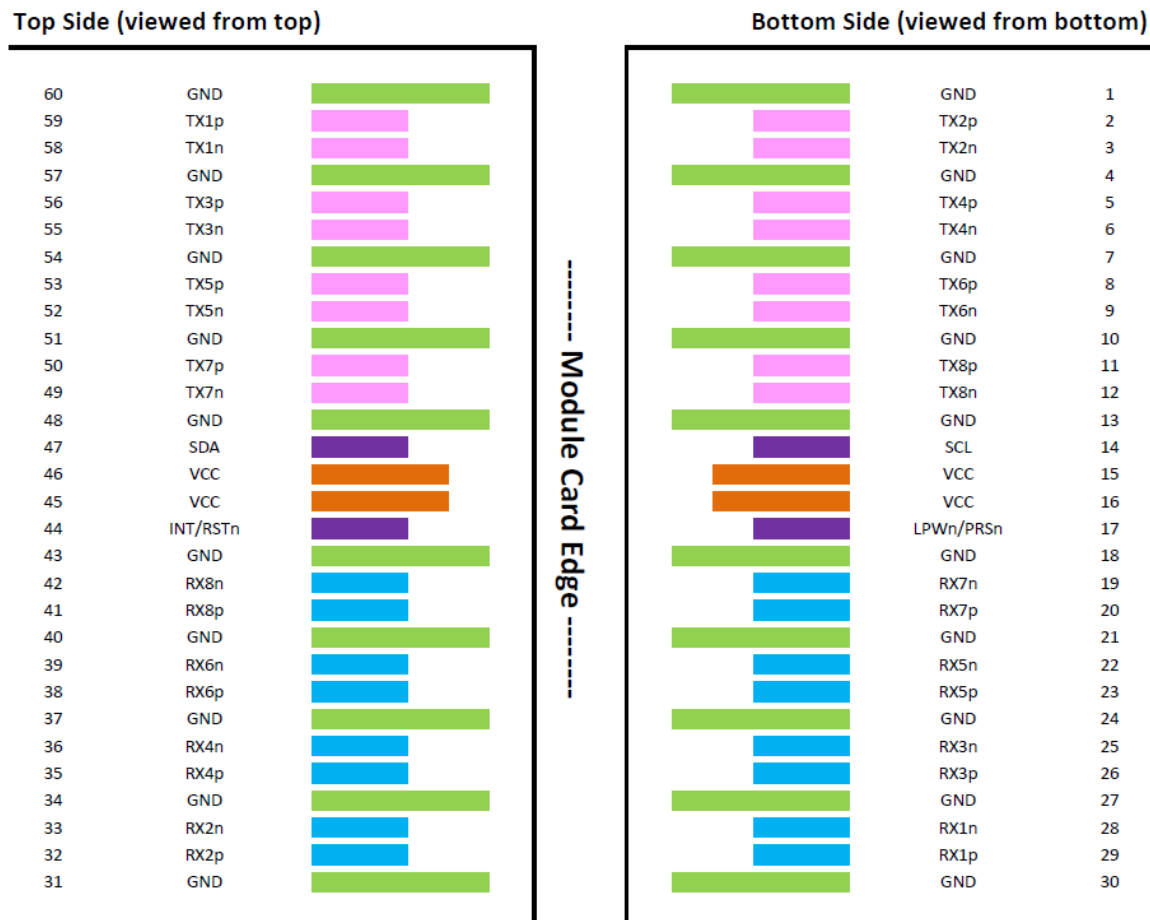


Figure 11-1: OSFP module pinout

## 11.2 Pin Descriptions

*Table 11-1: OSFP module signal pin descriptions*

Name	Direction	Description
TX[8:1]p	input	Transmit differential pairs from host to module.
TX[8:1]n	input	
RX[8:1]p	output	Receive differential pairs from module to host.
RX[8:1]n	output	
SCL	bidir	2-wire serial clock signal. Requires pull-up resistor to 3.3V on host.
SDA	bidir	2-wire serial data signal. Requires pull-up resistor to 3.3V on host.
LPWn/PRSn	bidir	Multi-level signal for low power control from host to module and module presence indication from module to host. This signal requires the circuit as described in Section 11.5.3
INT/RSTn	bidir	Multi-level signal for interrupt request from module to host and reset control from host to module. This signal requires the circuit as described in Section 11.5.2
VCC	power	3.3V power for module.
GND	ground	Module Ground. Logic and power return path.

## 11.3 Pin List

*Table 11-2: OSFP connector pin list*

Pin#	Symbol	Description	Logic	Direction	Plug Sequence	Notes
1	GND	Ground			1	
2	TX2p	Transmitter Data Non-Inverted	CML-I	Input from Host	3	
3	TX2n	Transmitter Data Inverted	CML-I	Input from Host	3	
4	GND	Ground			1	
5	TX4p	Transmitter Data Non-Inverted	CML-I	Input from Host	3	
6	TX4n	Transmitter Data Inverted	CML-I	Input from Host	3	
7	GND	Ground			1	
8	TX6p	Transmitter Data Non-Inverted	CML-I	Input from Host	3	
9	TX6n	Transmitter Data Inverted	CML-I	Input from Host	3	
10	GND	Ground			1	
11	TX8p	Transmitter Data Non-Inverted	CML-I	Input from Host	3	
12	TX8n	Transmitter Data Inverted	CML-I	Input from Host	3	
13	GND	Ground			1	
14	SCL	2-wire Serial interface clock	LVC MOS-I/O	Bi-directional	3	Open-Drain with pull-up resistor on Host
15	VCC	+3.3V Power		Power from Host	2	
16	VCC	+3.3V Power		Power from Host	2	
17	LPWn/PRSn	Low-Power Mode / Module Present	Multi-Level	Bi-directional	3	See pin description for required circuit
18	GND	Ground			1	
19	RX7n	Receiver Data Inverted	CML-O	Output to Host	3	
20	RX7p	Receiver Data Non-Inverted	CML-O	Output to Host	3	
21	GND	Ground			1	
22	RX5n	Receiver Data Inverted	CML-O	Output to Host	3	
23	RX5p	Receiver Data Non-Inverted	CML-O	Output to Host	3	
24	GND	Ground			1	
25	RX3n	Receiver Data Inverted	CML-O	Output to Host	3	
26	RX3p	Receiver Data Non-Inverted	CML-O	Output to Host	3	
27	GND	Ground			1	
28	RX1n	Receiver Data Inverted	CML-O	Output to Host	3	
29	RX1p	Receiver Data Non-Inverted	CML-O	Output to Host	3	
30	GND	Ground			1	

Pin#	Symbol	Description	Logic	Direction	Plug Sequence	Notes
31	GND	Ground			1	
32	RX2p	Receiver Data Non-Inverted	CML-O	Output to Host	3	
33	RX2n	Receiver Data Inverted	CML-O	Output to Host	3	
34	GND	Ground			1	
35	RX4p	Receiver Data Non-Inverted	CML-O	Output to Host	3	
36	RX4n	Receiver Data Inverted	CML-O	Output to Host	3	
37	GND	Ground			1	
38	RX6p	Receiver Data Non-Inverted	CML-O	Output to Host	3	
39	RX6n	Receiver Data Inverted	CML-O	Output to Host	3	
40	GND	Ground			1	
41	RX8p	Receiver Data Non-Inverted	CML-O	Output to Host	3	
42	RX8n	Receiver Data Inverted	CML-O	Output to Host	3	
43	GND	Ground			1	
44	INT/RSTn	Module Interrupt / Module Reset	Multi-Level	Bi-directional	3	See pin description for required circuit
45	VCC	+3.3V Power		Power from Host	2	
46	VCC	+3.3V Power		Power from Host	2	
47	SDA	2-wire Serial interface data	LVC MOS-I/O	Bi-directional	3	Open-Drain with pull-up resistor on Host
48	GND	Ground			1	
49	TX7n	Transmitter Data Inverted	CML-I	Input from Host	3	
50	TX7p	Transmitter Data Non-Inverted	CML-I	Input from Host	3	
51	GND	Ground			1	
52	TX5n	Transmitter Data Inverted	CML-I	Input from Host	3	
53	TX5p	Transmitter Data Non-Inverted	CML-I	Input from Host	3	
54	GND	Ground			1	
55	TX3n	Transmitter Data Inverted	CML-I	Input from Host	3	
56	TX3p	Transmitter Data Non-Inverted	CML-I	Input from Host	3	
57	GND	Ground			1	
58	TX1n	Transmitter Data Inverted	CML-I	Input from Host	3	
59	TX1p	Transmitter Data Non-Inverted	CML-I	Input from Host	3	
60	GND	Ground			1	

## 11.4 High-Speed Signals

The high-speed signals consist of 8 transmit and 8 receive differential pairs identified as TX[8:1]p / TX[8:1]n and RX[8:1]p / RX[8:1]n. These signals can be operated in either 400GAUI-8 or dual CAUI-4 modes depending on the capability of the host ASIC.

400GAUI-8 mode provides 8 differential lanes using PAM4 signaling operating at 26.5625 GBaud. This results in 8 lanes of 50Gb/s for a total of 400Gb/s. This mode allows connection to PMD configurations of 1x400G, 2x200G, 4x100G or 8x50G.

Dual CAUI-4 mode provides 8 differential lanes using NRZ signaling operating at 25.78125 GBaud. This results in 8 lanes of 25Gb/s for a total of 200Gb/s. This mode allows connection to PMD configurations of 2x100G, 4x50G or 8x25G.

The high-speed signals follow the electrical specifications of IEEE802.3bs, IEEE802.3cd and CEI-56G-VSR-PAM as defined in OIF-CEI-04.0 for 400GAUI-8 mode and IEEE802.3bj, IEEE802.3bm for CAUI-4 mode.

The lane assignments in Table 11-3 shall be used for the different PMD configurations.

*Table 11-3: High-speed signal lane mapping*

(\*L means Lane, L1 means Lane 1 in the port.)

PMD Configuration	Transmit and Receive Lane Assignments							
	L1	L2	L3	L4	L5	L6	L7	L8
1x400G (PAM4)	Port 1							
2x200G (PAM4) 2x100G (NRZ)	Port 1 L1*				Port 2 L1			
4x100G (PAM4) 4x50G (NRZ)	Port 1 L1		Port 2 L1		Port 3 L1		Port 4 L1	
8x50G (PAM4) 8x25G (NRZ)	Port 1	Port 2	Port 3	Port 4	Port 5	Port 6	Port 7	Port 8

## 11.5 Low-Speed Signals

There are 4 low-speed signals consisting of SCL, SDA, LPWn/PRSn and INT/RSTn. These signals are used for configuration and control of the module by the host. SCL and SDA use 3.3V LVCMOS levels and are bidirectional signals. LPWn/PRSn and INT/RSTn have additional circuitry on the host and module to enable multi-level bidirectional signaling.

### 11.5.1 SCL and SDA

SCL and SDA are a 2-wire serial interface between the host and module using the I<sup>2</sup>C or I<sup>3</sup>C protocols. SCL is defined as the serial interface clock signal and SDA as the serial interface data signal. Both signals are open-drain and require pull-up resistors to +3.3V on the host. The pull-up resistor value shall be 1k ohms to 4.7k ohms depending on capacitive load.

This 2-wire interface supports bus speeds:

- Required - I<sup>2</sup>C Fast-mode (Fm) ≤ 400 kbit/s
- Optional - I<sup>2</sup>C Fast-mode Plus (Fm+) ≤ 1 Mbit/s
- Optional - I<sup>3</sup>C Single Data Rate (SDR) ≤ 12.5 Mbit/s

The host shall default to using 100 kbit/s standard-mode I<sup>2</sup>C when first accessing an unidentified module for backward compatibility. Once the module has been brought out of reset, the host can read the module's 2-wire interface speed register to determine the maximum supported speed the module allows. For an OSFP, the host may then use I<sup>2</sup>C Fast-mode, I<sup>2</sup>C Fast-mode Plus or I<sup>3</sup>C Single Data Rate, as indicated by the module. It is optional for the host to change the speed of the 2-wire interface but remaining at a low speed could lead to slow management transactions for modules that require frequent accesses.

SCL and SDA signals follow the electrical specifications of Fast-mode, and Fast-mode Plus as defined in the I<sup>2</sup>C-bus specification or Single Data Rate mode as defined in the Specification for I<sup>3</sup>C.

### 11.5.2 INT/RSTn

INT/RSTn is a dual function signal that allows the module to raise an interrupt to the host and also allows the host to reset the module. The circuit shown in Figure 11-3 enables multi-level signaling to provide direct signal control in both directions. Reset is an active-low signal on the host which is translated to an active-low signal on the module. Interrupt is an active-high signal on the module which gets translated to an active-low signal on the host.

The INT/RSTn signal operates in 3 voltage zones to indicate the state of Reset for the module and Interrupt for the host. Figure 11-2 shows these 3 zones. The host uses a voltage reference at 2.5 volts to determine the state of the H\_INTn signal and the module uses a voltage reference at 1.25V to determine the state of the M\_RSTn signal.

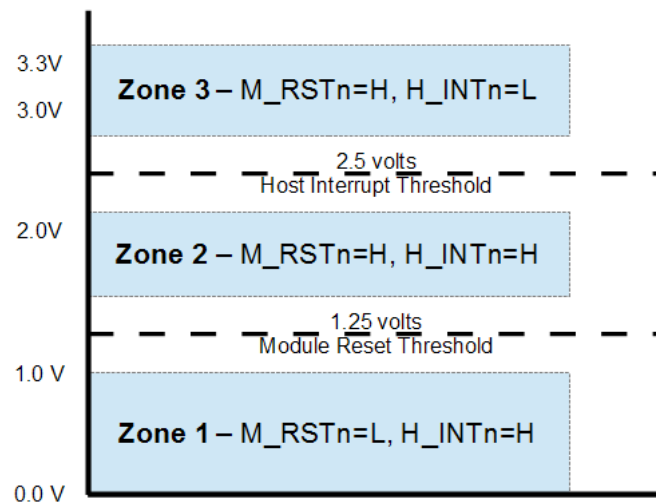


Figure 11-2: INT/RSTn voltage zones

- Zone 1 – Reset operation – Zone 1 is the state when the module is in reset and interrupt deasserted (M\_RSTn=Low, H\_INTn=High). The min/max voltages for Zone 1 are defined by parameters V\_INT/RSTn\_1 and V\_INT/RSTn\_2 in Table 11-4.
- Zone 2 – Normal operation – Zone 2 is the normal operating state with reset deasserted (M\_RSTn=High) and interrupt deasserted (H\_INTn=High). The min/max voltages for Zone 2 are defined by parameter V\_INT/RSTn\_3 in Table 11-4.



- Zone 3 – Interrupt operation – Zone 3 is the state for the module to assert interrupt and the module must also be out of reset ( $M\_RSTn=High$ ,  $H\_INTn=Low$ ). The min/max voltages for Zone 3 are defined by parameter  $V\_INT/RSTn\_4$  in Table 11-4.

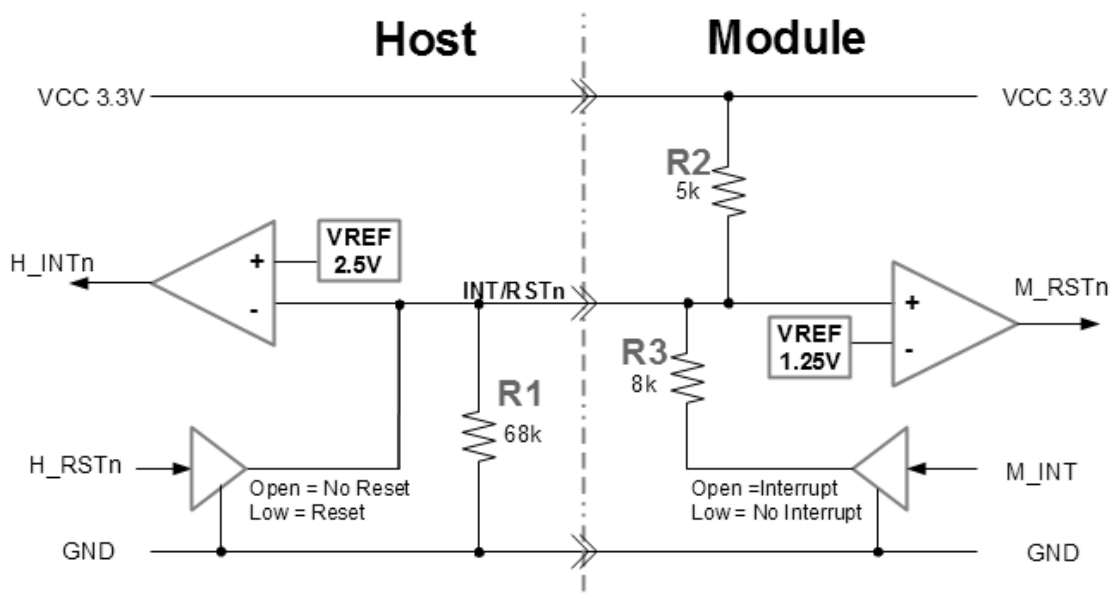


Figure 11-3: INT/RSTn circuit

Table 11-4: INT/RSTn circuit parameters

Parameter	Nominal	Min	Max	Units	Note
Host VCC	3.300	3.135	3.465	Volts	VCC voltage on the Host
H_Vref_INTn	2.500	2.475	2.525	Volts	Precision voltage reference for H_INTn
M_Vref_RSTn	1.250	1.238	1.263	Volts	Precision voltage reference for M_RSTn
R1	68k	66k	70k	Ohms	Recommend 68.1k ohms 1% resistor
R2	5k	4.9k	5.1k	Ohms	Recommend 4.99k ohms 1% resistor
R3	8k	7.8k	8.2k	Ohms	Recommend 8.06k ohms 1% resistor
$V\_INT/RSTn\_1$	0.000	0.000	1.000	Volts	INT/RSTn voltage for No Module
$V\_INT/RSTn\_2$	0.000	0.000	1.000	Volts	INT/RSTn voltage for Module installed, H_RSTn=Low
$V\_INT/RSTn\_3$	1.900	1.500	2.250	Volts	INT/RSTn voltage for Module installed, H_RSTn=High, M_INT=Low
$V\_INT/RSTn\_4$	3.000	2.750	3.465	Volts	INT/RSTn voltage for Module installed, H_RSTn=High, M_INT=High

### 11.5.3 LPWn/PRSn

LPWn/PRSn is a dual function signal that allows the host to signal Low Power mode and the module to indicate Module Present. The circuit shown in Figure 11-5 enables multi-level signaling to provide direct signal control in both directions. Low Power mode is an active-low signal on the host which gets converted to an active-low signal on the module. Module Present is controlled by a pull-down resistor on the module which gets converted to an active-low logic signal on the host.

The LPWn/PRSn signal operates in 3 voltage zones to indicate the state of Low Power mode for the module and Module Present for the host. Figure 11-4 shows these 3 zones.

The host uses a voltage reference at 2.5 volts to determine the state of the H\_PRSn signal and the module uses a voltage reference at 1.25V to determine the state of the M\_LPWn signal.

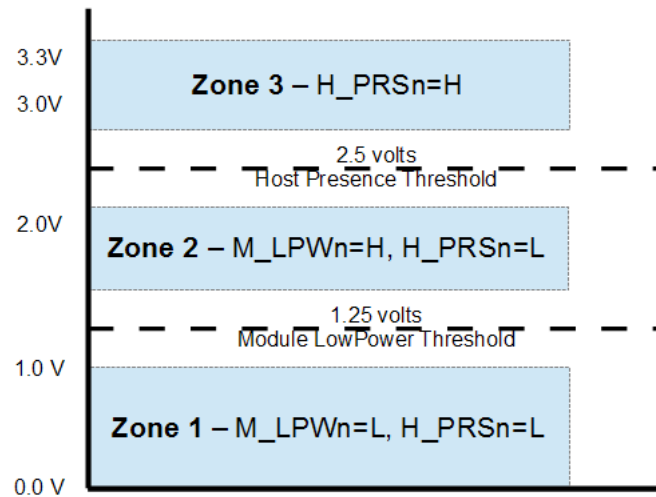


Figure 11-4: LPWn/PRSn voltage zones

- Zone 1 – Low Power mode – Zone 1 is the low power state and module is present (M\_LPWn=Low, H\_PRSn=Low). The min/max voltages for Zone 1 are defined by parameters V\_LPWn/PRSn\_1 in Table 11-5.
- Zone 2 – High Power mode – Zone 2 is the high power state and module is present (M\_LPWn=High, H\_PRSn=Low). The min/max voltages for Zone 2 are defined by parameters V\_LPWn/PRSn\_2 in Table 11-5.
- Zone 3 – Module Not Present – Zone 3 is the state for when the module is not present (H\_PRSn=High). The min/max voltages for Zone 3 are defined by parameters V\_LPWn/PRSn\_3 in Table 11-5.

**Module Removal** – If the module is being unplugged and LPWn/PRSn loses contact, the pull-down resistor on the module shall assert Low Power mode on the module (M\_LPWn=Low). The module is required to transition to low power (Power Class 1) and disable transmitters within the time specified by T\_hplp in Table 11-7. This maximum transition time is to ensure the module is in Low Power mode before the power contacts lose connection to avoid potential damage from arcing.

The LPWn/PRSn signal is driven High or Open by the host for Low Power mode control. If logic is used to generate the High level then 3.3V LVCMOS is preferred.

For very low cost modules, such as DAC, the voltage comparator on the module may be omitted and the LPWn/PRSn pin shall in that case be tied to GND in the module. This type of module may only be used for low power mode (Power Class 1).

The module transmitters must be disabled when in Low Power mode. This ensures Power Class 1 and also provides a fast hardware shut down mechanism for applications such as redundancy switch-over. In addition, software controlled transmitter disable is provided by the TX Disable register via the I<sup>2</sup>C interface.

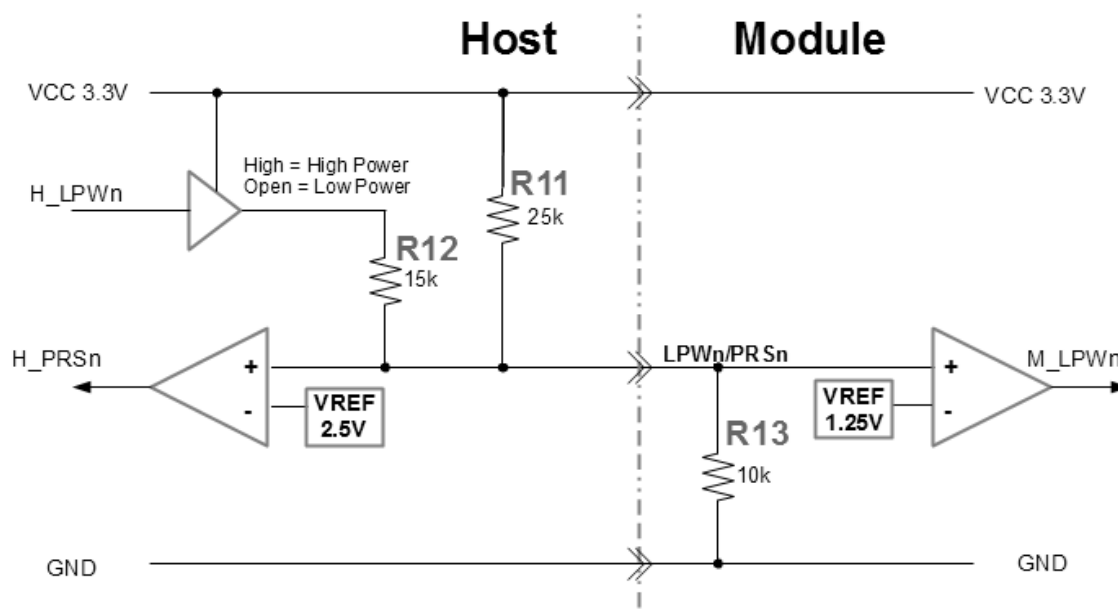


Figure 11-5: LPWn/PRSn circuit

Table 11-5: LPWn/PRSn circuit parameters

Parameter	Nominal	Min	Max	Units	Note
Host VCC	3.300	3.135	3.465	Volts	VCC voltage on the Host
H_Vref_PRSn	2.500	2.475	2.525	Volts	Precision voltage reference for H_PRSn
M_Vref_LPWn	1.250	1.238	1.263	Volts	Precision voltage reference for M_LPWn
R11	25k	24.5k	25.5k	Ohms	Recommend 24.9k ohms 1% resistor
R12	15k	14.7k	15.3k	Ohms	Recommend 15k ohms 1% resistor
R13	10k	9.8k	10.2k	Ohms	Recommend 10k ohms 1% resistor
V_LPWn/PRSn_1	0.950	0.000	1.100	Volts	LPWn/PRSn voltage for Module installed, H_LPWn=Low
V_LPWn/PRSn_2	1.700	1.400	2.250	Volts	LPWn/PRSn voltage for Module installed, H_LPWn=High
V_LPWn/PRSn_3	3.300	2.750	3.465	Volts	LPWn/PRSn voltage for No Module

#### 11.5.4 Timing for control and status functions

The QSFP-DD specification should be followed for any timing of control and status functions that have not been defined in this specification.

### 11.5.5 OSFP module power up behavior

The OSFP module shall power up when system power is enabled or on module insertion or on VCC power enable to the module. Once powered, the module shall either wait in Low Power mode or enter High Power mode based on the state of the Reset signal, Low Power signal and ForceLowPwr bit of the module. The ForceLowPwr bit default is pre-programmed in the module by the manufacturer and typically would be set to 0. The host can change the ForceLowPwr bit after power up but it shall return to its pre-programmed default when the module is placed in reset or power cycled. The Reset and Low Power signals are described in sections 11.5.2 and 11.5.3. The ForceLowPwr bit is defined in the OSFP Management Interface Specification.

The table below shows the module power up state based on Low Power and ForceLowPwr. If LPWn=0 then the module shall go to low power mode and transmitters disabled. If ForceLowPwr=0 and LPWn=1 then the module shall immediately enable transmitters. If ForceLowPwr=1 and LPWn=1 then the module shall wait in Low Power mode until the host clears the ForceLowPwr bit for the module to enable transmitters.

*Table 11-6: Power Up Behavior*

Module State	ForceLowPwr = 0	ForceLowPwr = 1
<b>Low Power asserted (LPWn = 0)</b>	Low Power Mode (transmitters Disabled)	Low Power Mode (transmitters Disabled)
<b>Low Power de-asserted (LPWn = 1)</b>	Operational (transmitters Enabled*)	Low Power Mode (transmitters Disabled)

\*The host may use the management interface to alter this default behavior

### 11.5.6 OSFP module reset behavior

Reset is a hardware signal from the INT/RSTn pin as defined in section 11.5.2. Asserting Reset overrides all other hardware and software controls and forces the module into the Reset state. This includes forcing Low Power mode and disabling transmitters.

## 11.6 Power

+3.3V power is delivered to the module via 4 power pins (VCC). These 4 power pins shall be connected together on the module and also together on the host. Each power pin allows up to 1.6 Amps for a total of 6.4 Amps. This enables a potential maximum of up to 21.1 Watts of power at 3.3V nominal voltage to the module.

The specification of the module power is in accordance with methods defined by SFF-8679 Rev 1.7 section 5.5. There are 8 power classes defined as shown in Table 11-8. All modules in reset or the default low power mode must comply with Power Class 1. High power mode enables the module to draw power up to its advertised power class, and may be conditionally enabled by the host. The host may read the module power class register to know the power class of the module before or after enabling high power mode. The module shall not exceed the power class it identifies for itself.

Transition between low and high power mode is controlled by the M\_RSTn (reset) signal, M\_LPWn (low power mode) signal and ForceLowPwr bit. The module shall remain in or transition to low power mode when M\_LPWn or M\_RSTn are asserted or the ForceLowPwr bit is set. While in low power mode, active modules shall also disable transmitters. The module may transition to high power mode once M\_RSTn and M\_LPWn are deasserted and the ForceLowPwr bit is cleared.

The specifications of Table 11-7 and Table 11-8 are for the combined power of all 4 power pins. The measurement location for these specifications is at the OSFP connector VCC pins on the host board.

*Table 11-7: OSFP power specification*

Parameter	Symbol	Minimum	Nominal	Maximum	Units
Host power supply voltages including ripple, droop and noise below 100 kHz	Vcc_Module	3.135	3.300	3.465	V
Host RMS noise output 10 Hz-10 MHz	e <sub>N_Host</sub>			25	mV
Module RMS noise output 10 Hz - 10 MHz	e <sub>N_Mod</sub>			15	mV
Module inrush - instantaneous peak duration	T <sub>ip</sub>			50	μs
Module inrush - initialization time	T <sub>init</sub>			500	ms
Inrush and Discharge Current (1)	I <sub>didt</sub>			100	mA/μs
High power mode to Low power mode transition time from assertion of M_LPWn or M_RSTn or ForceLowPwr	T <sub>hplp</sub>			200	μs

- (1) The specified Inrush and Discharge Current (I<sub>didt</sub>) limit shall not be exceeded for all power transient events. This includes hot-plug, hot-unplug, power-up, power-down, initialization, low-power to high-power and high-power to low-power.

Table 11-8: OSFP power classes

Parameter	Symbol	Minimum	Nominal	Maximum	Units
<b>Power Class 1 module (low power mode – M_LPWn or M_RSTn asserted or ForceLowPwr)</b>					
Power consumption	P_1			1.5	W
Instantaneous peak current at hot plug	lcc_ip_1			600	mA
Sustained peak current at hot plug	lcc_sp_1			500	mA
Steady state current (2)	lcc_1			478	mA
<b>Power Class 2 module (high power mode)</b>					
Power consumption	P_2			3.5	W
Instantaneous peak current at high power enable	lcc_ip_2			1400	mA
Sustained peak current at high power enable	lcc_sp_2			1167	mA
Steady state current (2)	lcc_2			1116	mA
<b>Power Class 3 module (high power mode)</b>					
Power consumption	P_3			7	W
Instantaneous peak current at high power enable	lcc_ip_3			2800	mA
Sustained peak current at high power enable	lcc_sp_3			2333	mA
Steady state current (2)	lcc_3			2233	mA
<b>Power Class 4 module (high power mode)</b>					
Power consumption	P_4			8	W
Instantaneous peak current at high power enable	lcc_ip_4			3200	mA
Sustained peak current at high power enable	lcc_sp_4			2666	mA
Steady state current (2)	lcc_4			2552	mA
<b>Power Class 5 module (high power mode)</b>					
Power consumption	P_5			10	W
Instantaneous peak current at high power enable	lcc_ip_5			4000	mA
Sustained peak current at high power enable	lcc_sp_5			3333	mA
Steady state current (2)	lcc_5			3190	mA
<b>Power Class 6 module (high power mode)</b>					
Power consumption	P_6			12	W
Instantaneous peak current at high power enable	lcc_ip_6			4800	mA
Sustained peak current at high power enable	lcc_sp_6			4000	mA
Steady state current (2)	lcc_6			3828	mA
<b>Power Class 7 module (high power mode)</b>					
Power consumption	P_7			14	W
Instantaneous peak current at high power enable	lcc_ip_7			5600	mA
Sustained peak current at high power enable	lcc_sp_7			4666	mA
Steady state current (2)	lcc_7			4466	mA
<b>Power Class 8 module (high power mode)</b>					
Power consumption	P_8 (3)			>14	W
Instantaneous peak current at high power enable	lcc_ip_8			P_8 * 400	mA
Sustained peak current at high power enable	lcc_sp_8			P_8 * 333	mA
Steady state current (2)	lcc_8			6400	mA

- (2) Steady state current must not allow power consumption to exceed the specified maximum power for the selected power class.
- (3) Power consumption P\_8 is readable from the module Max Power register as defined in the Management Specification.

### 11.6.1 Power Filter

Figure 11-6 provides an example implementation for a 3.3V power filter on the host board. If an alternate circuit is used for power filtering then the same filter characteristics as this example filter shall be met.

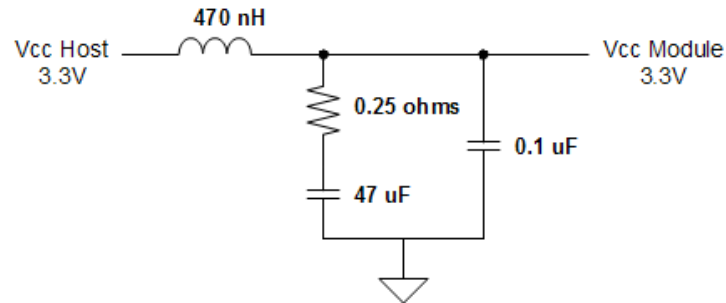


Figure 11-6: Host board power filter circuit

### 11.6.2 Power Electronic Circuit Breaker (optional)

For safety and protection of the host system, the power to each OSFP module may be protected by an electronic circuit breaker on the host board which is enabled with the H\_PRSn signal such that power is only enabled when the module is fully engaged into the OSFP connector.

### 11.7 OSFP Host Board and Module Block Diagram

Figure 11-7 is an example block diagram of the host board's connections to the OSFP module.

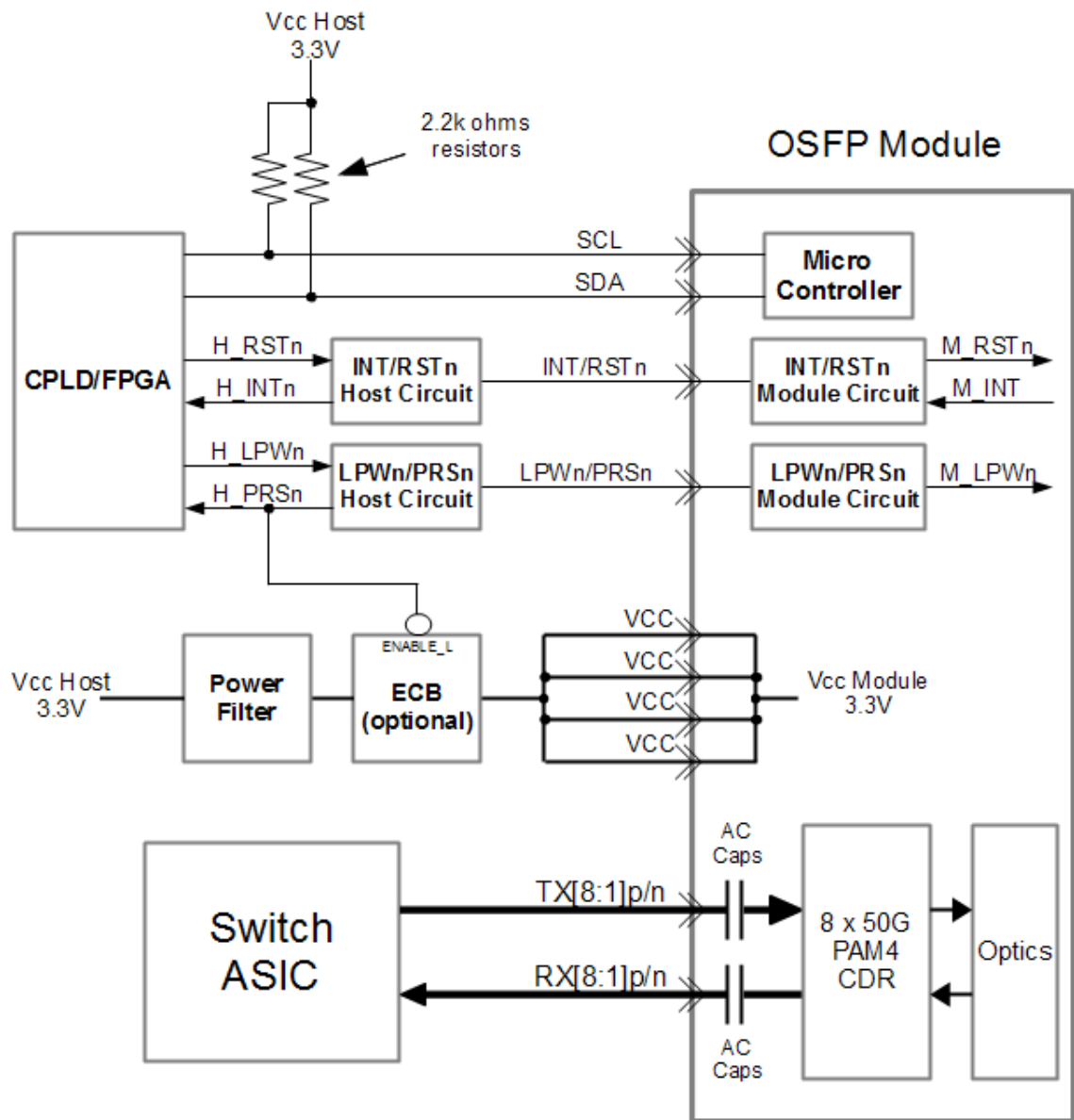


Figure 11-7: Host board and Module block diagram



**11.8 Electrostatic Discharge (ESD)**

Where ESD performance is not otherwise specified, the OSFP module shall meet ESD requirements given in EN61000-4-2, criterion B test specification when installed in a properly grounded cage and chassis. The units are subjected to 15kV air discharges during operation and 8kV direct contact discharges to the case.

The OSFP module and host high-speed signal, low-speed signal and power contacts shall withstand 1000 V electrostatic discharge based on Human Body Model per ANSI/ESDA/JEDEC JS-001.

## Appendix A. OSFP Module LED (Informative)

### A.1 LED Indicator and its Scheme

An OSFP module may have one or more LEDs at the front for use as a status indicator. In cases where a single LED is used for status indication of a multi-channel OSFP module, a green/yellow bi-color LED is recommended. In such case, the LED should light solid green when all channels of the module are operational and solid yellow when all channels are disabled. In cases where some channels are operational and some have fault conditions, a repeating pattern of LED flashing as outlined in Table A-1 is recommended.

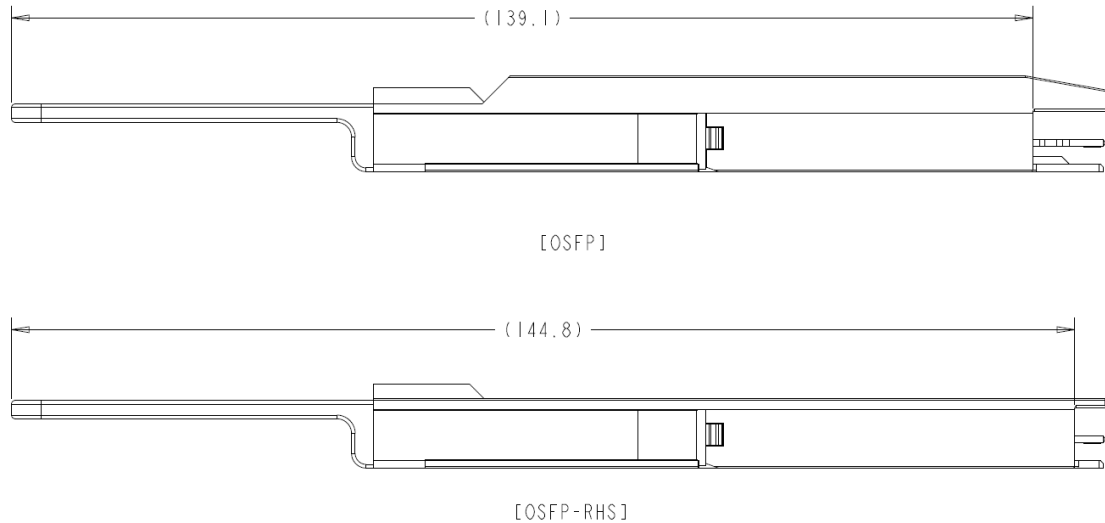
*Table A-1: Suggested OSFP LED signaling scheme for multiple channel modules*

LED Status	Indication
On for 0.22 seconds	Green indicates channel 1 operational; Yellow indicates channel 1 is non-operational or disabled.
Off for 0.22 seconds	Pause until LED indicates status of next channel.
On for 0.22 seconds	Green indicates channel 2 operational; Yellow indicates channel 2 is non-operational or disabled.
Off for 0.22 seconds	Pause until LED indicates status of next channel.
.... Pattern repeats to final (nth) port	...
LED off for 1.76 seconds	Long pause for clear separation before pattern repeats from the beginning.

## Appendix B. OSFP Pull Tab Length (Informative)

### B.1 OSFP Pull Tab Length

An OSFP module may have a pull tab. Figure B-1 shows a reference pull tab length with respect to the module positive stop. Note that this does not apply to passive copper cables.



*Figure B-1: OSFP module lengths with pull tab*